How to choose augmenting paths?

- ▶ We need to find paths efficiently.
- ▶ We want to guarantee a small number of iterations.

Several possibilities:

- ▶ Choose path with maximum bottleneck capacity.
- ▶ Choose path with sufficiently large bottleneck capacity.
- ► Choose the shortest augmenting path.

Algorithm 2 maxflow(G, s, t, c)

© Harald Räcke

424

426

Capacity Scaling

```
1: foreach e \in E do f_e \leftarrow 0;

2: \Delta \leftarrow 2^{\lceil \log_2 C \rceil}

3: while \Delta \geq 1 do

4: G_f(\Delta) \leftarrow \Delta-residual graph

5: while there is augmenting path P in G_f(\Delta) do

6: f \leftarrow \text{augment}(f, c, P)

7: \text{update}(G_f(\Delta))

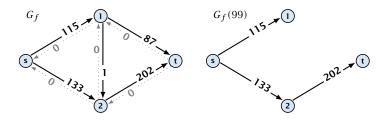
8: \Delta \leftarrow \Delta/2

9: return f
```

Capacity Scaling

Intuition:

- ► Choosing a path with the highest bottleneck increases the flow as much as possible in a single step.
- Don't worry about finding the exact bottleneck.
- Maintain scaling parameter Δ .
- ▶ $G_f(\Delta)$ is a sub-graph of the residual graph G_f that contains only edges with capacity at least Δ .



© Harald Räcke

11.3 Capacity Scaling

425

Capacity Scaling

Assumption:

All capacities are integers between $1\ \mathrm{and}\ \mathcal{C}.$

Invariant:

All flows and capacities are/remain integral throughout the algorithm.

Correctness:

The algorithm computes a maxflow:

- because of integrality we have $G_f(1) = G_f$
- therefore after the last phase there are no augmenting paths anymore
- this means we have a maximum flow.

Capacity Scaling

Lemma 1

There are $\lceil \log C \rceil$ *iterations over* Δ .

Proof: obvious.

Lemma 2

Let f be the flow at the end of a Δ -phase. Then the maximum flow is smaller than $\operatorname{val}(f) + m\Delta$.

Proof: less obvious, but simple:

- ▶ There must exist an *s*-*t* cut in $G_f(\Delta)$ of zero capacity.
- ▶ In G_f this cut can have capacity at most $m\Delta$.
- ► This gives me an upper bound on the flow that I can still add.



11.3 Capacity Scaling

428

Capacity Scaling

Lemma 3

There are at most 2m augmentations per scaling-phase.

Proof:

- Let *f* be the flow at the end of the previous phase.
- $ightharpoonup \operatorname{val}(f^*) \le \operatorname{val}(f) + 2m\Delta$
- ▶ Each augmentation increases flow by Δ .

Theorem 4

We need $\mathcal{O}(m \log C)$ augmentations. The algorithm can be implemented in time $\mathcal{O}(m^2 \log C)$.



11.3 Capacity Scaling

429