

# Symmetries and Dynamics of Discrete Systems

Talk at CASC 2007, Bonn, Germany

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19 September 2007

# Motivations

- Symmetry analysis of finite **discrete systems** can be **complete** in contrast to **continuous systems** where only negligible small part of all thinkable symmetries is considered: **point** and **contact Lie**, **Bäcklund** and **Lie–Bäcklund**, sporadic instances of **non-local** symmetries etc.
- Many hints from quantum mechanics and quantum gravity that **discreteness is more suitable for physics** at small distances than **continuity** which arises only as a logical limit in considering large collections of discrete structures

# Discrete Relations and Discrete Dynamical Systems

Any **collection of discrete points** taking values in **finite sets** possesses some kind of **locality**:

such collection has a structure of **abstract simplicial complex**

Special cases are

- systems of **polynomial equations** over finite fields
- **cellular automata**

In this talk we consider relations on **graphs** — 1D simplicial complexes

Two types of discrete **dynamical systems** — discrete relations evolving in **discrete time**:

- state of **deterministic** system at any point of time is **function** of previous states (**we consider cellular automata with symmetric local rules**)
- in **non-deterministic** system transition from one state to any other state is possible with some probability (**we consider mesoscopic lattice models — some ensembles of discrete relations**)

# Lattices and Their Symmetries

- **Space** of discrete dynamical system is **lattice**  $\Gamma \equiv k$ -valent **graph**
  - **Symmetry** of lattice  $\Gamma$  is graph automorphism group  $\text{Aut}(\Gamma)$
  - We assume  $\text{Aut}(\Gamma)$  acts **transitively** on vertices  $V(\Gamma)$  of lattice: very idea of “space” implies possibility to reach any point by “moves” in the space
- 
- In applications it is assumed often that lattice is embedded in some continuous space — in this case notion of ‘**dimension**’ of lattice makes sense
  - In our context such embeddings are of little importance — we shall use them for visualization only

# Functions on Lattices and Their Orbits

- $Q = \{0, \dots, q - 1\}$  is **set of values** of lattice vertices
- $\Sigma = Q^\Gamma$  is space of  **$Q$ -valued functions** on  $\Gamma$
- $\text{Aut}(\Gamma)$  acts non-transitively on  $\Sigma$  splitting this space

into **orbits** of different sizes  $\Sigma = \bigcup_{i=1}^{N_{\text{orbits}}} O_i$

**Action:**  $(g\varphi)(x) = \varphi(g^{-1}x)$

$x \in V(\Gamma), \varphi(x) \in \Sigma, g \in \text{Aut}(\Gamma)$

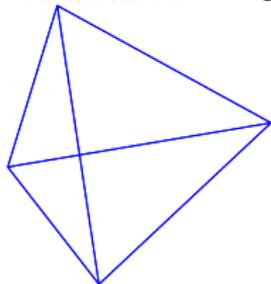
- **Burnside's lemma** counts total number of orbits

$$N_{\text{orbits}} = \frac{1}{|\text{Aut}(\Gamma)|} \sum_{g \in \text{Aut}(\Gamma)} q^{N_{\text{cycles}}^g},$$

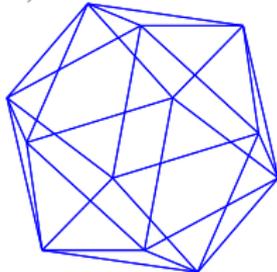
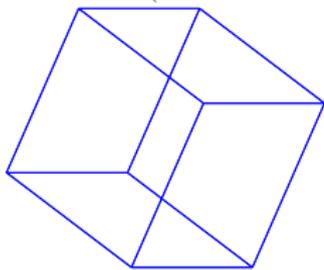
$N_{\text{cycles}}^g$  is number of cycles in group element  $g$

# Examples of Lattices

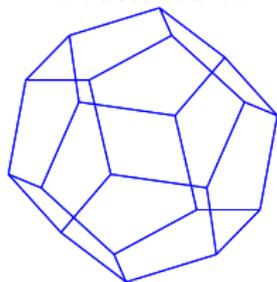
Tetrahedron



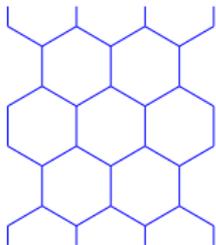
Hexahedron (= Graphene 4x2) Icosahedron



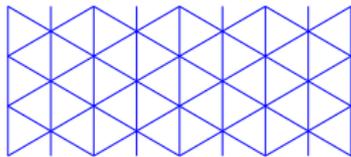
Dodecahedron



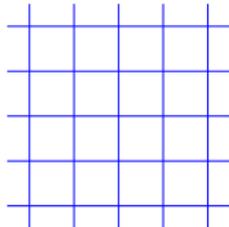
Graphene 6x4



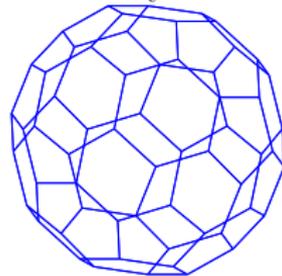
Triangular 4x6



Square 5x5



Buckyball

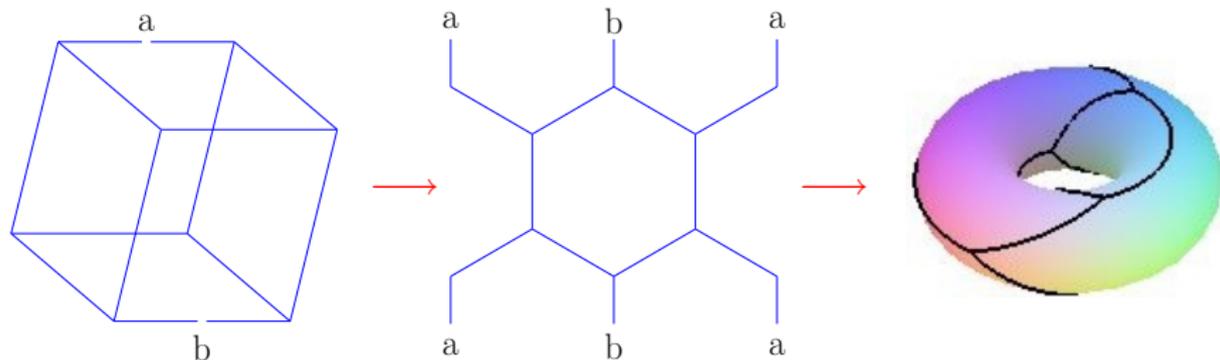


# Cube Is “Smallest Graphene” (Graphene $4 \times 2$ )

Embeddings of graph of **Hexahedron** form

**4**-gonal (**6** tetragons) regular tiling of sphere  $\mathbb{S}^2$  and

**6**-gonal (**4** hexagons) regular tiling of torus  $\mathbb{T}^2$



# Some Quantitative Characteristics

of lattices, their groups and orbits

Lattice	$ V(\Gamma) $	$ \text{Aut}(\Gamma) $	$\Omega = q^{ \text{V}(\Gamma) }$	$N_{\text{orbits}}$
Tetrahedron	4	24	16	5
Hexahedron	8	48	256	22
Icosahedron	12	120	4096	82
Dodecahedron	20	120	1048576	9436
Graphene $6 \times 4$ Torus	24	48	16777216	355353
Graphene $6 \times 4$ Klein bottle	24	16	16777216	1054756
Triangular $4 \times 6$	24	96	16777216	180070
Square $5 \times 5$	25	200	33554432	172112
Buckyball	60	120	$1152921504606846976$ $\approx 10^{18}$	$9607679885269312$ $\approx 10^{16}$

Klein bottle arrangement is **non-transitive** (2 orbits of sizes 8 and 16)

We discard such graphs as counterintuitive **nonhomogeneous** spaces

# C Program

## Input

- **Graph**  $\Gamma = \{N_1, \dots, N_n\}$   
 $N_i$  is neighborhood of  $i$ th vertex
- **Cellular automata branch:**
  - ▶ Set of local **rules**  $R = \{r_1, \dots, r_m\}$   
 $r_i$  is bit representation of  $i$ th rule
- **Lattice model branch:**
  - ▶ **Hamiltonian** of the model
- Control **parameters**

# C Program

## Program produces

- automorphism group  $\text{Aut}(\Gamma)$
- Cellular automata branch:
  - ▶ phase portraits of automata modulo  $\text{Aut}(\Gamma)$  for all rules from  $R$   
Manipulating control parameters we can
    - ★ select automata with specified properties, e.g., reversibility, Hamiltonian conservation etc.
    - ★ search automata producing specified structures, e.g., limit cycles, isolated cycles, “Gardens of Eden”, “Spaceships” etc.
- Lattice model branch:
  - ▶ partition function and other characteristics of the model
  - ▶ search of phase transitions

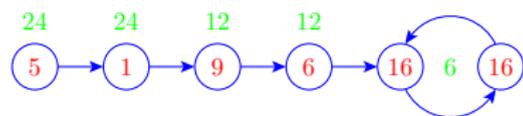
# General Dynamical Principle Induced By Symmetry

## For Any Deterministic Dynamical System

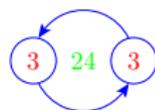
- trajectories can be directed only from larger orbits to smaller orbits or to orbits of the same size
- periodic trajectories must lie within the orbits of equal size
- Meaning: any isolated system may only lose information in its evolution — analog of “Second Law of Thermodynamics”
- Simple consequence of the fact that  
“deterministic” means “functional”

# Group Origin of Emergent Structures: typical phase portrait

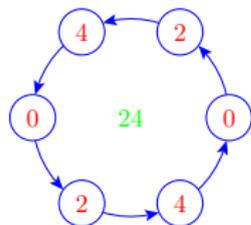
modulo  $\text{Aut}(\Gamma)$  contains **soliton**-like structures — “spaceships”



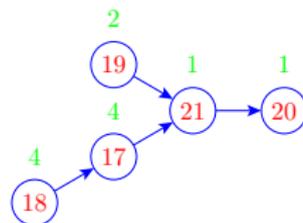
Solitons



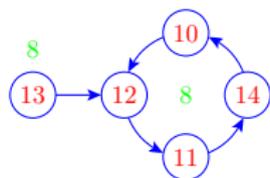
Solitons



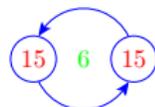
Solitons



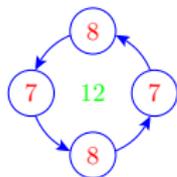
Sink



Ordinary limit cycles



Solitons



Solitons

# Eventually (Part of) Dynamics Is Reduced To Group Actions

State  $\varphi(x) \in O_i$  in cycle starting at moment 0 evolves after some time  $t$  into state  $\varphi_t(x) = A_t(\varphi(x))$  in the same orbit  $O_i$

Hence:

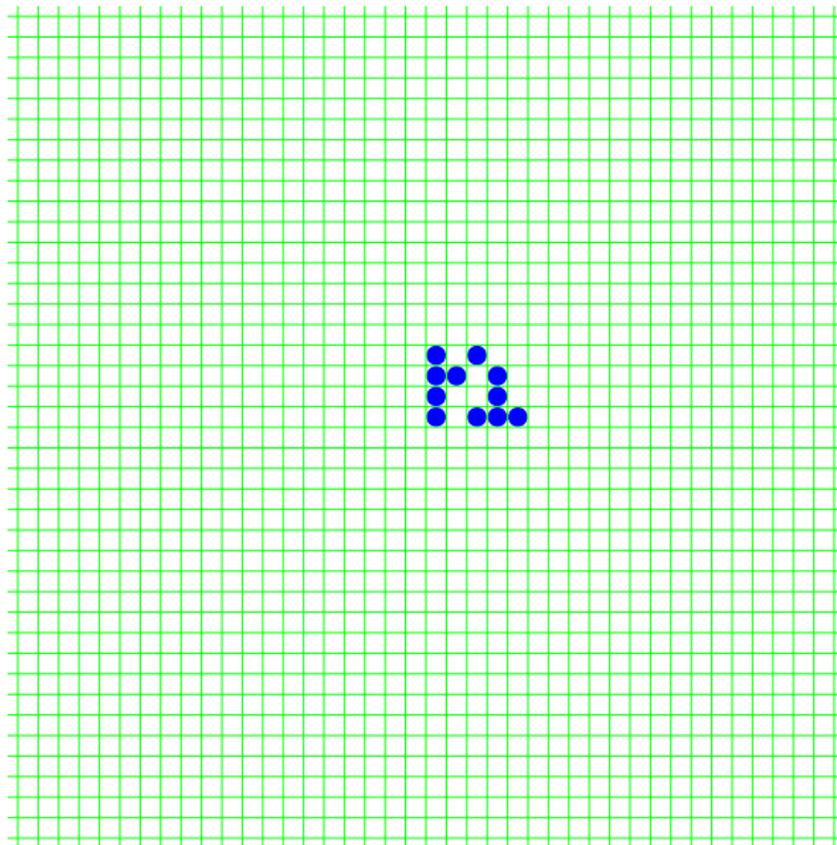
Evolution operator  $A_t$  can be replaced by group action

$$\varphi_t(x) = A_t(\varphi(x)) = \varphi(g_t^{-1}x)$$

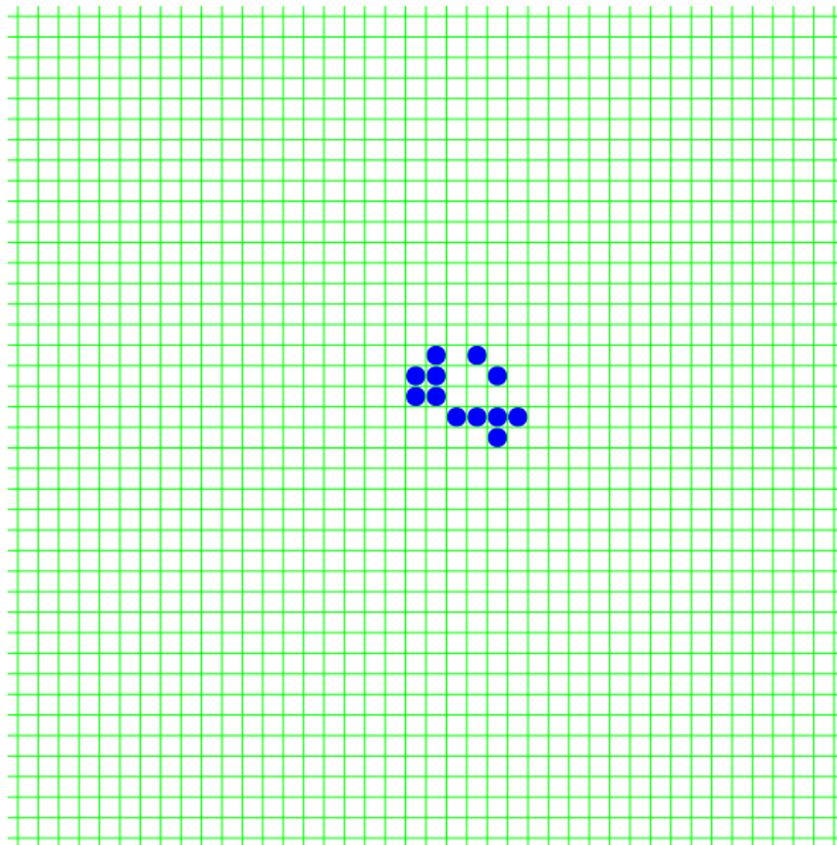
i.e., initial shape  $\varphi(x)$  is reproduced via some movement in space — formation of soliton-like structure

Galilei group analogy: many equations of mathematical physics have running wave solutions  $\varphi(x - vt)$  ( $= \varphi(g_t^{-1}x)$  for Galilei group)

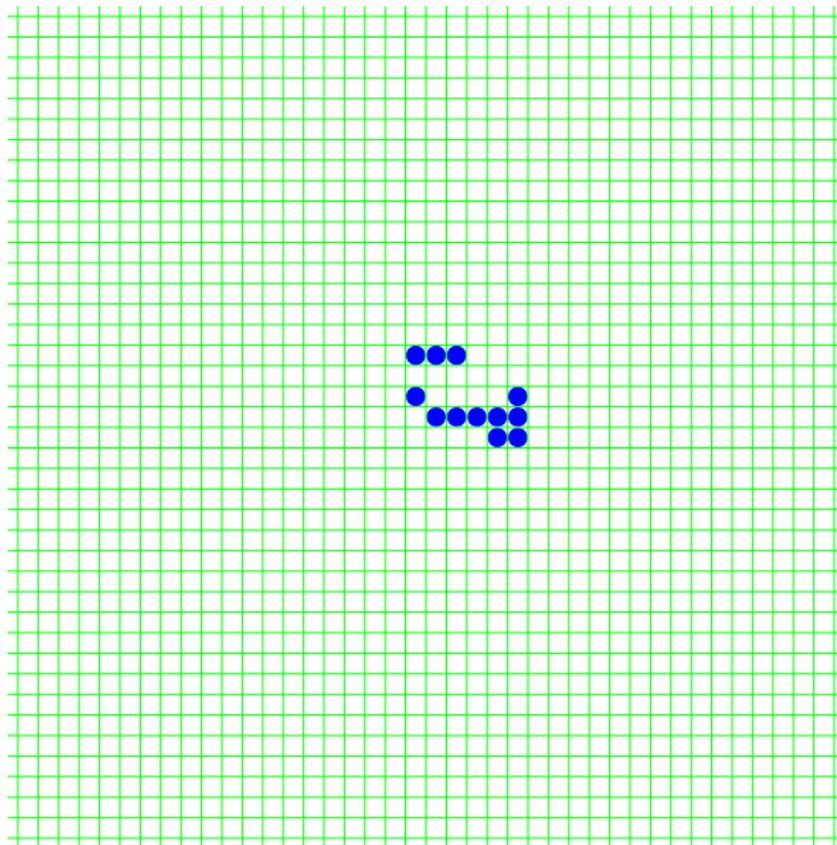
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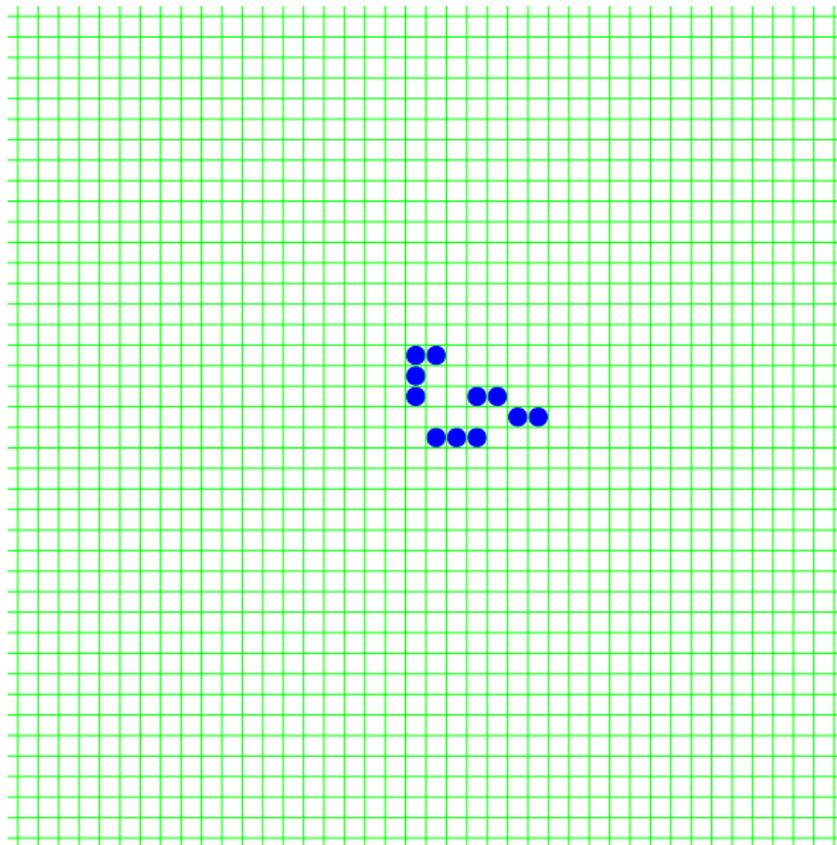


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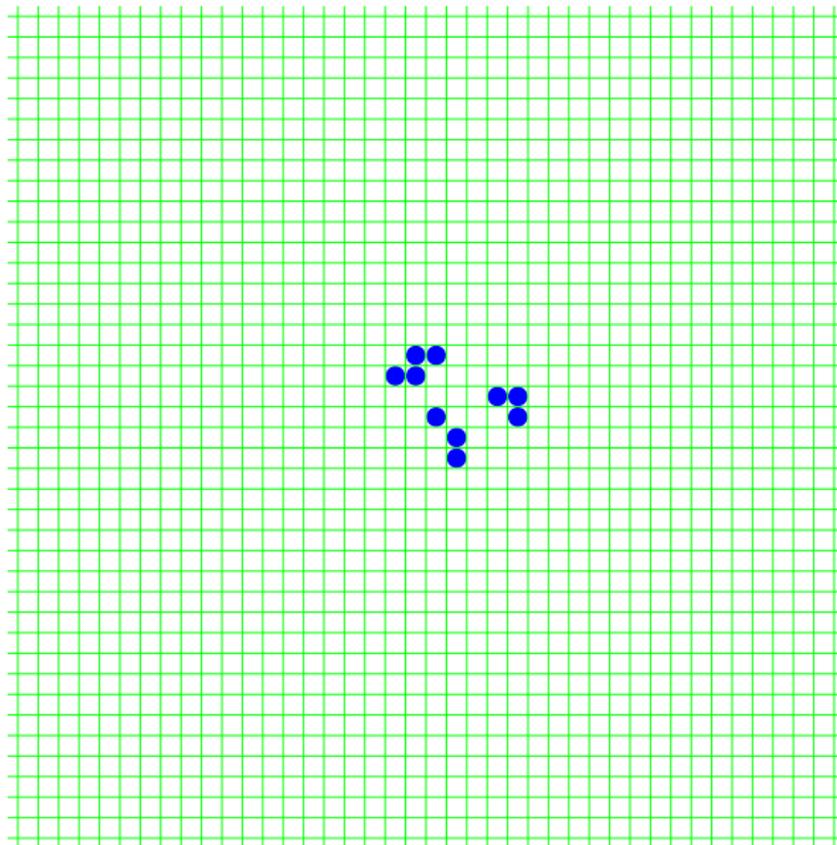




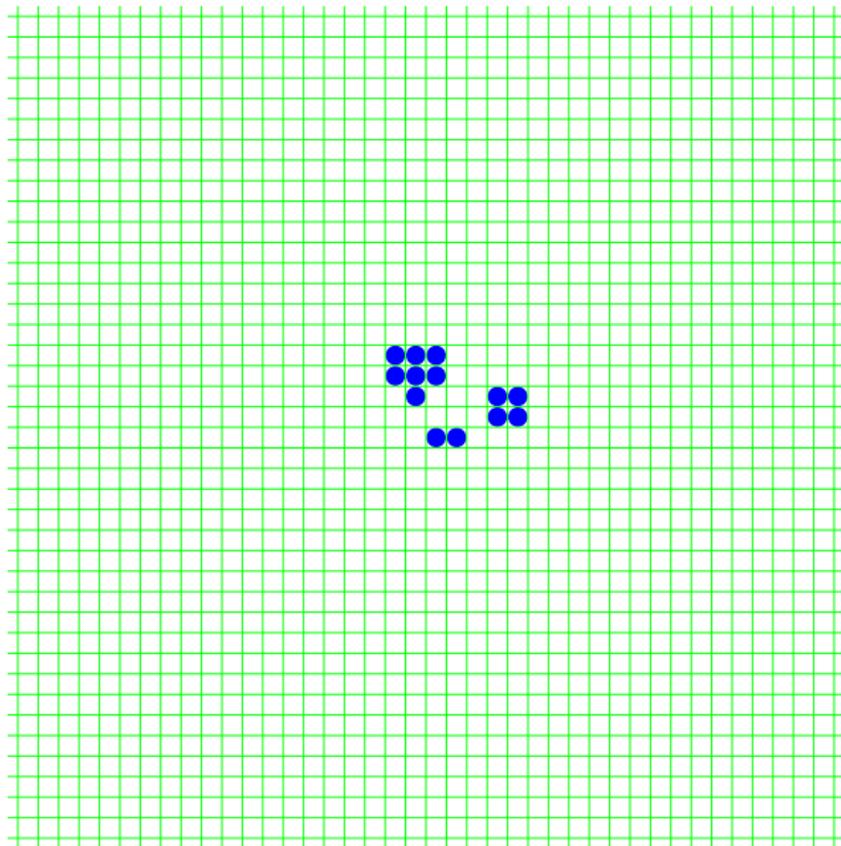
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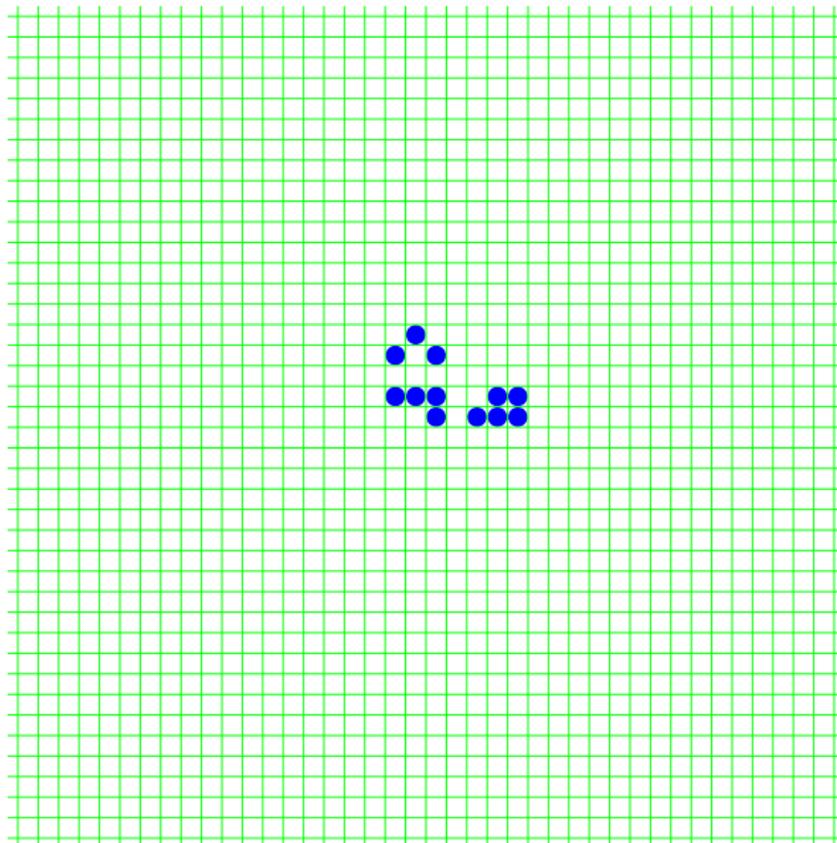
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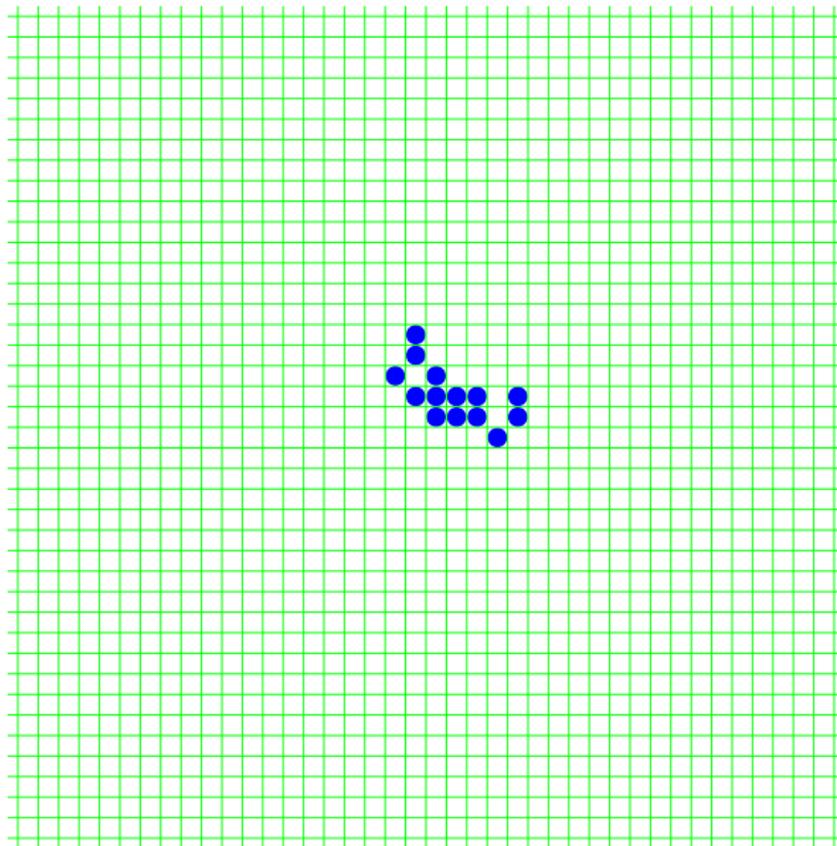
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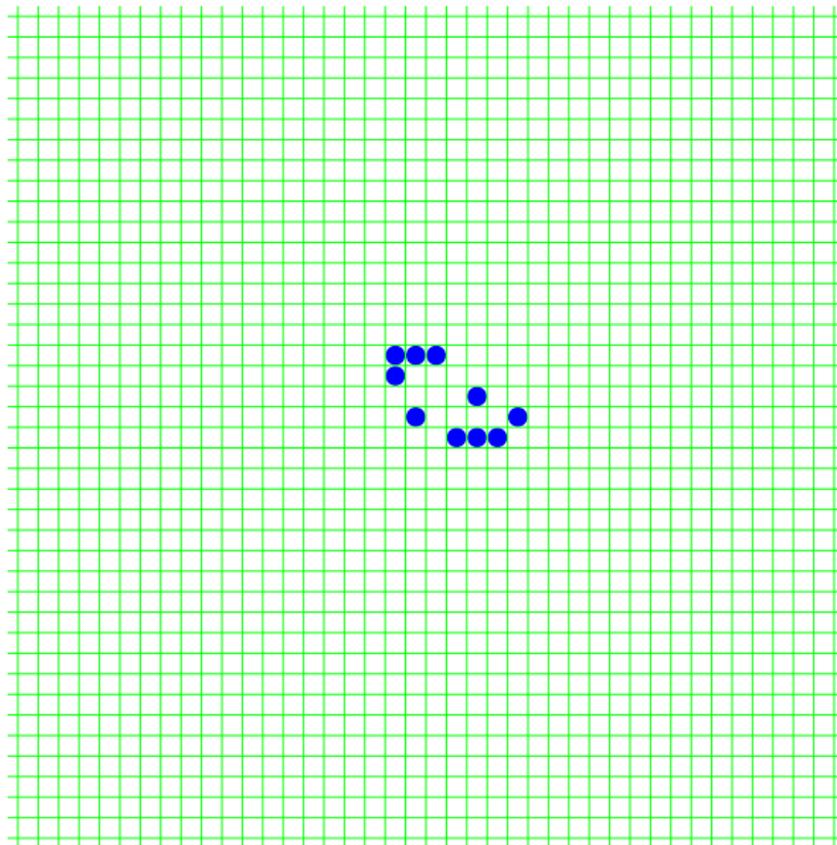
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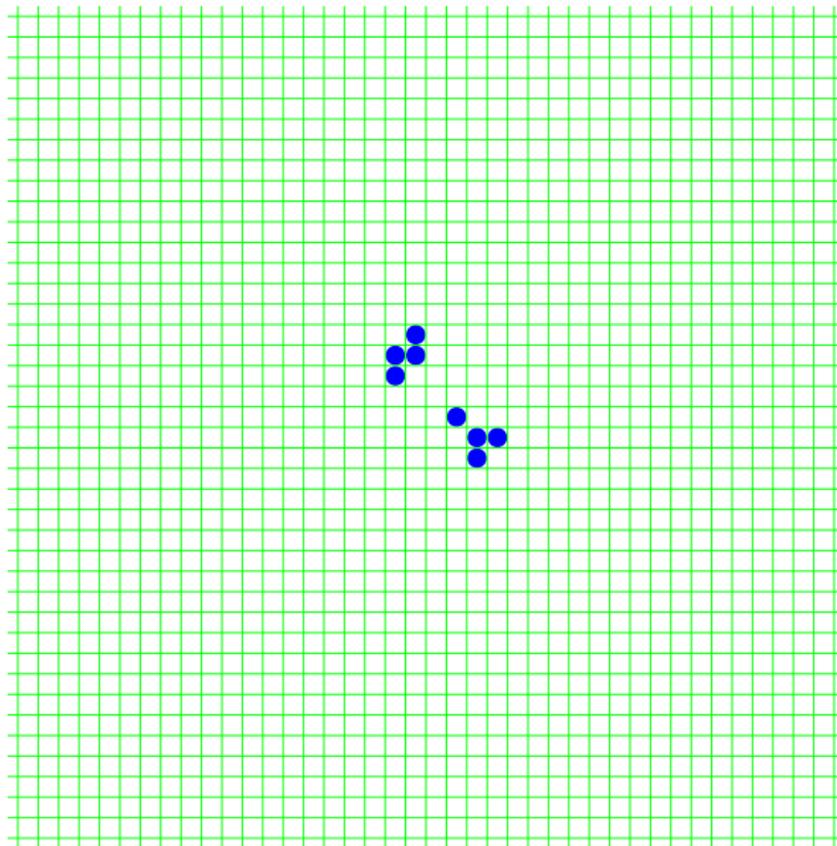
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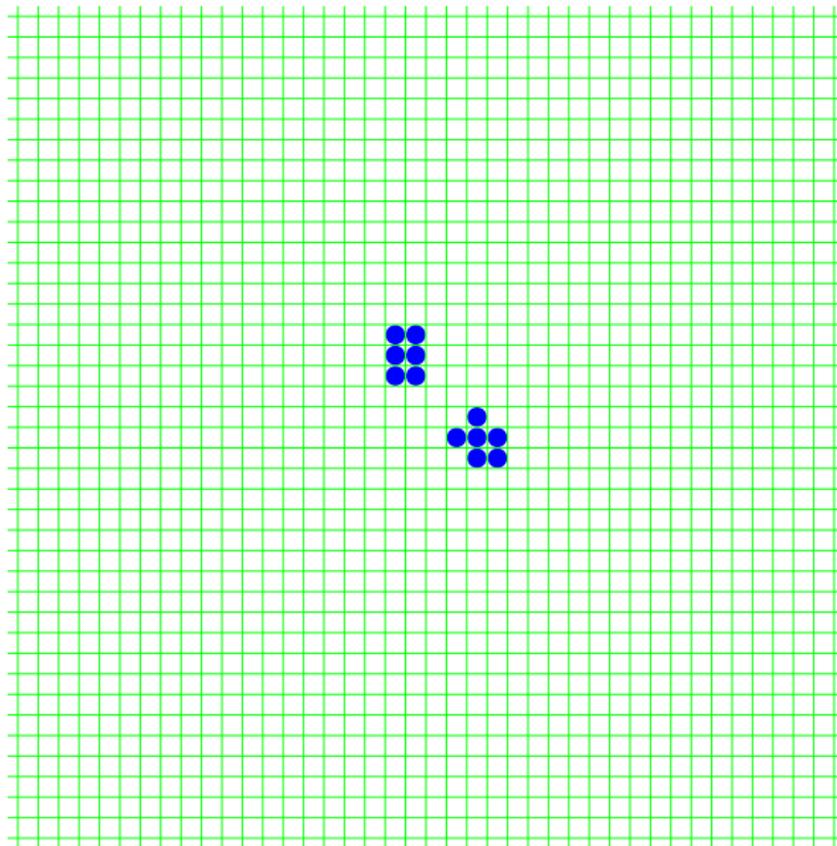
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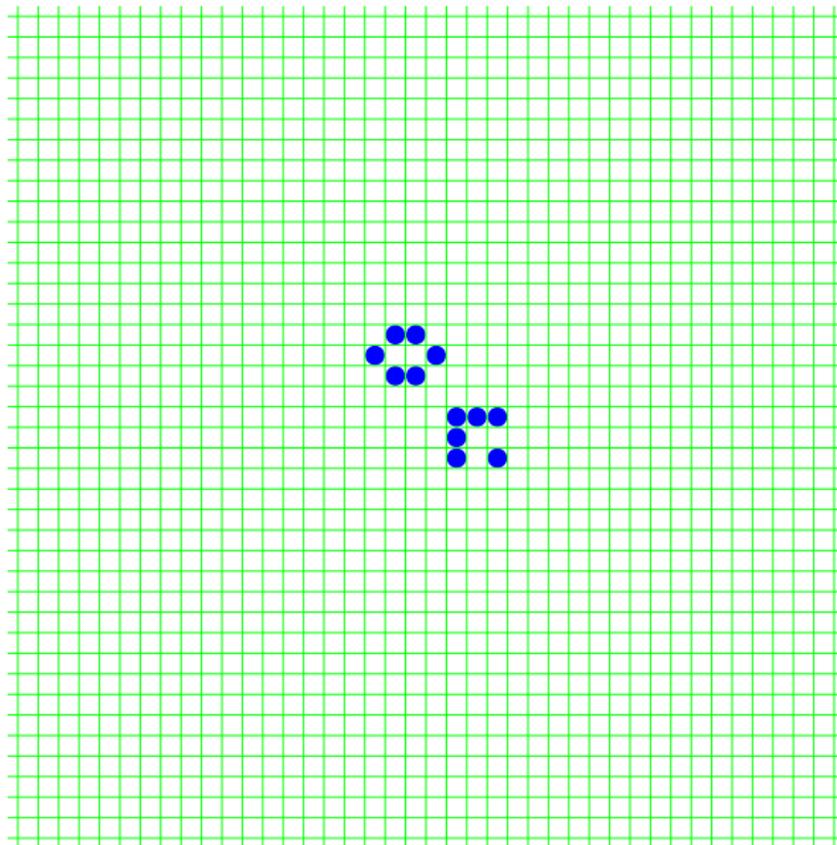
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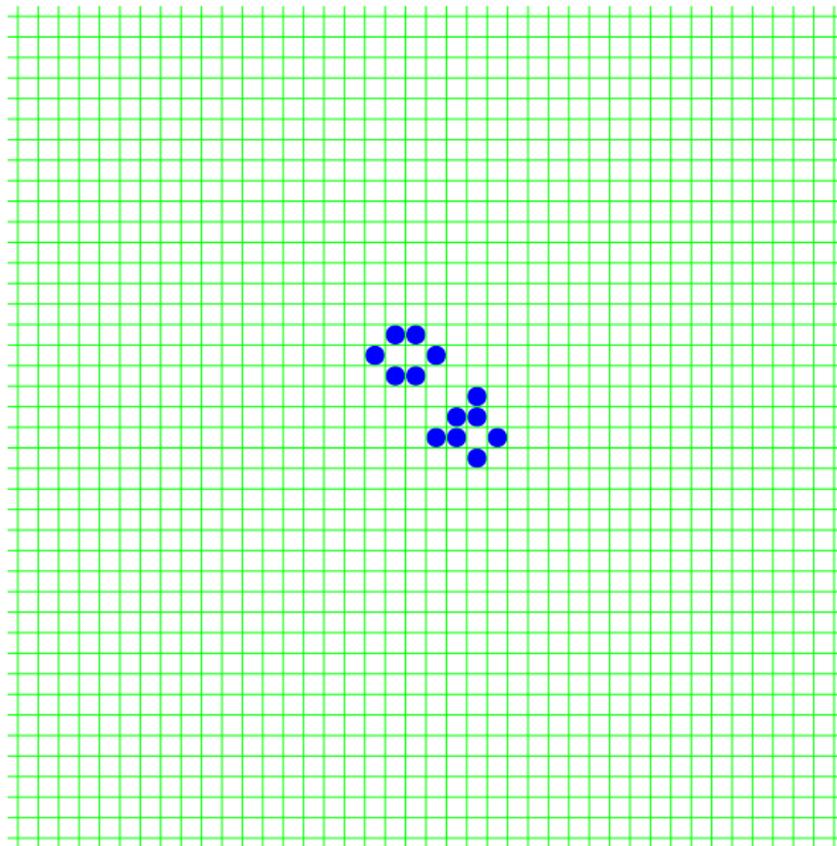
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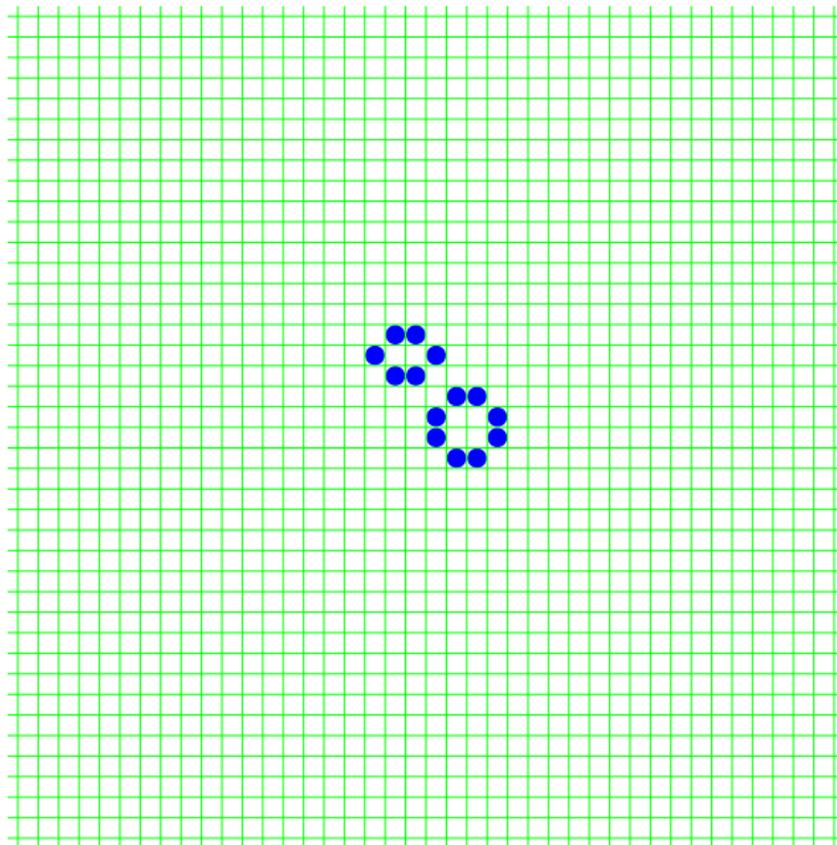
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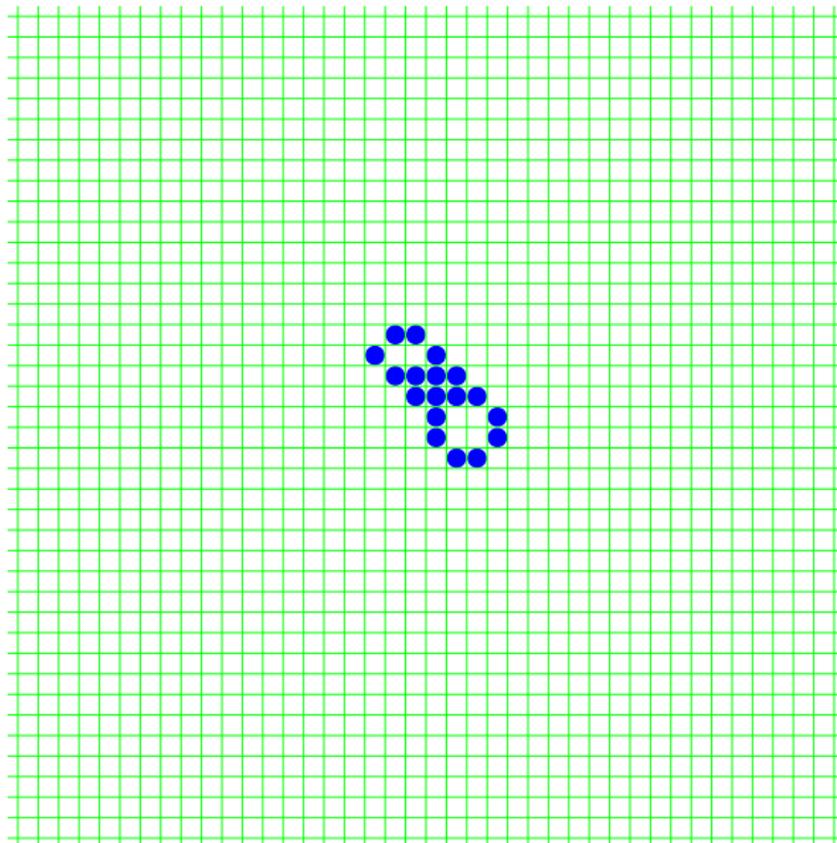
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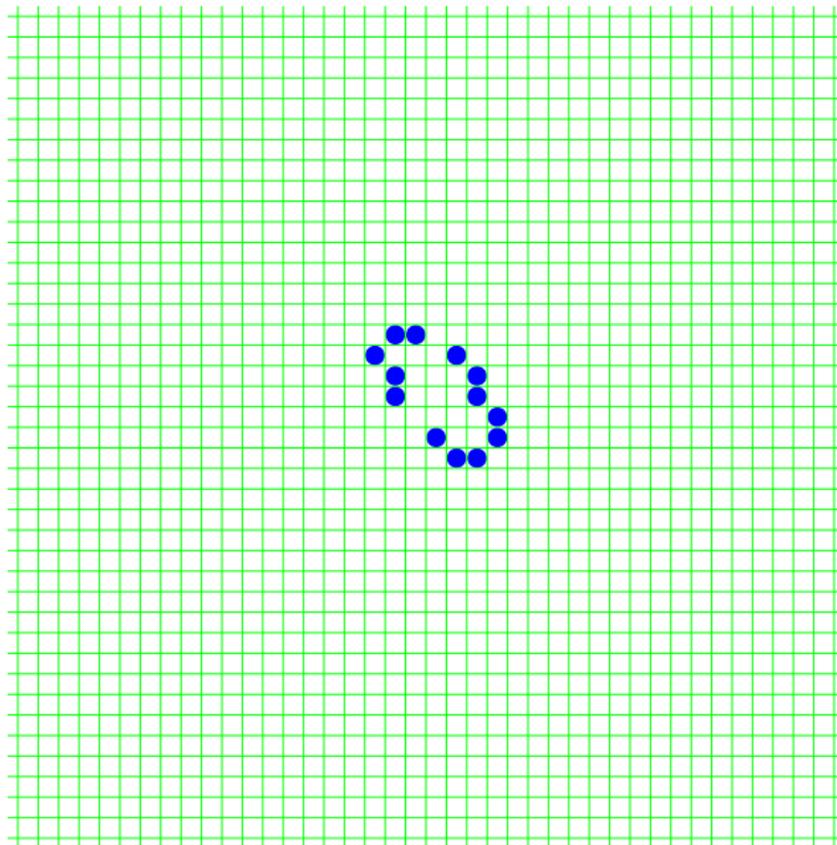
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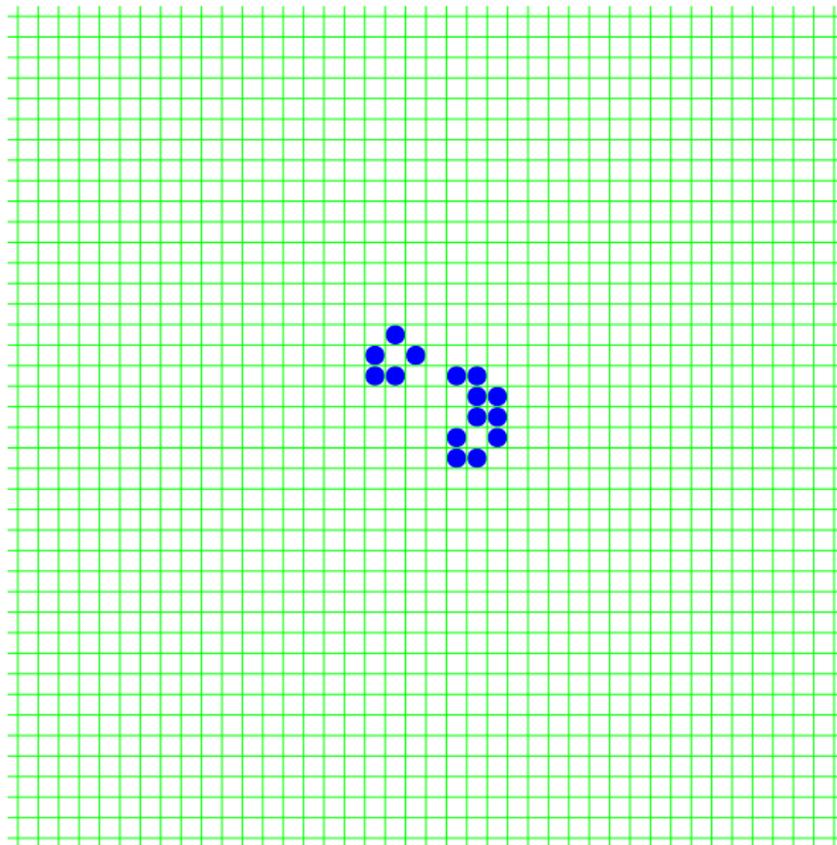
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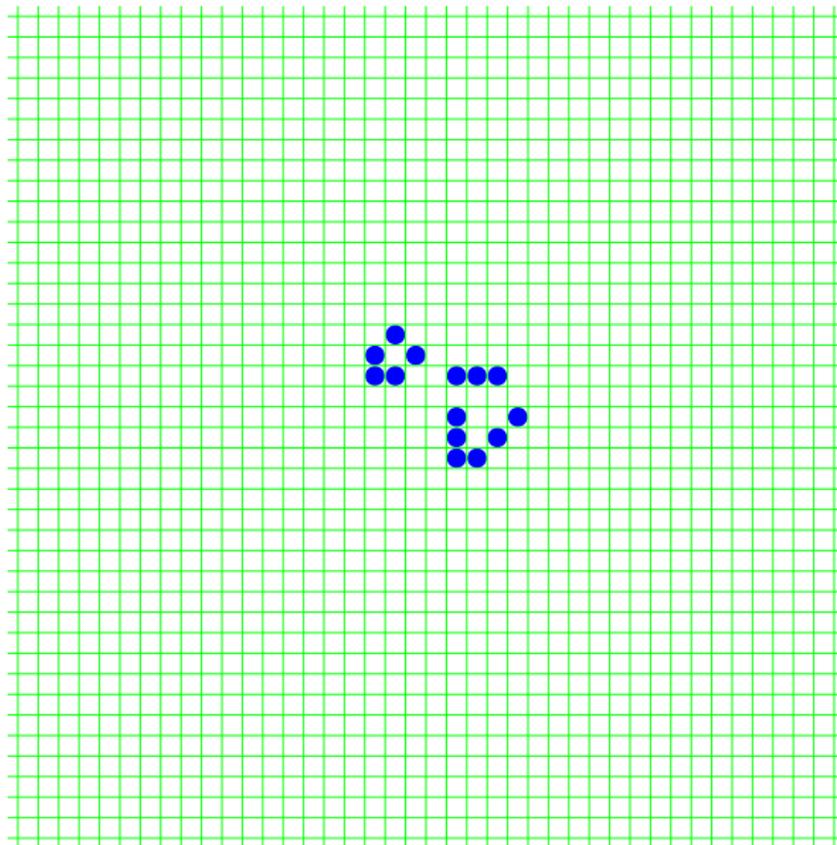
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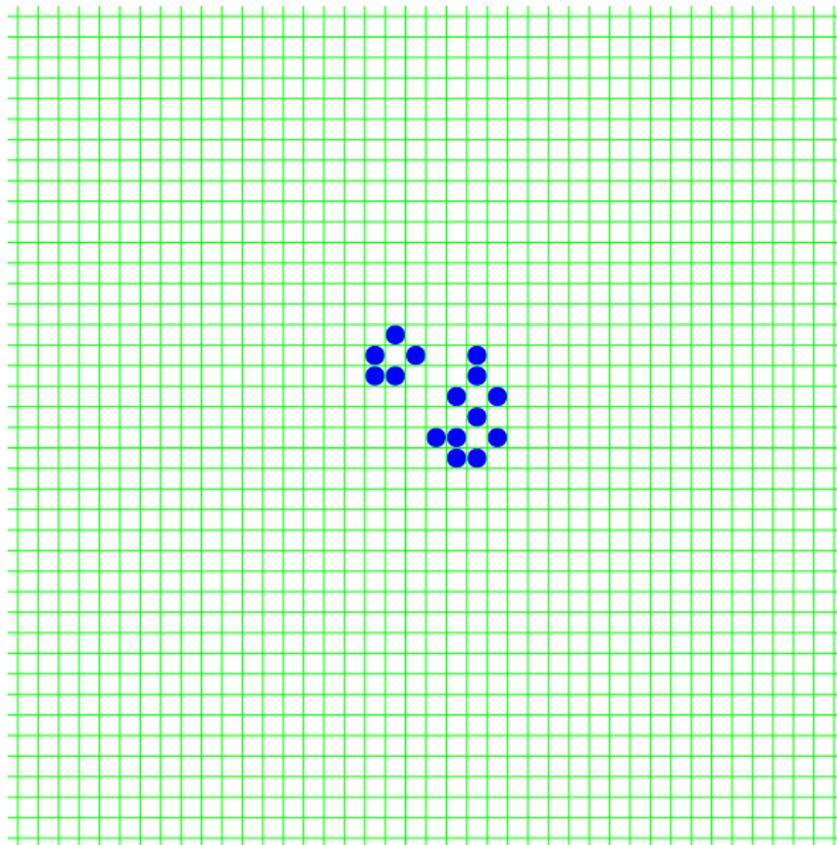
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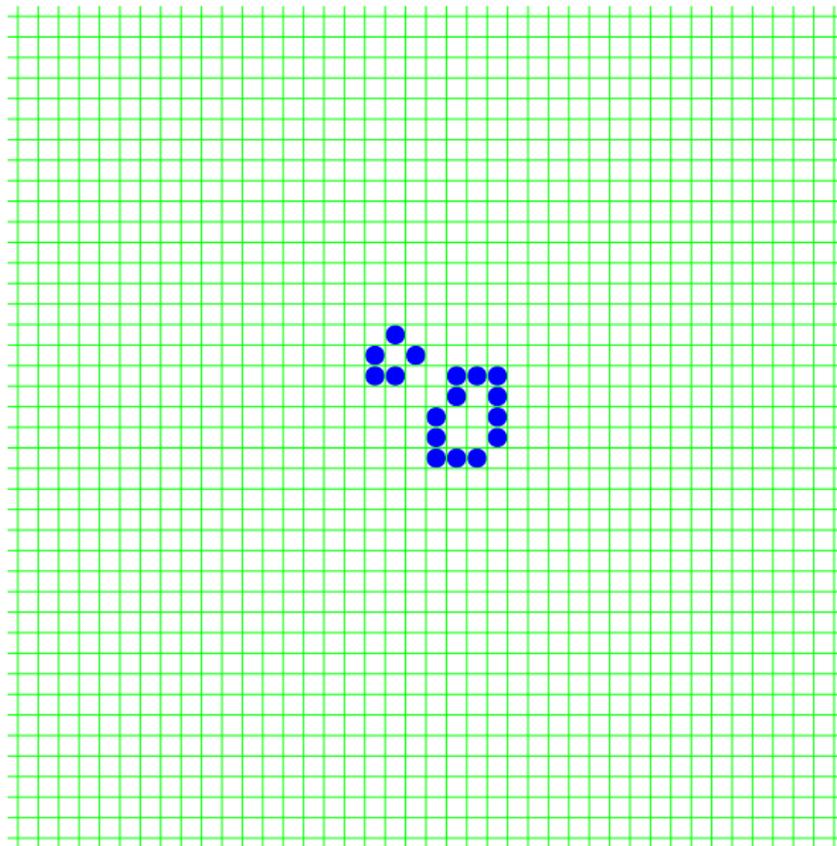
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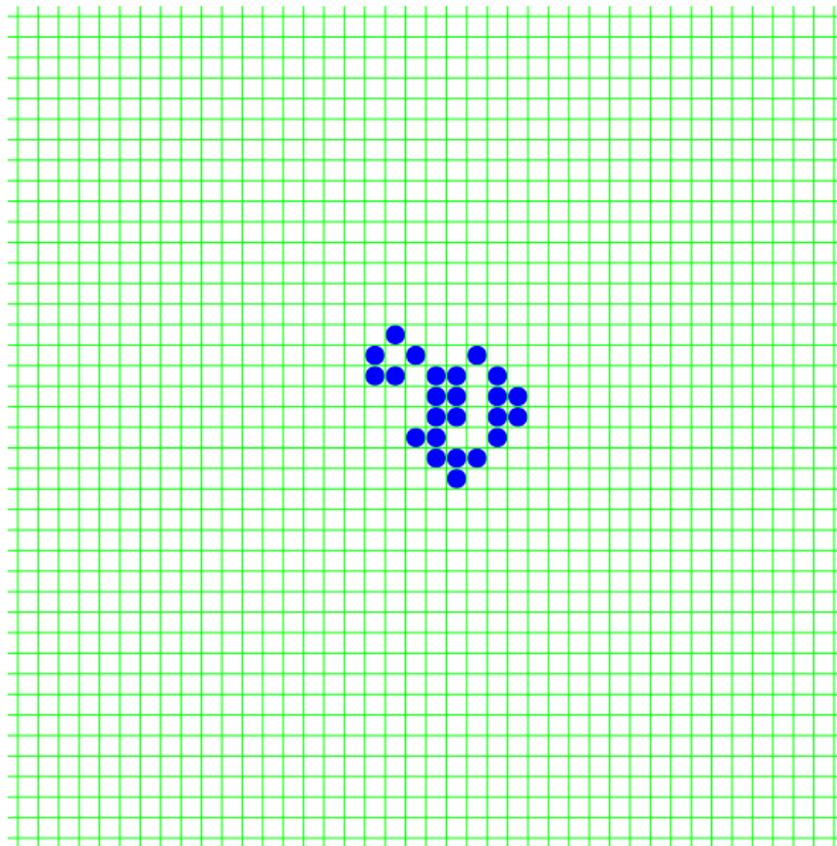
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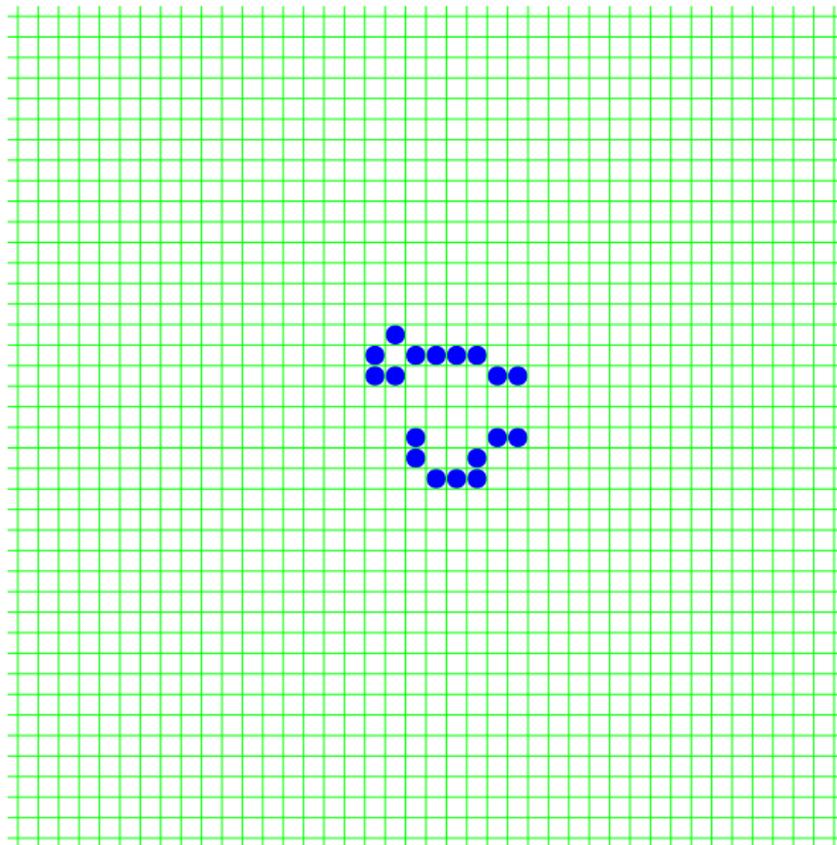
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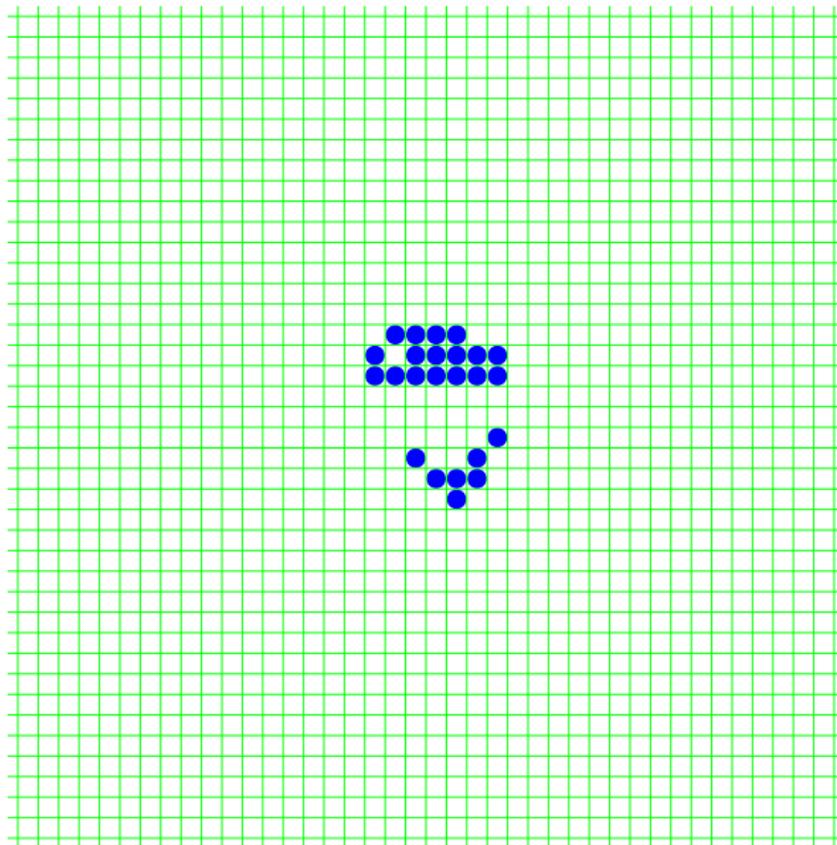
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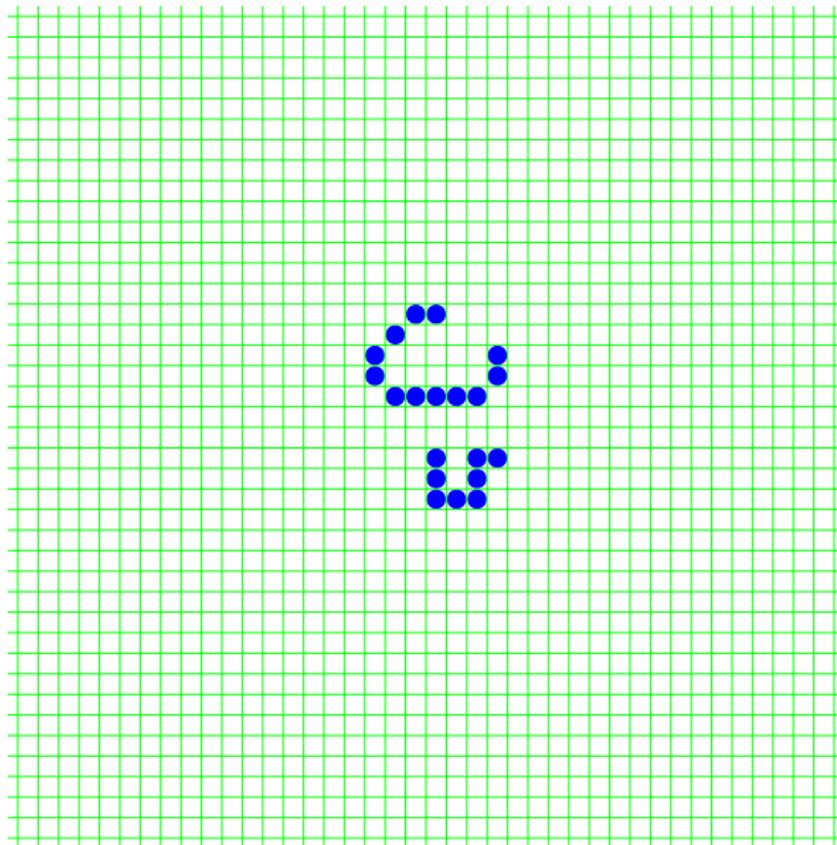
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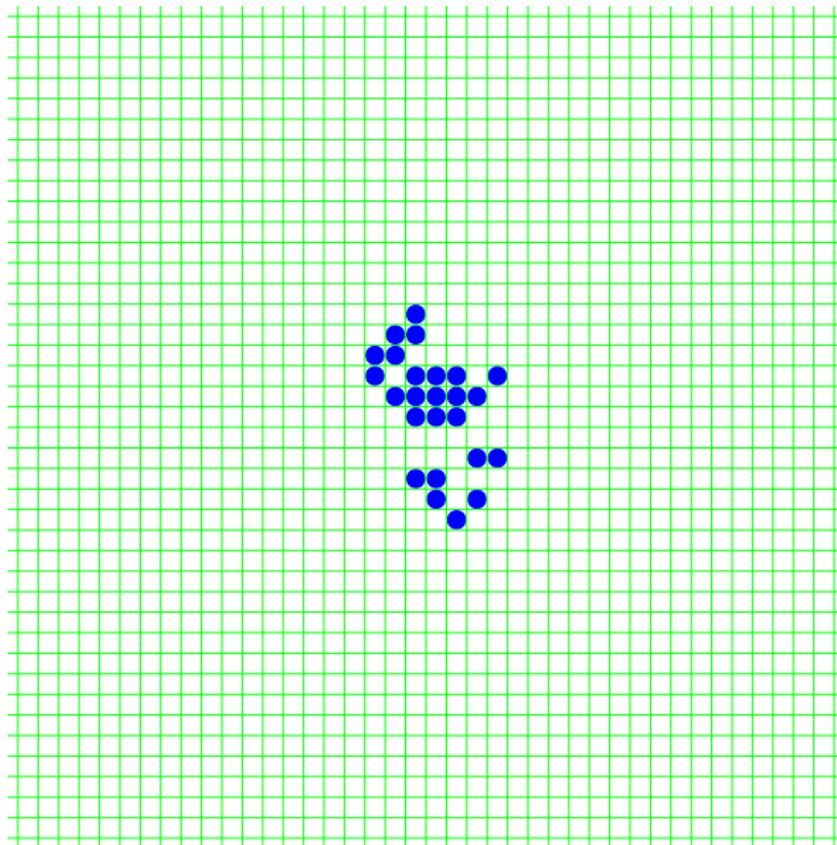
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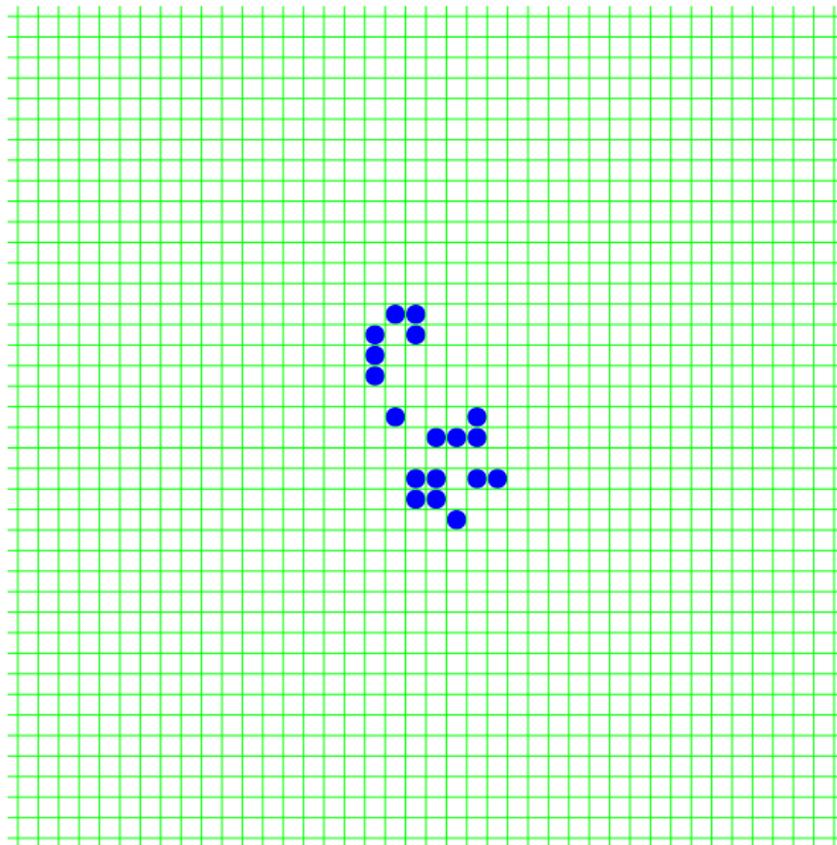
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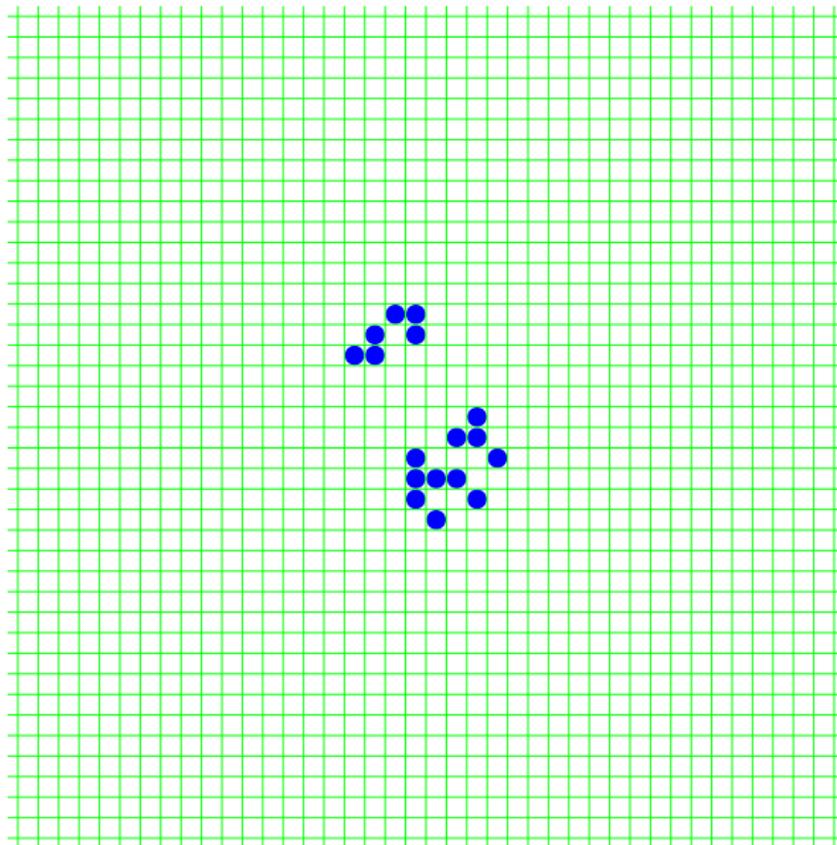
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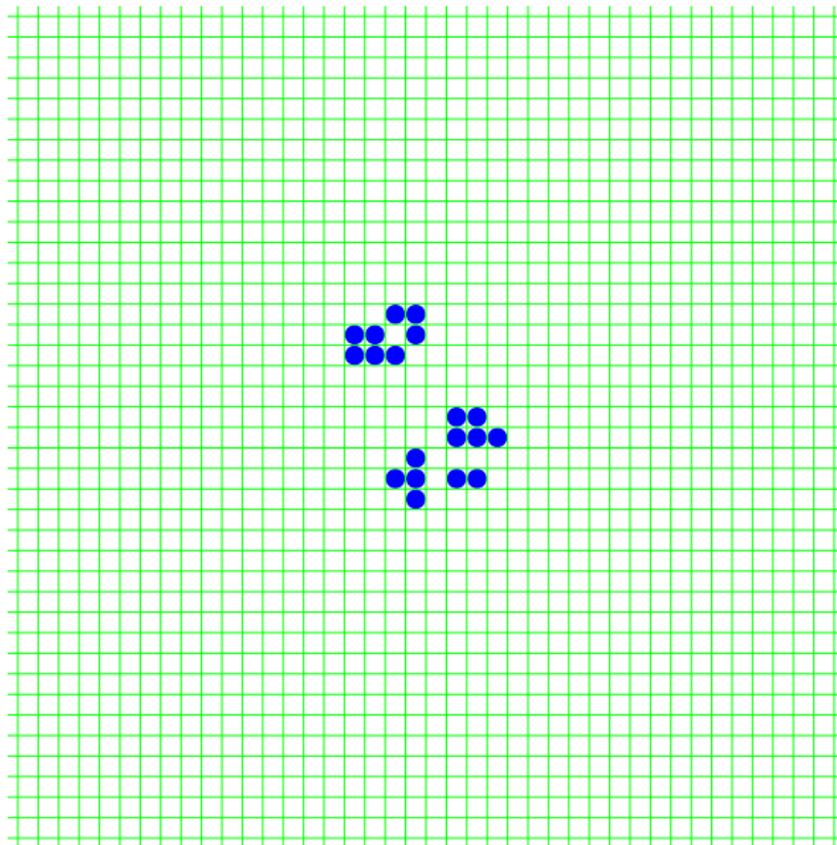
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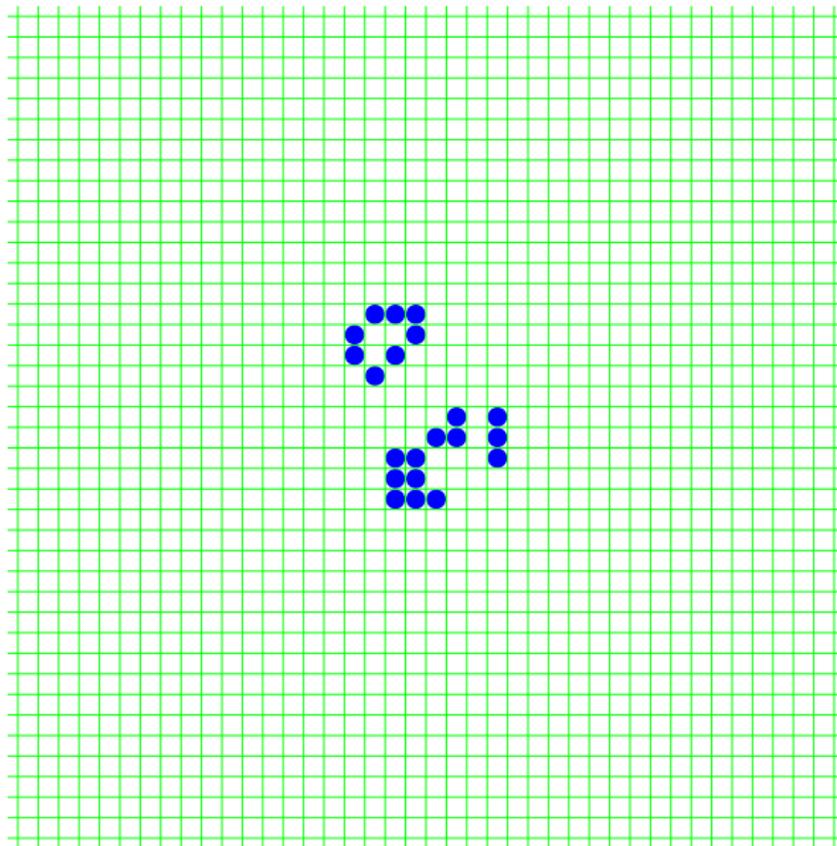
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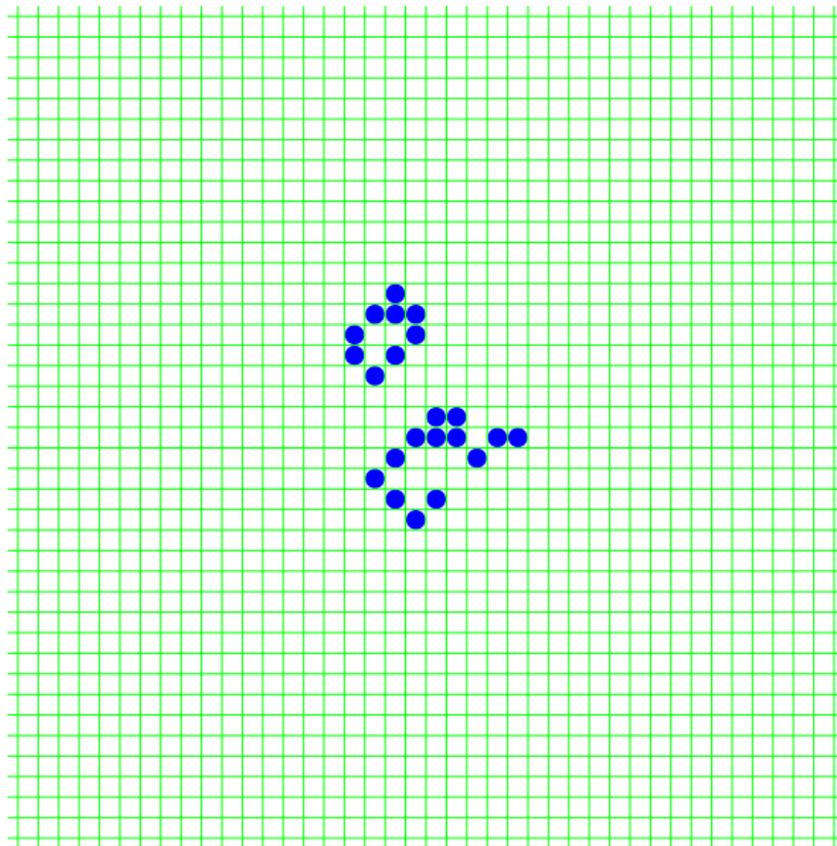
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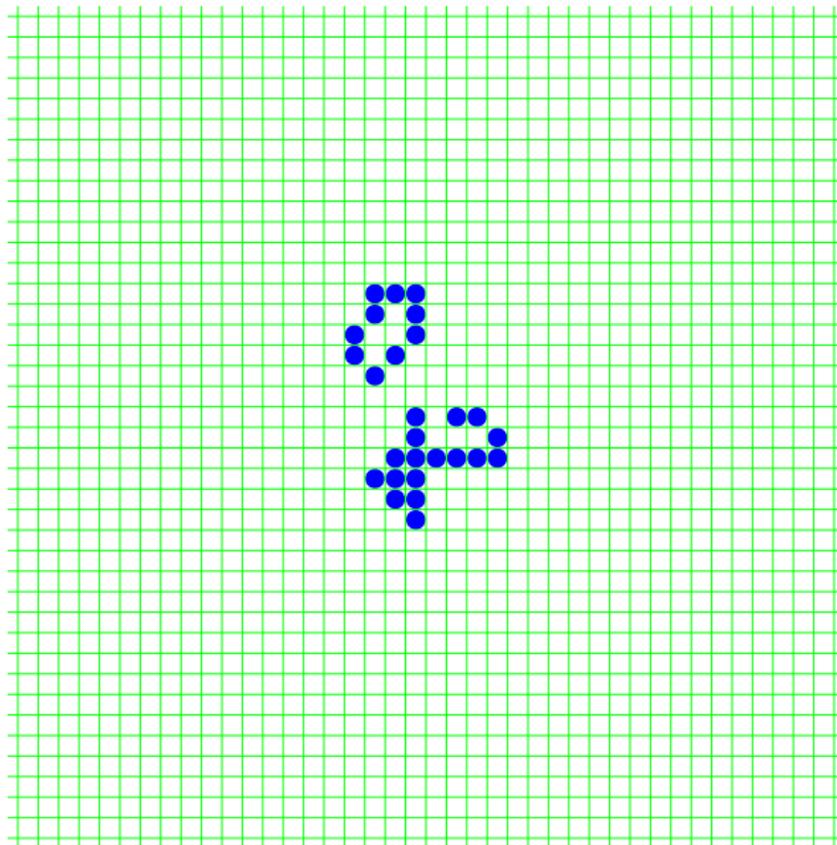
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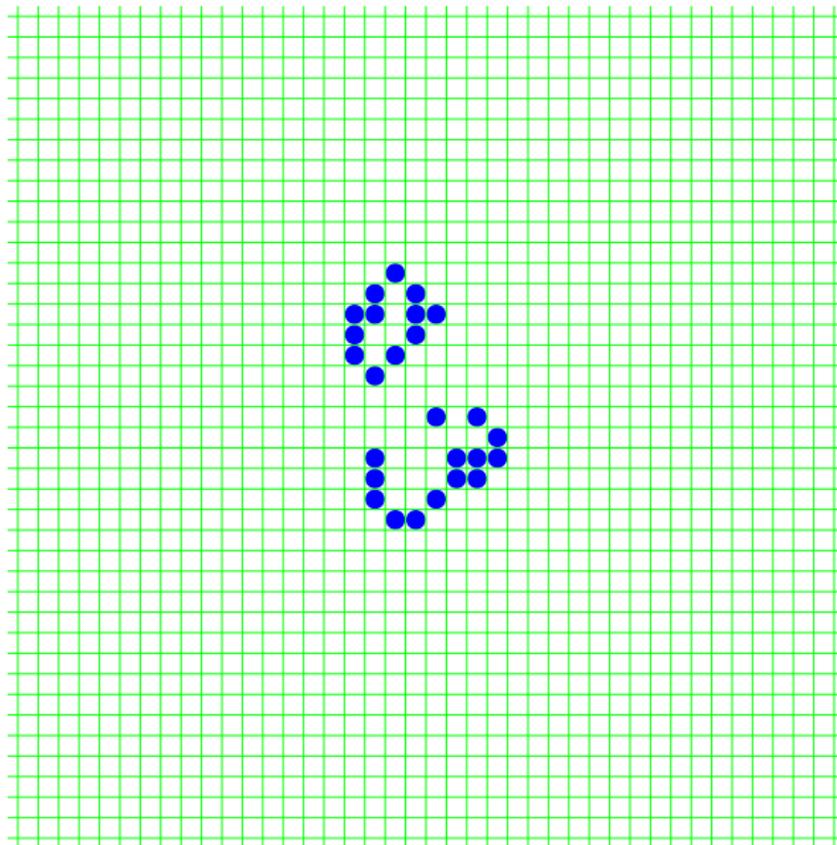
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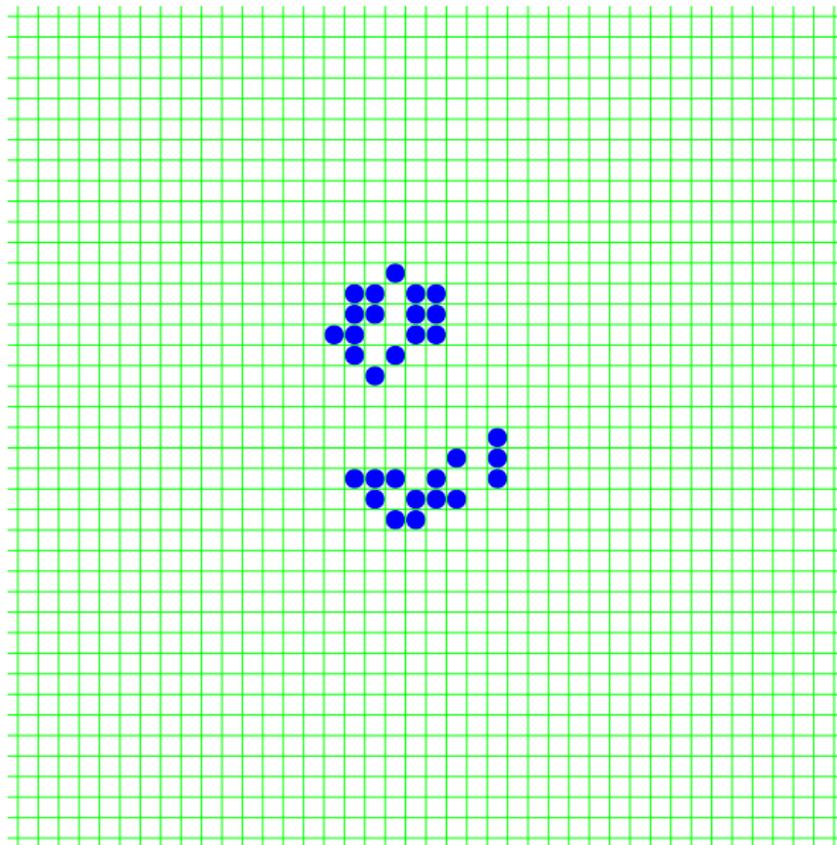
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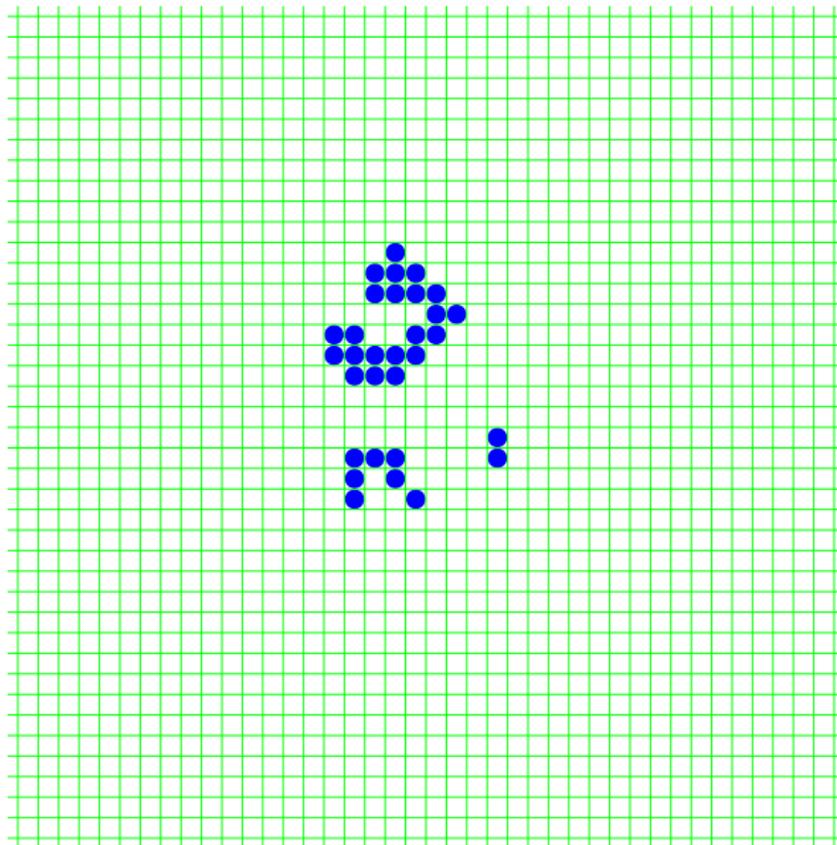


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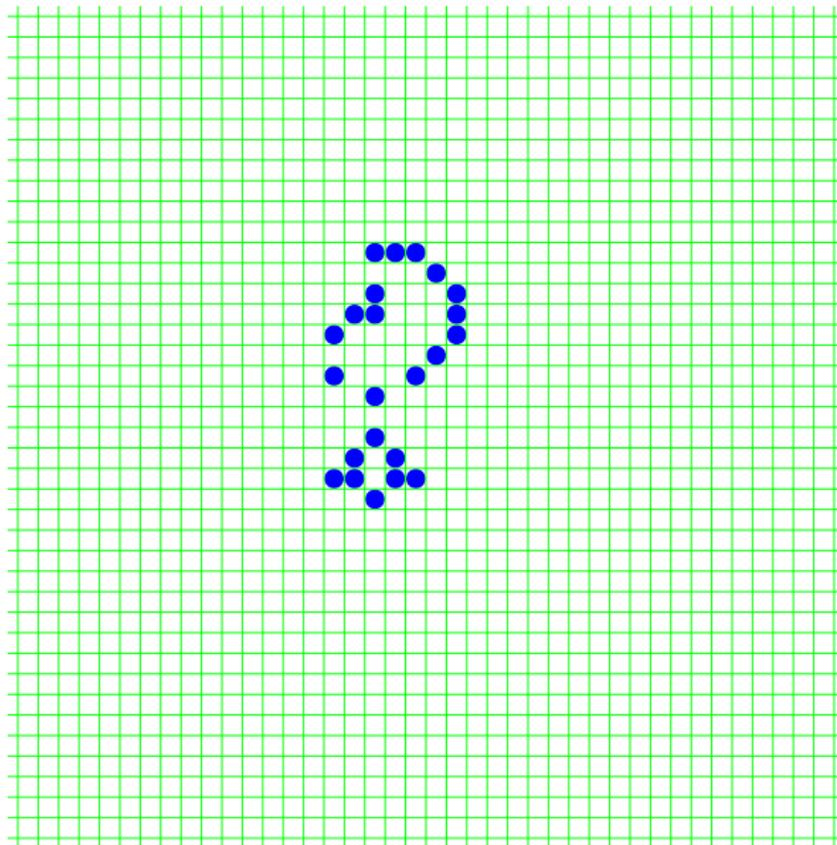




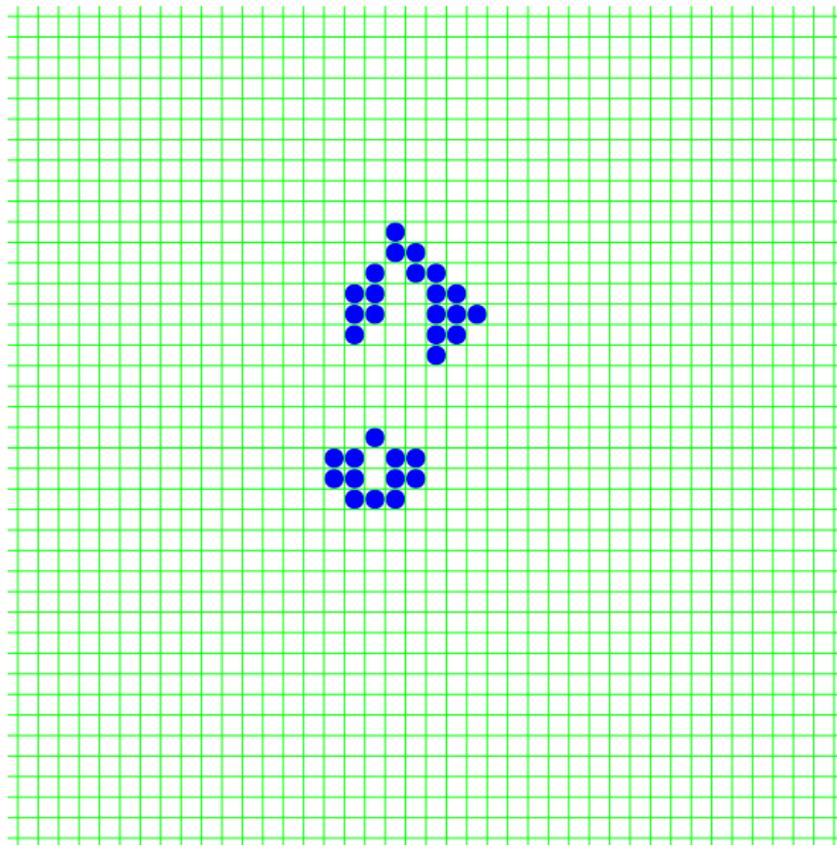
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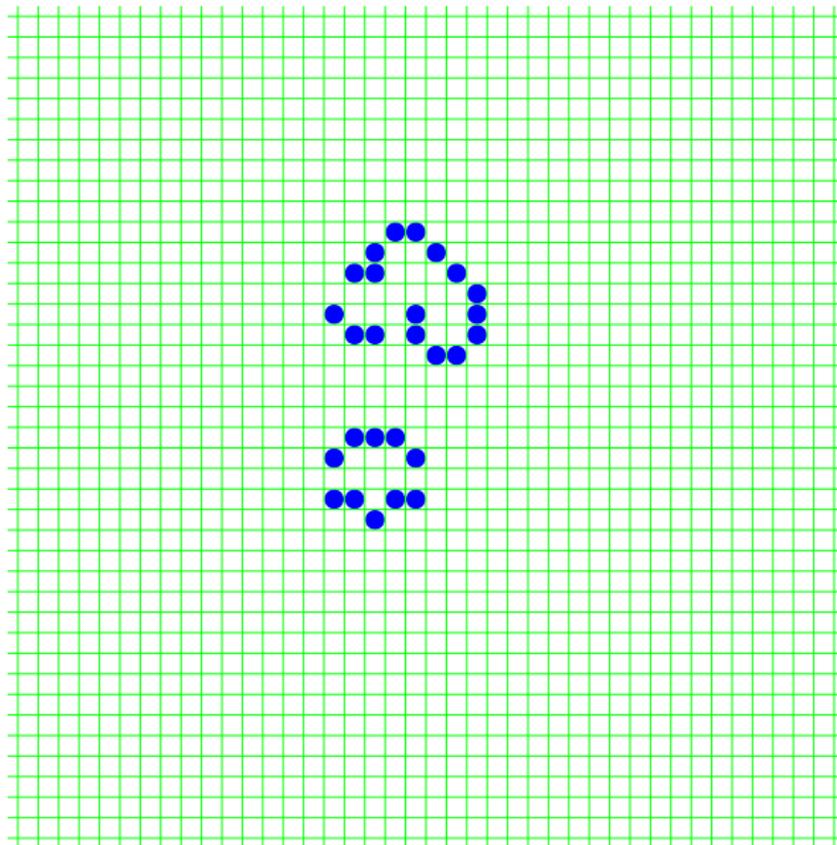
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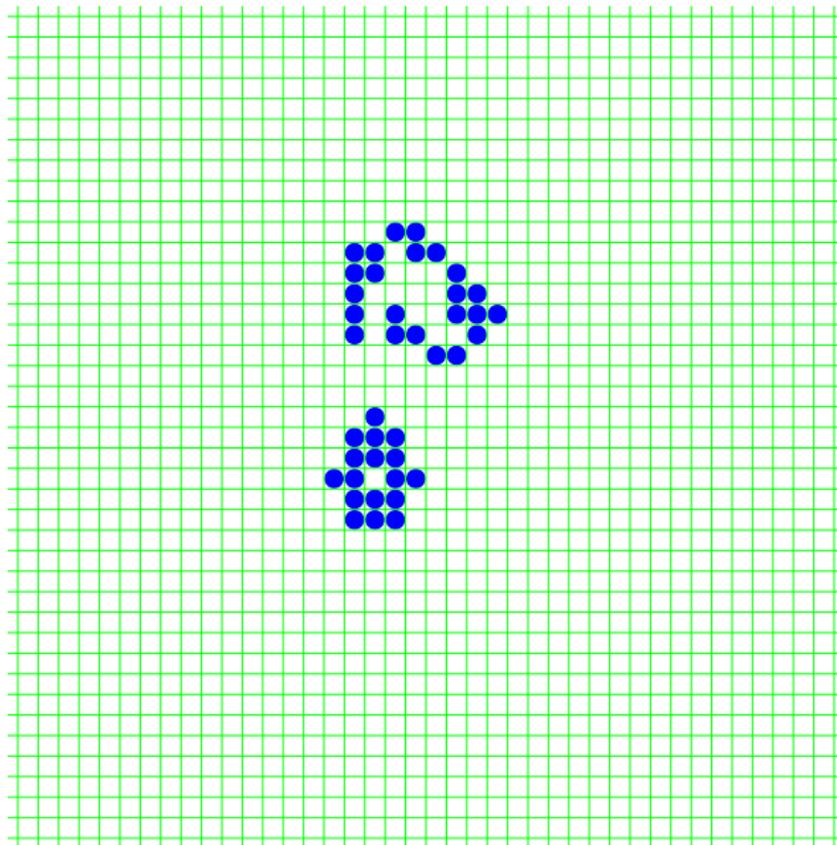
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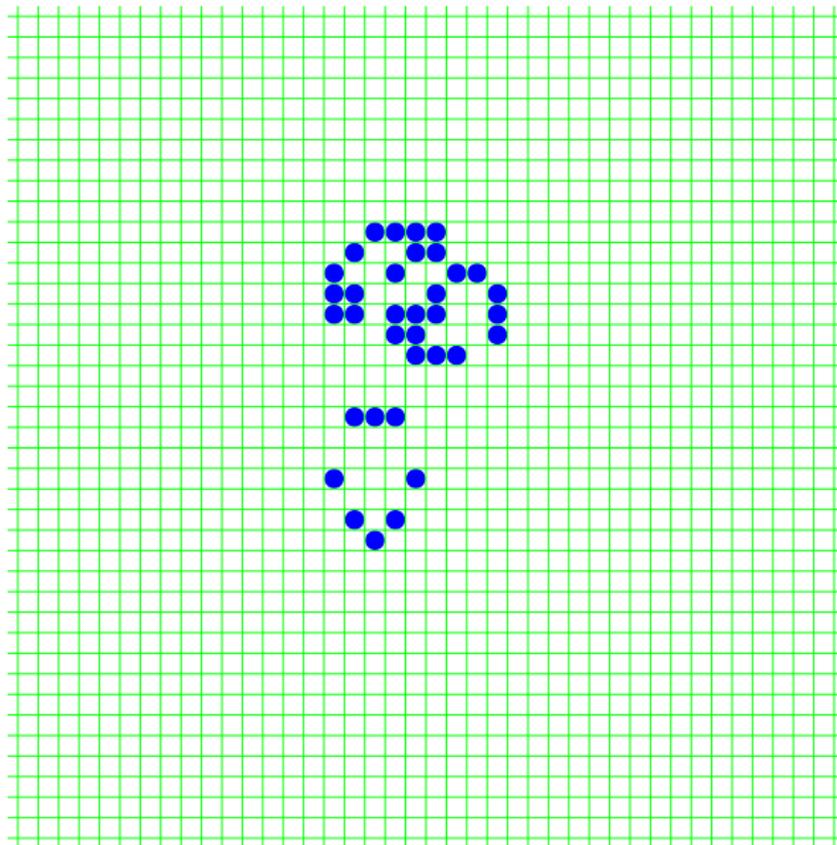
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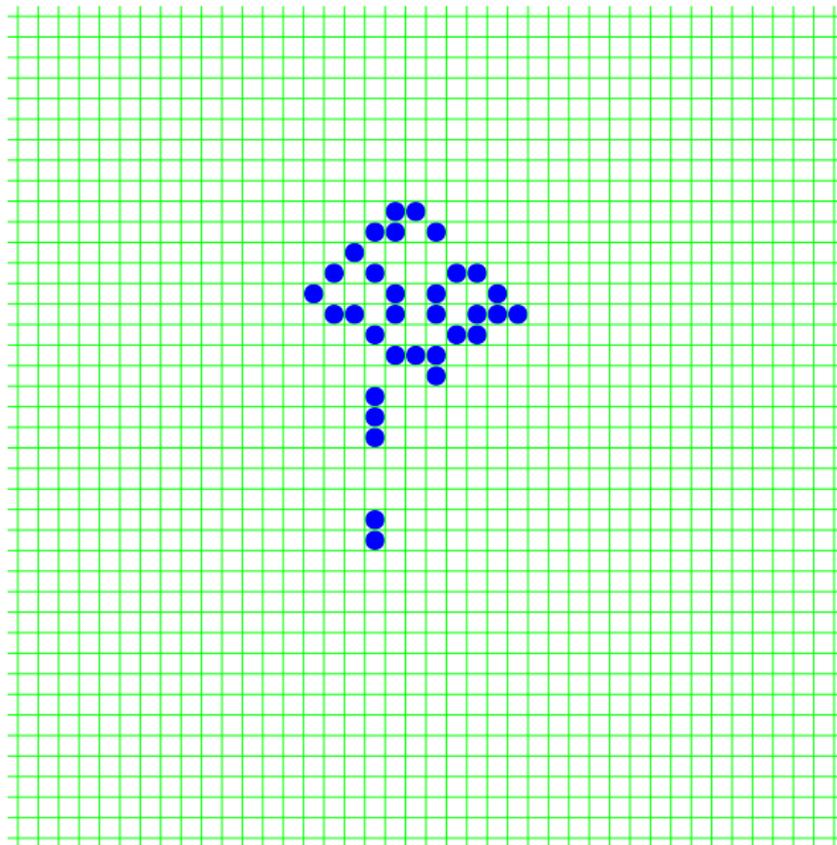
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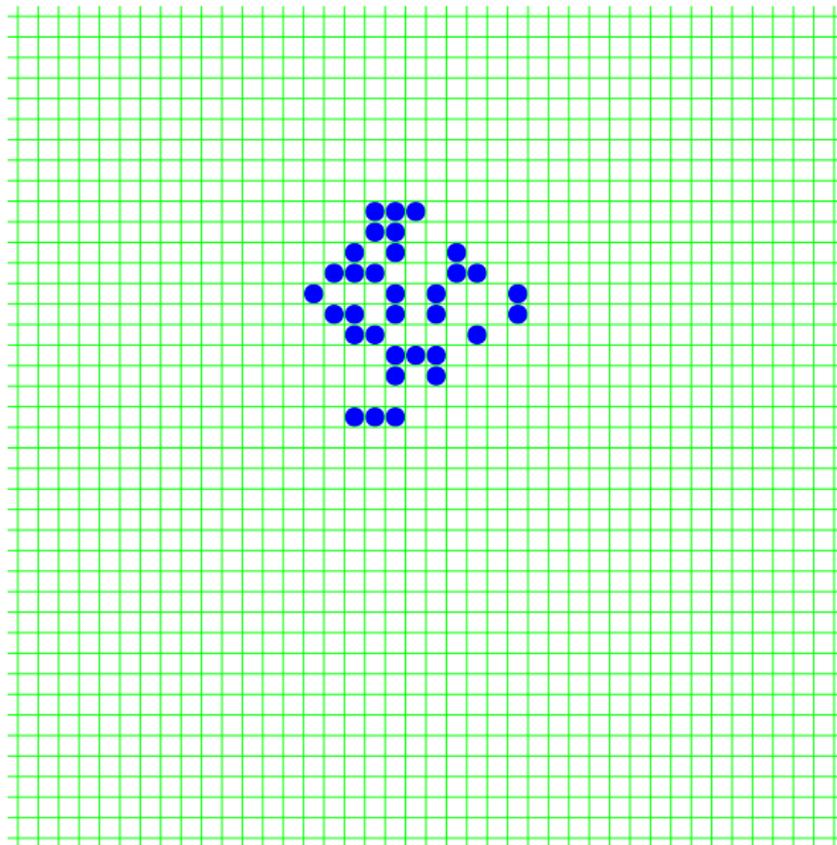
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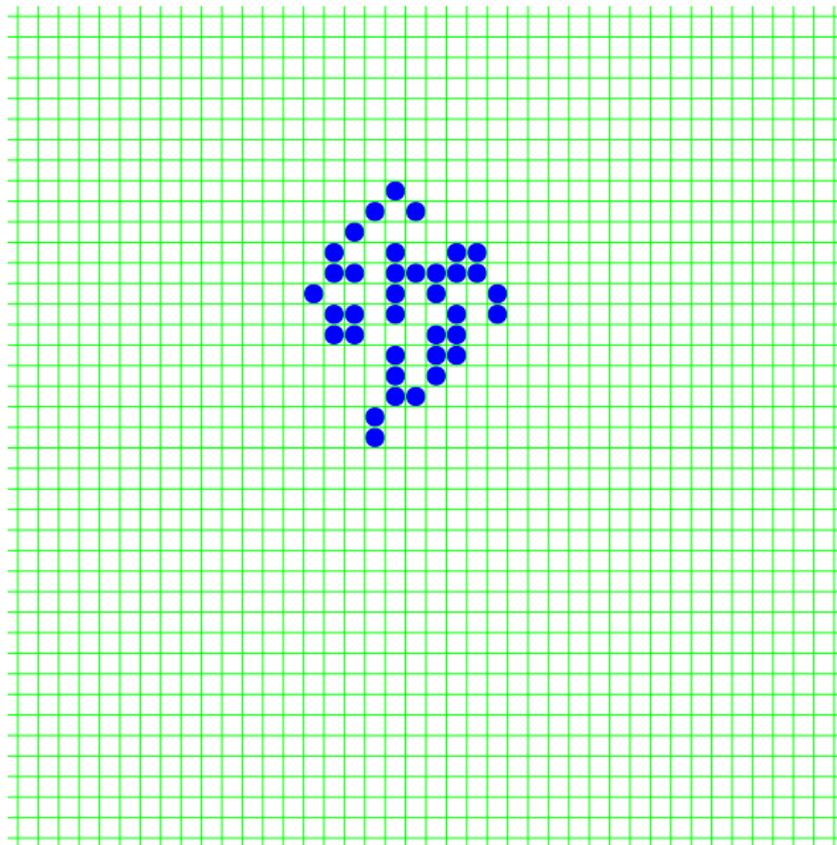
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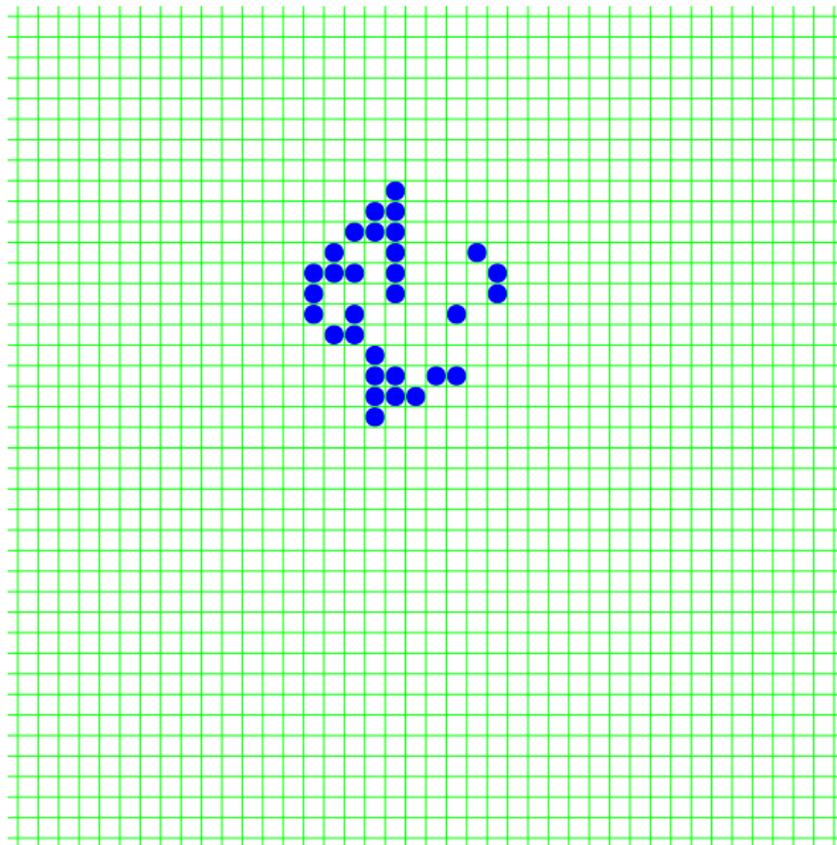
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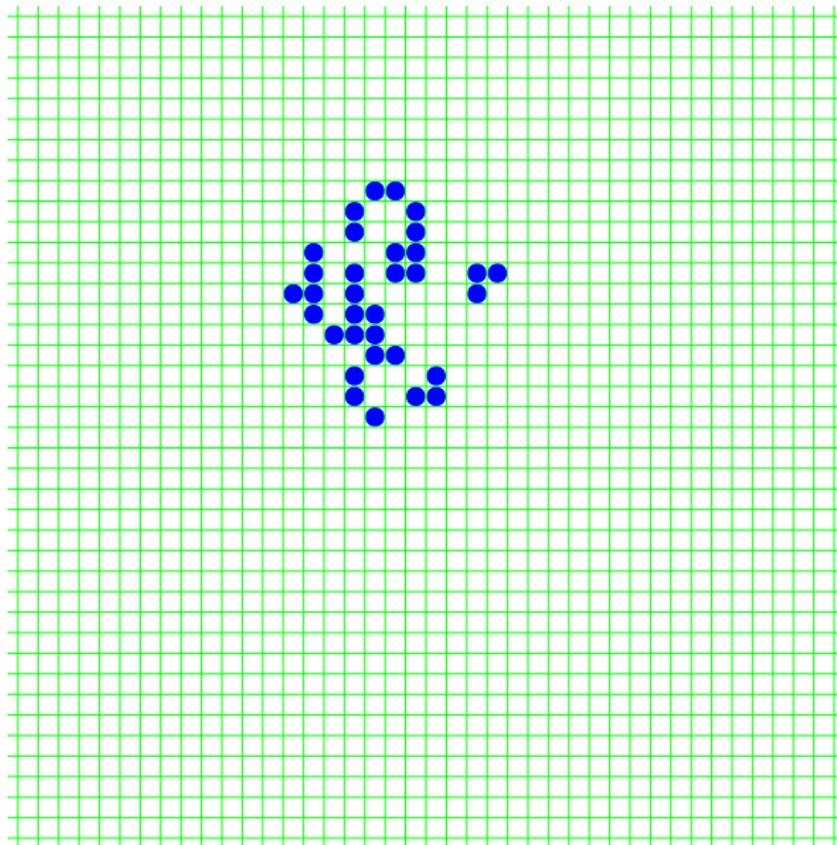
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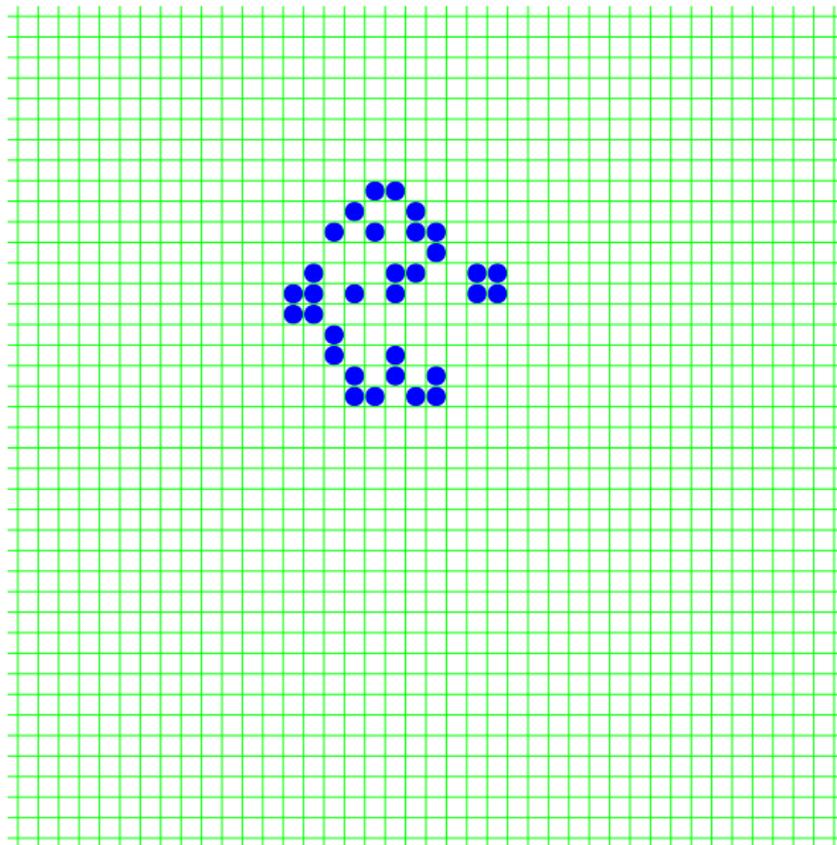
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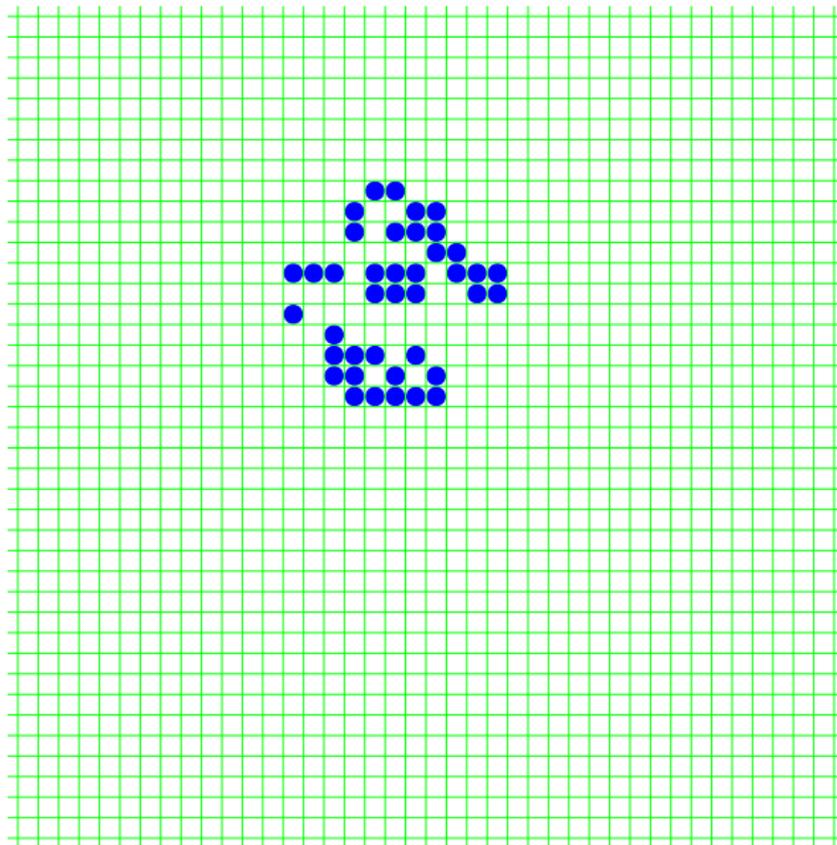
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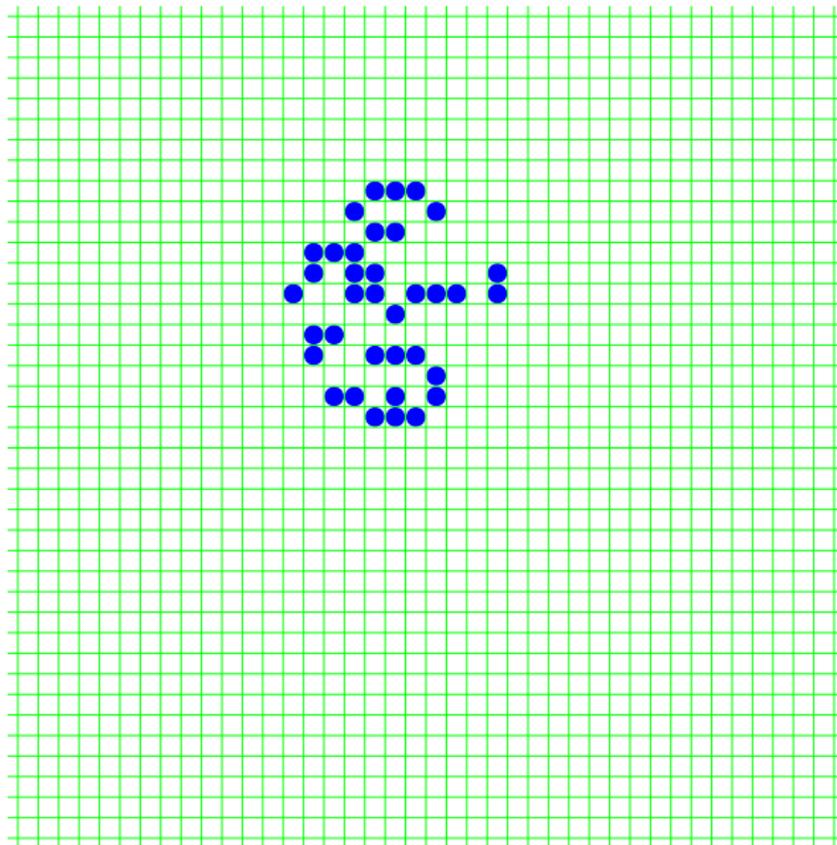
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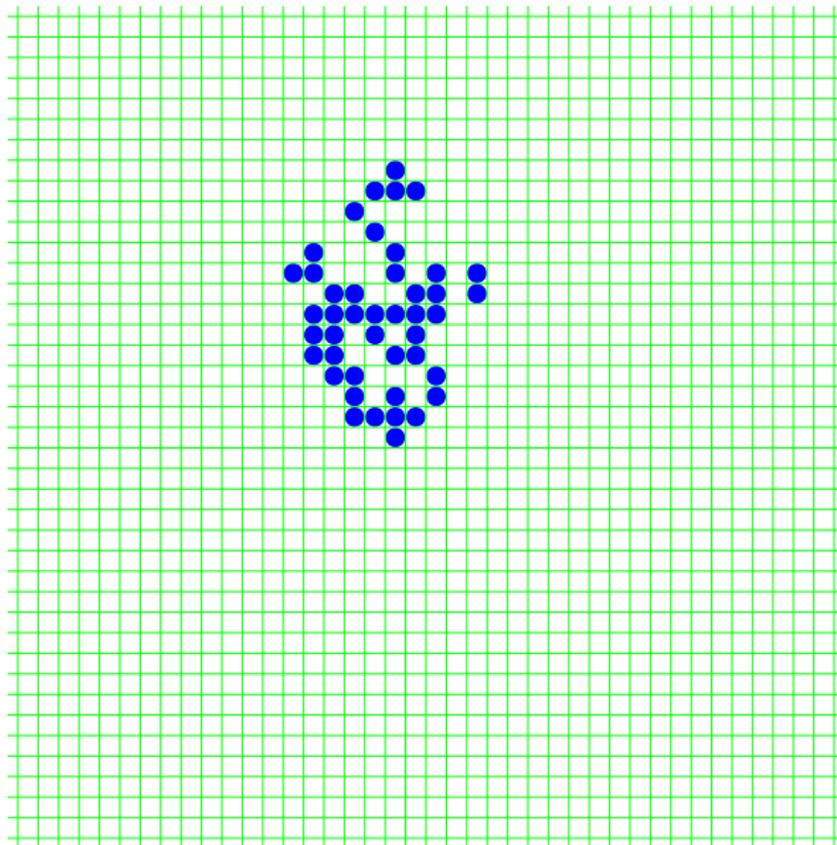
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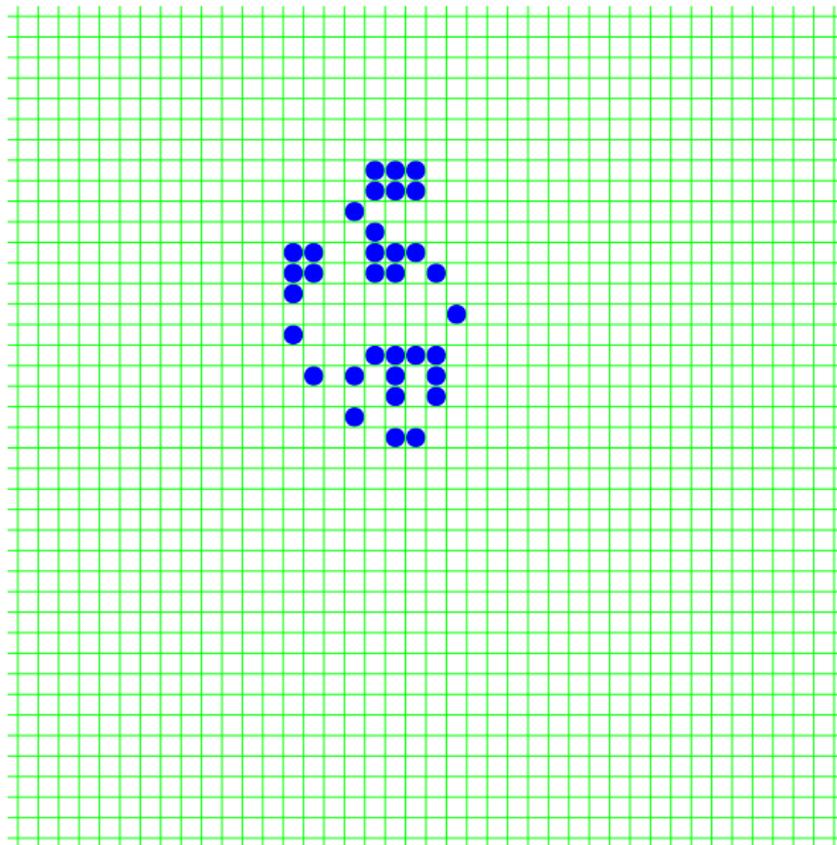
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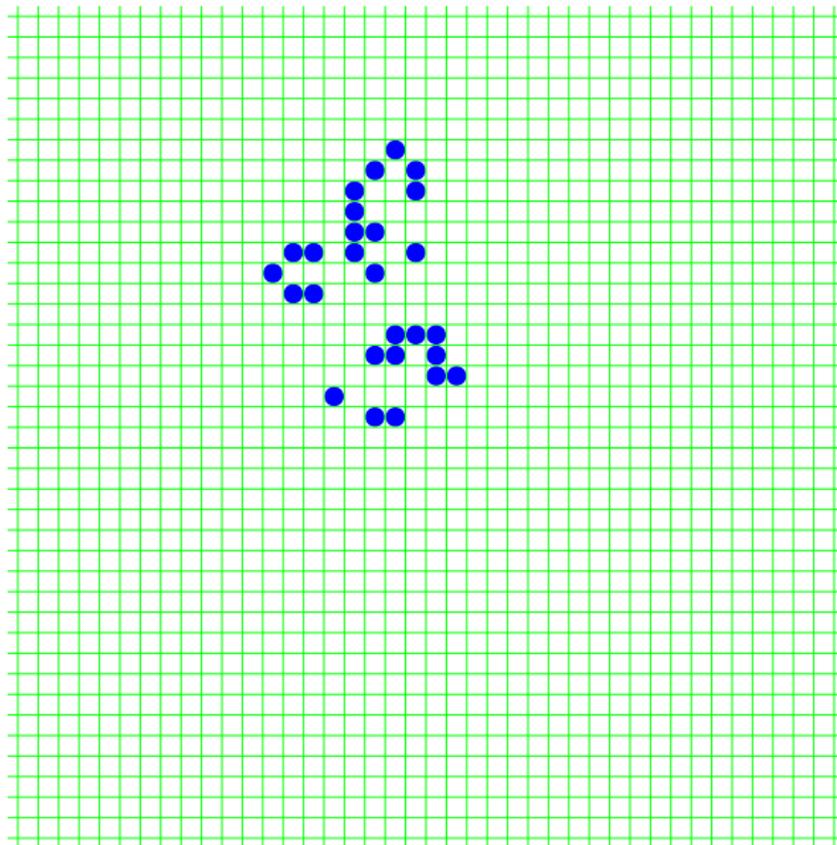
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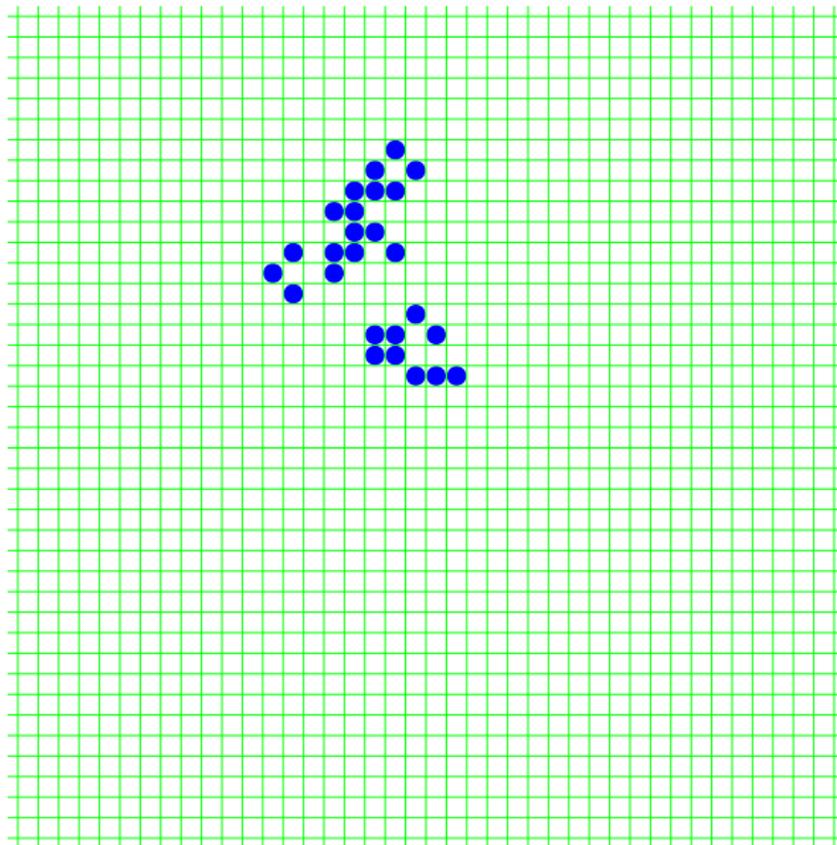
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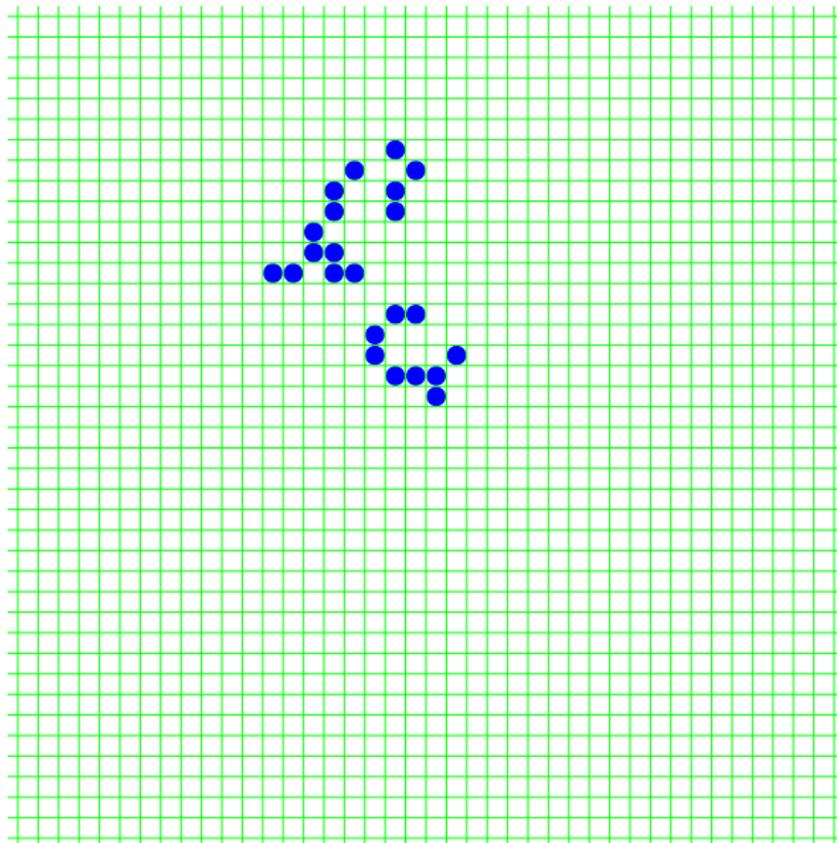
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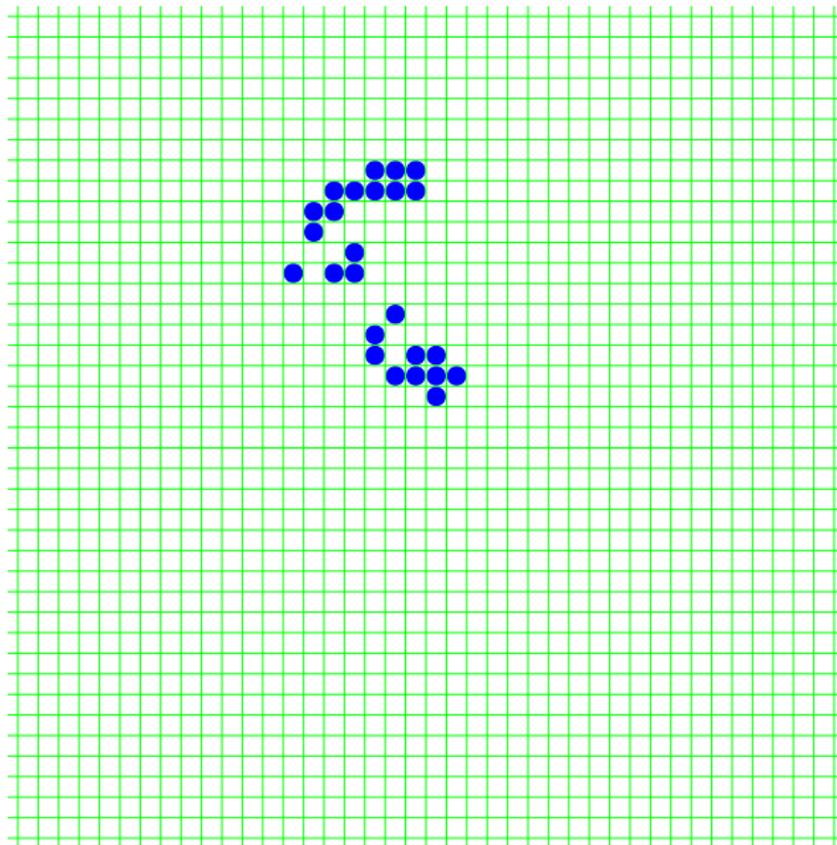
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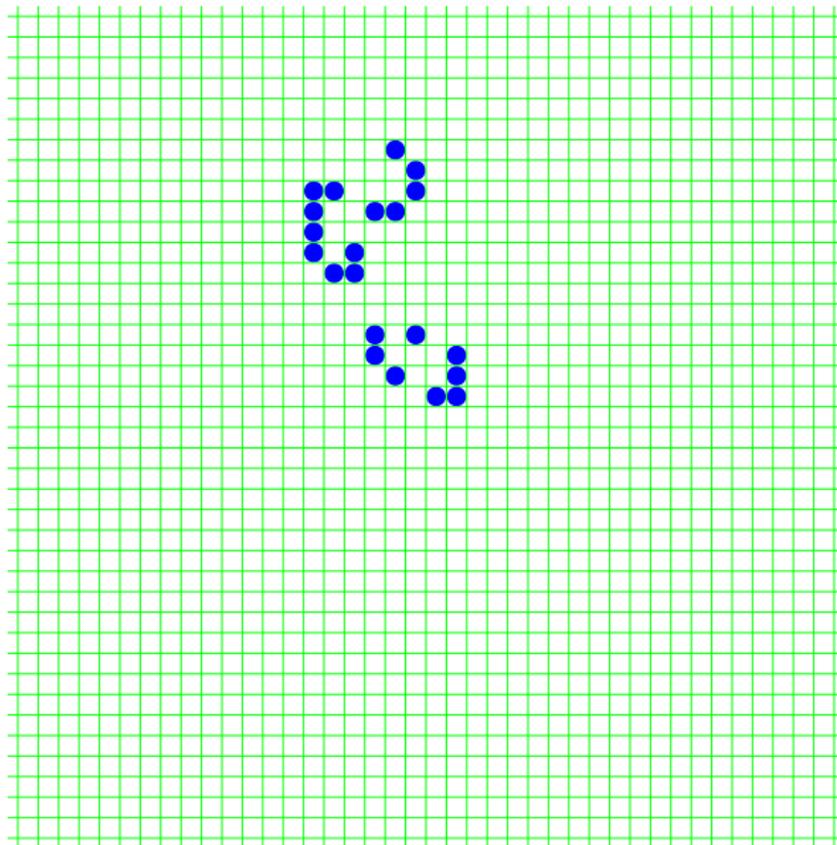
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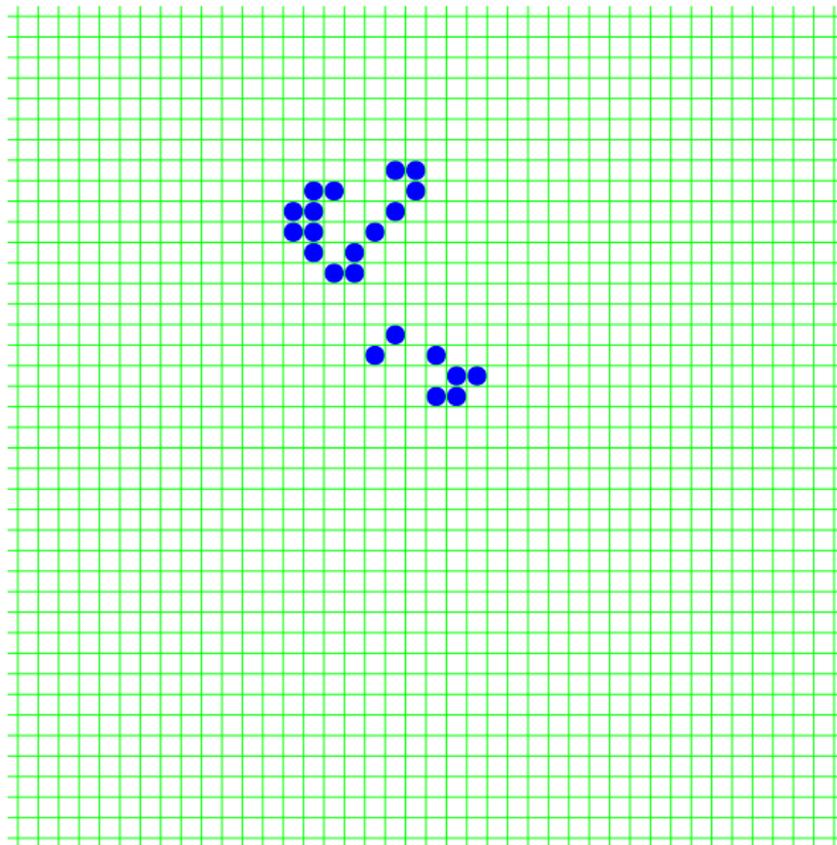
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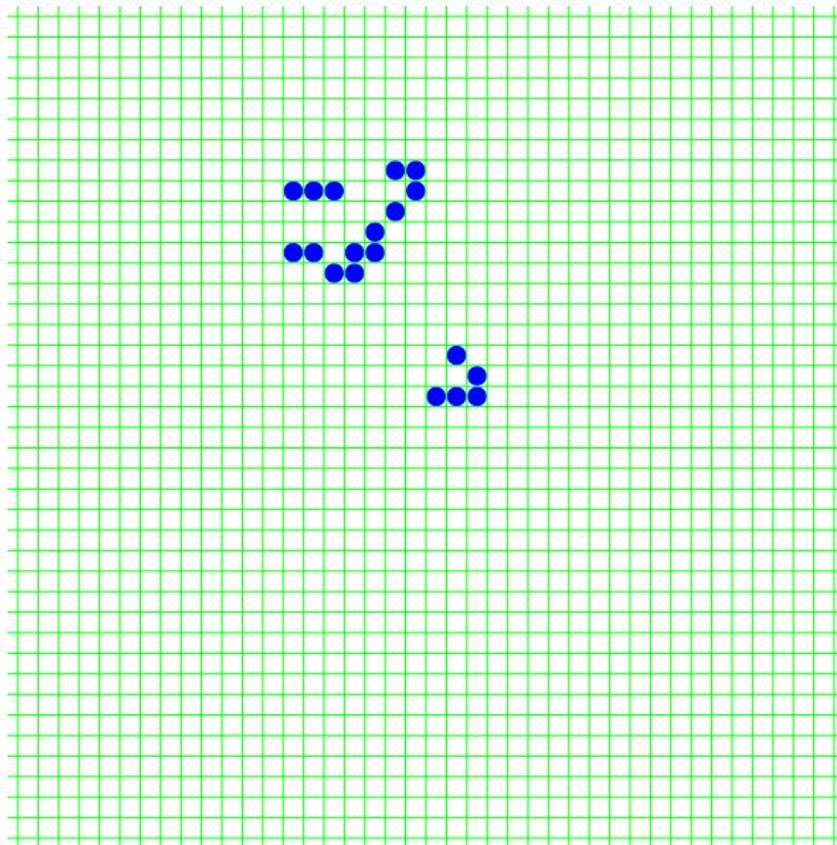
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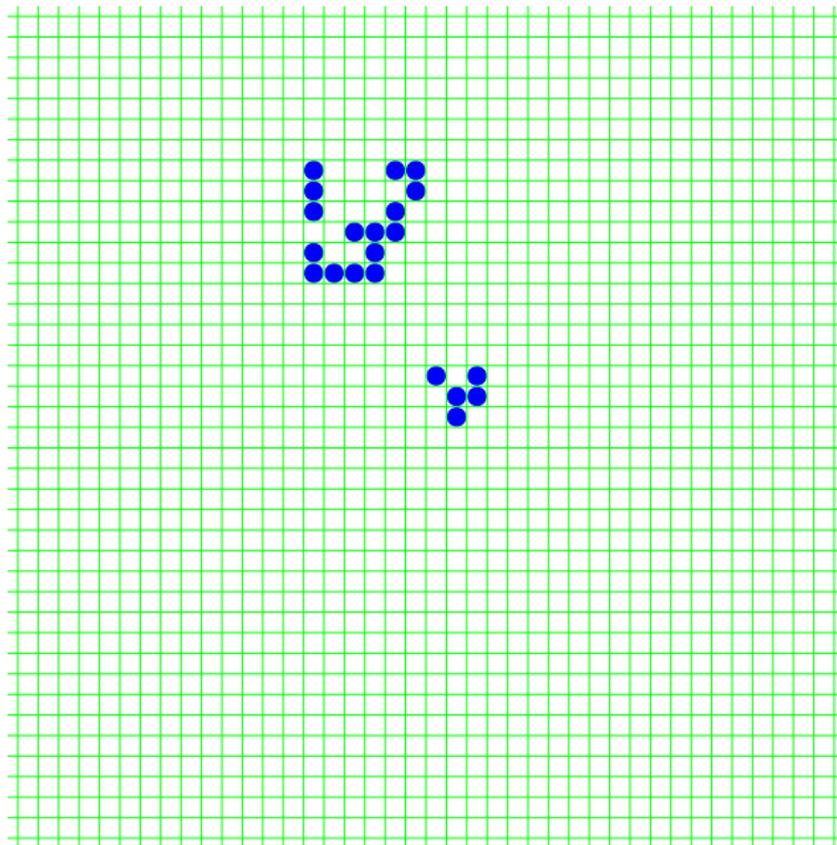
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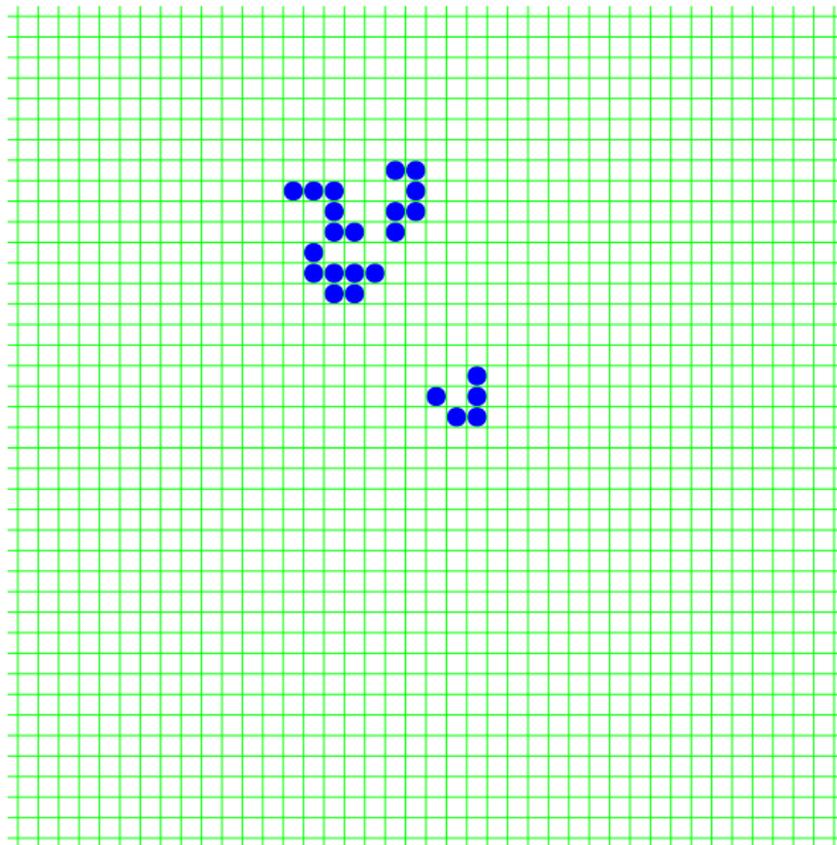
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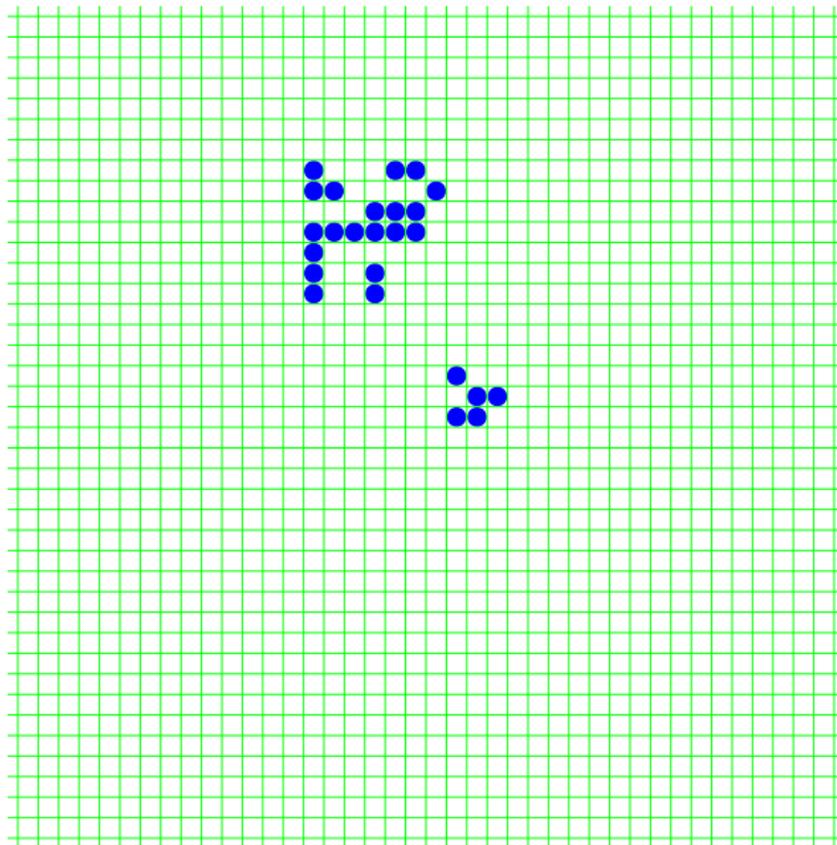
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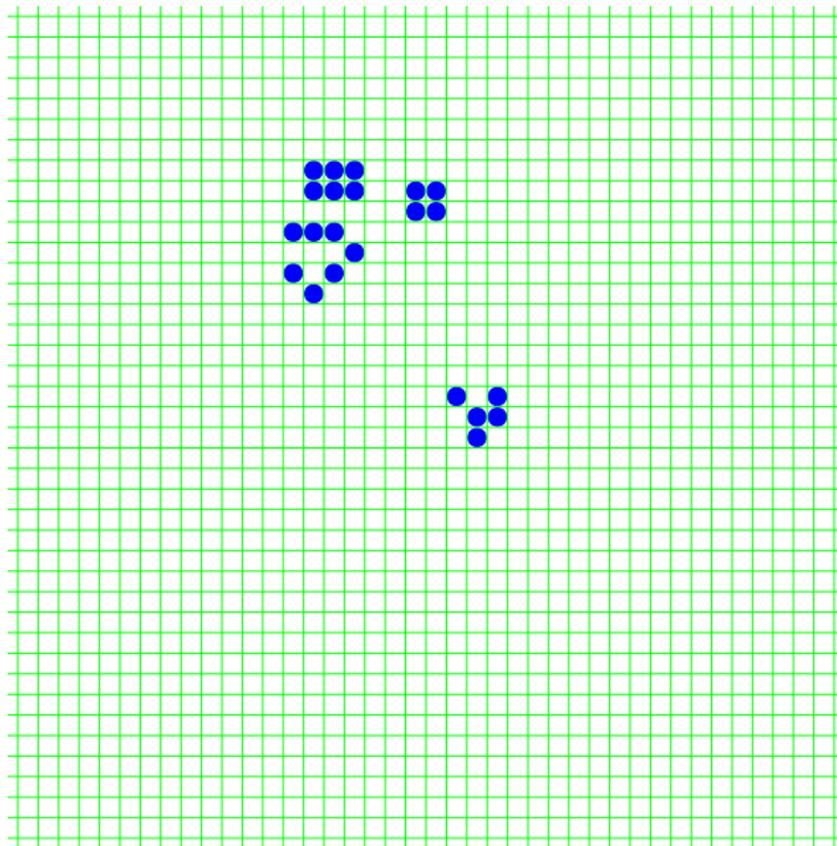


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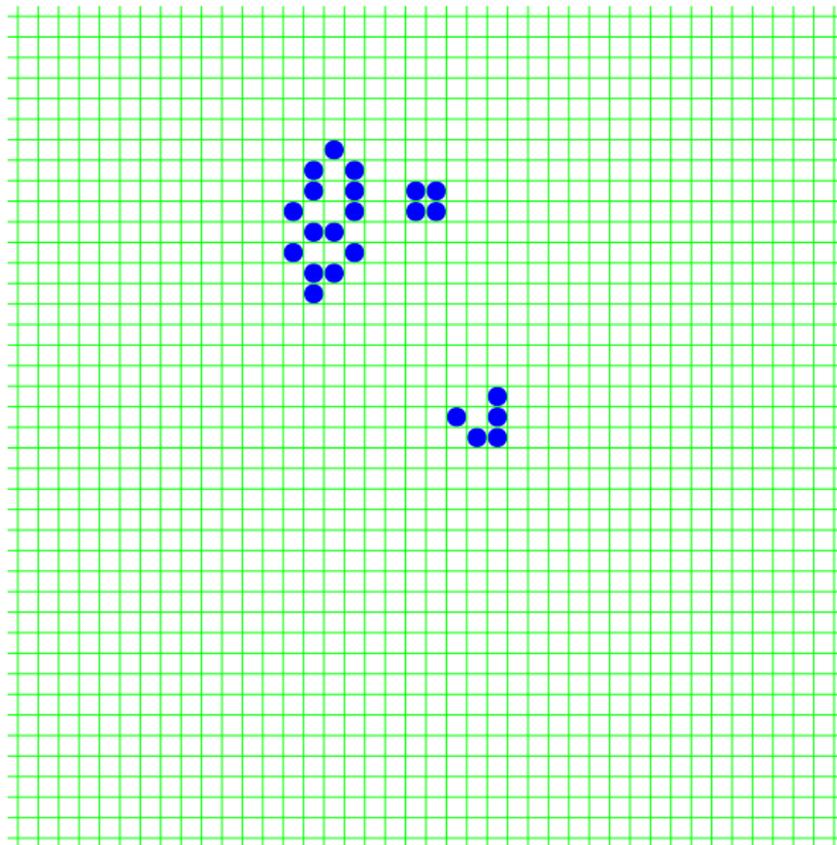




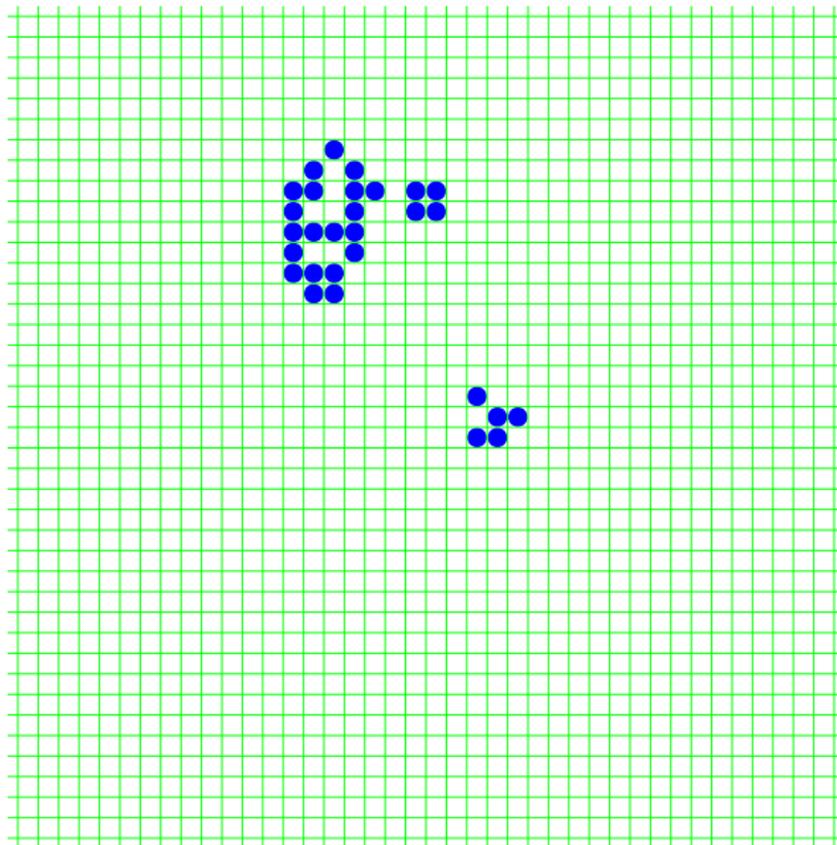
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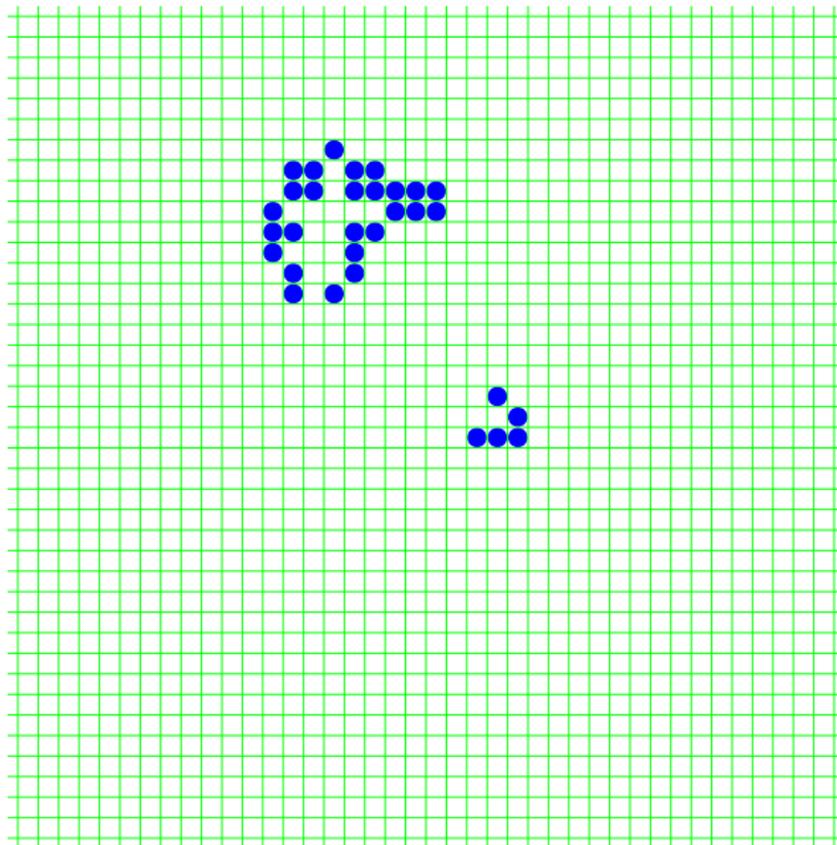
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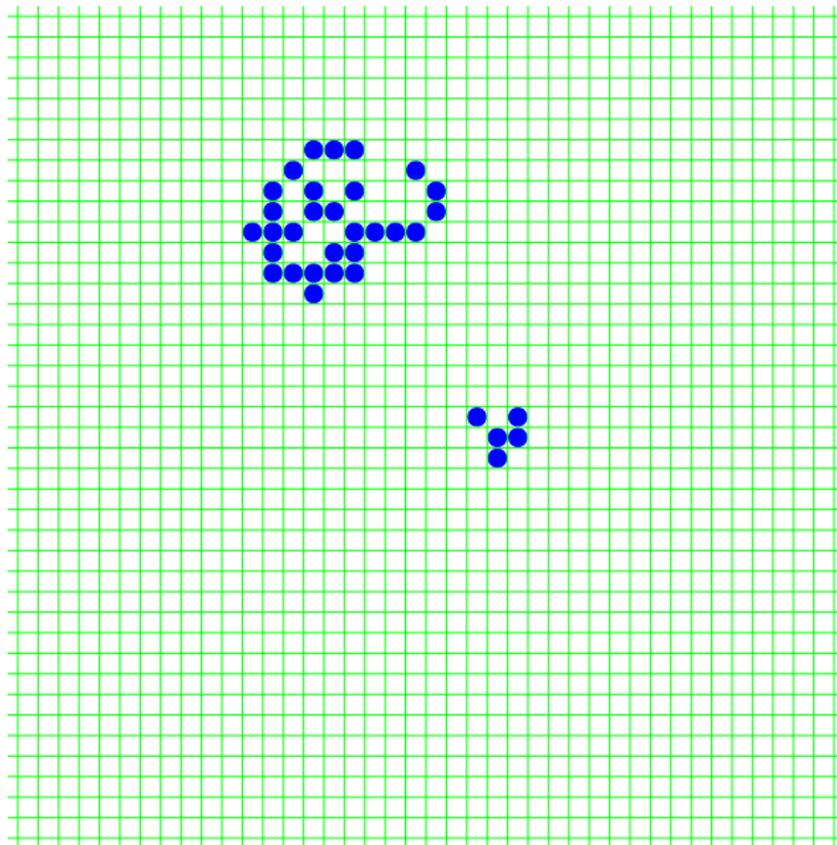
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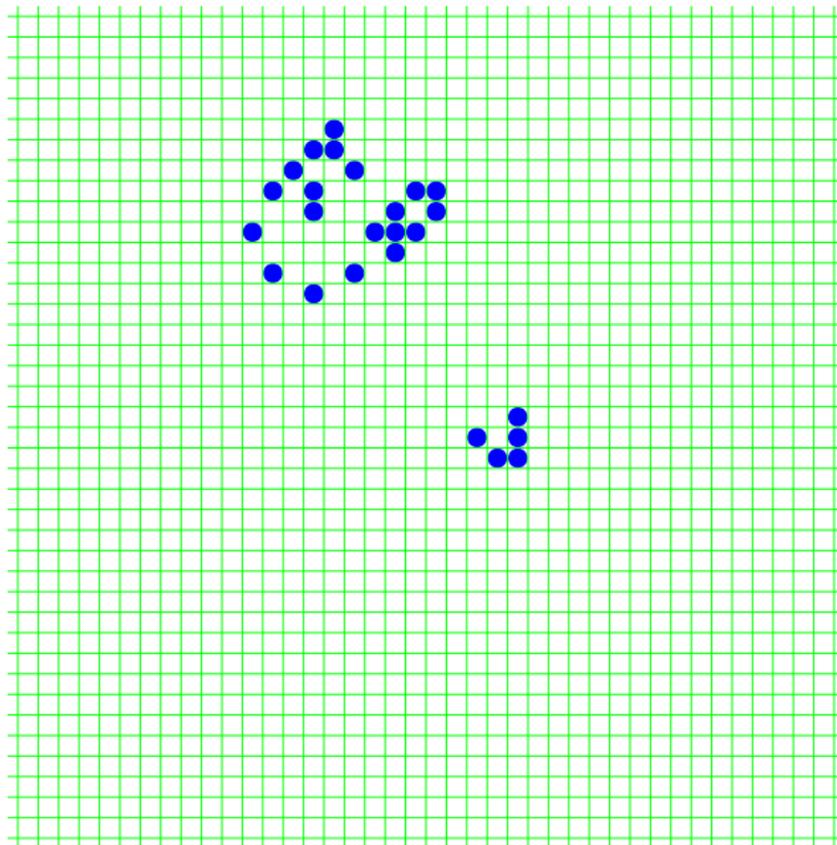
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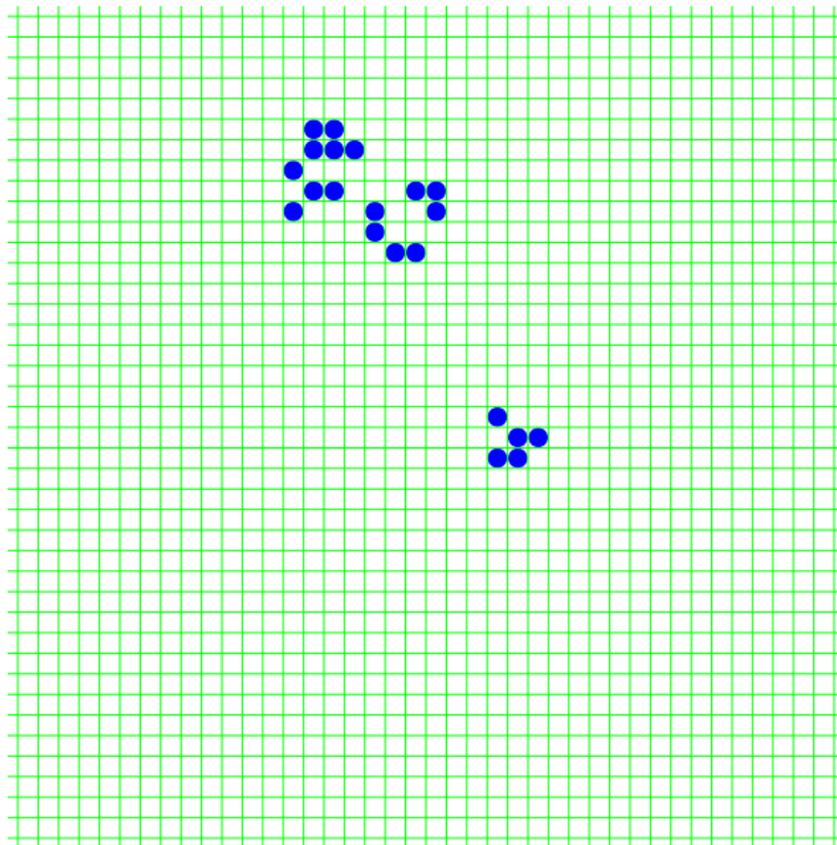
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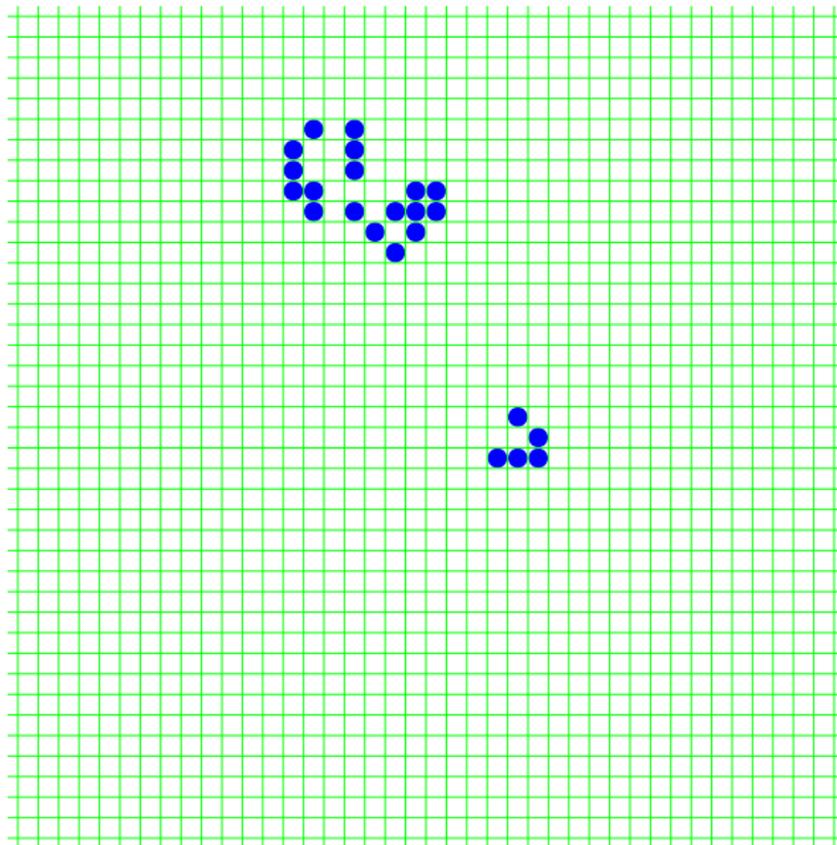
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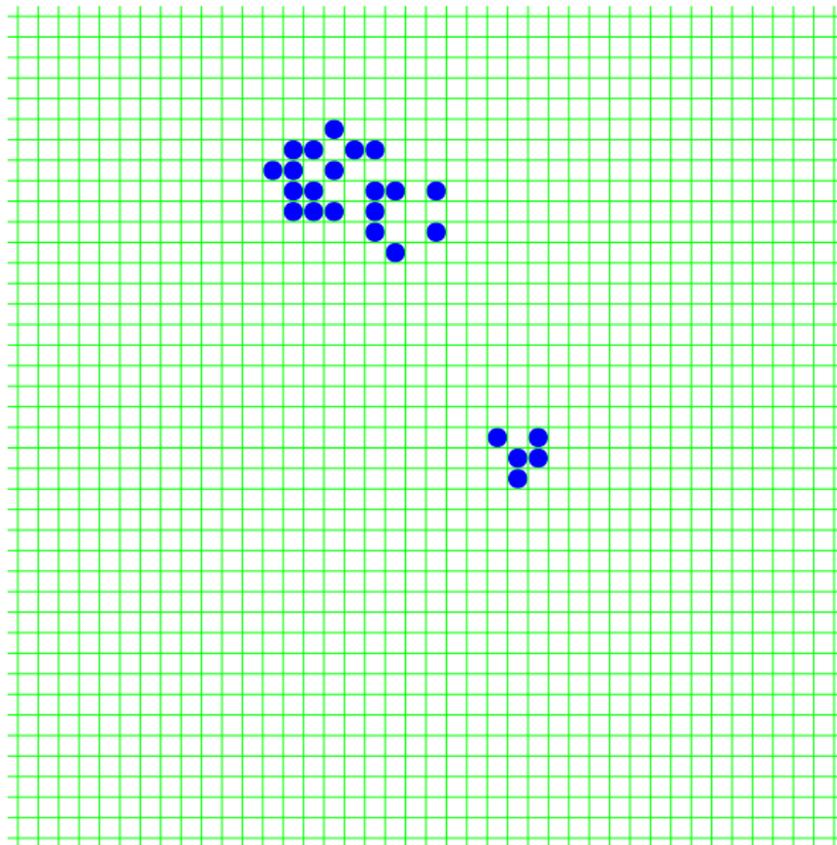
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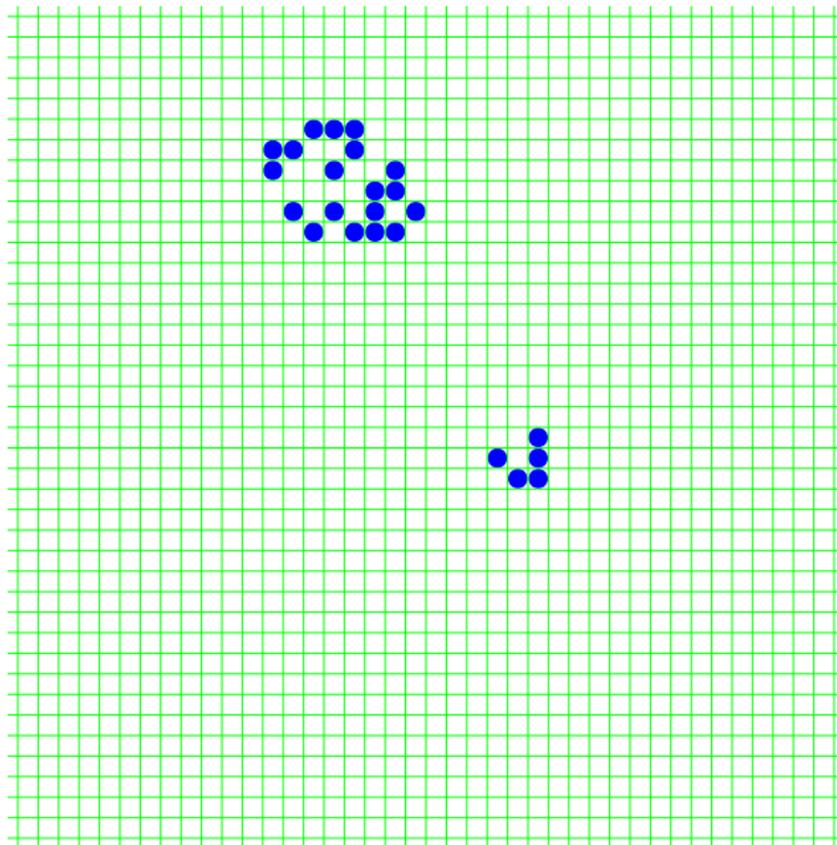
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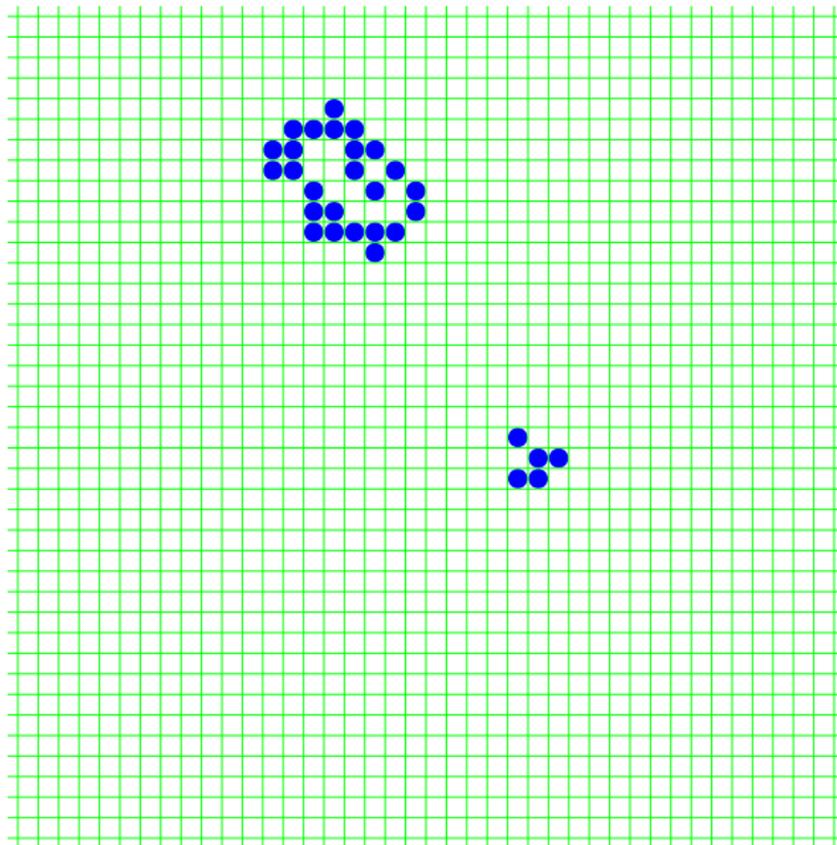
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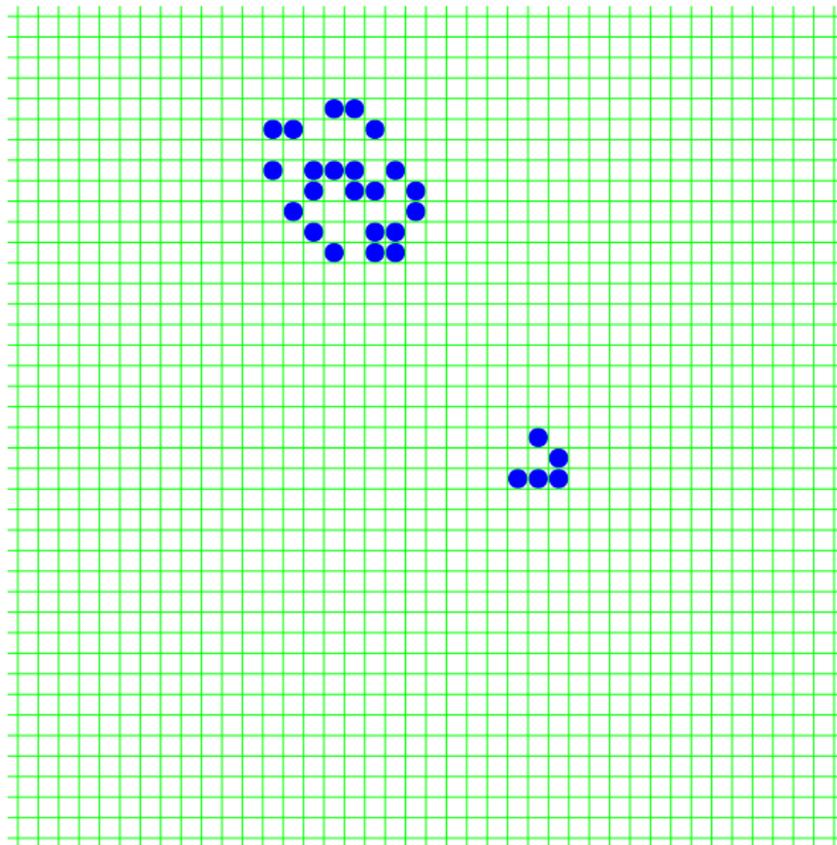
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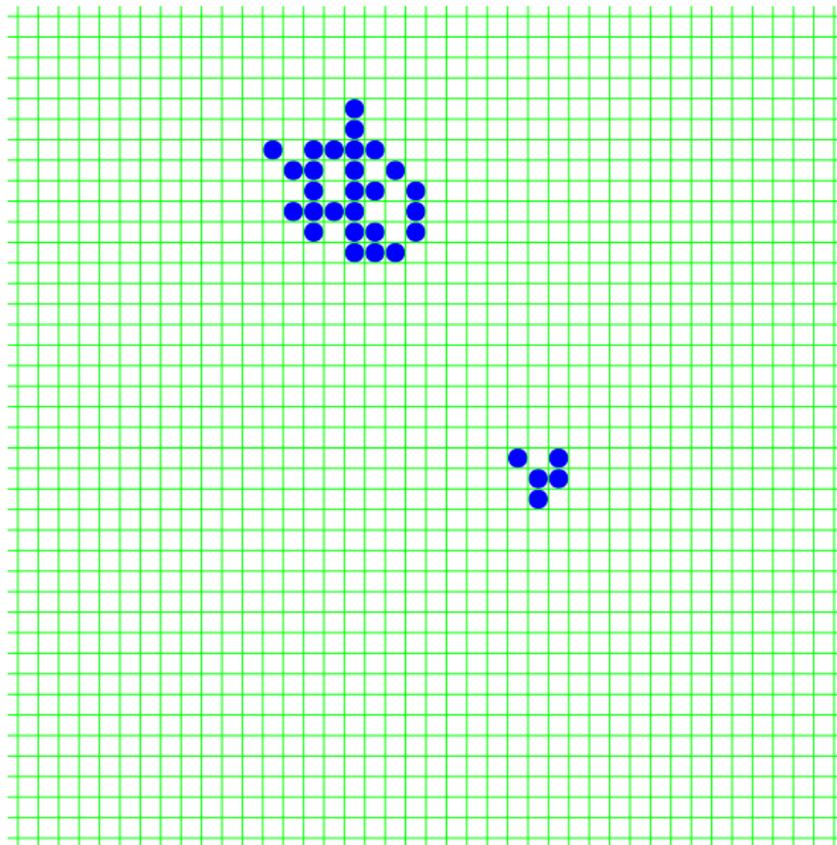
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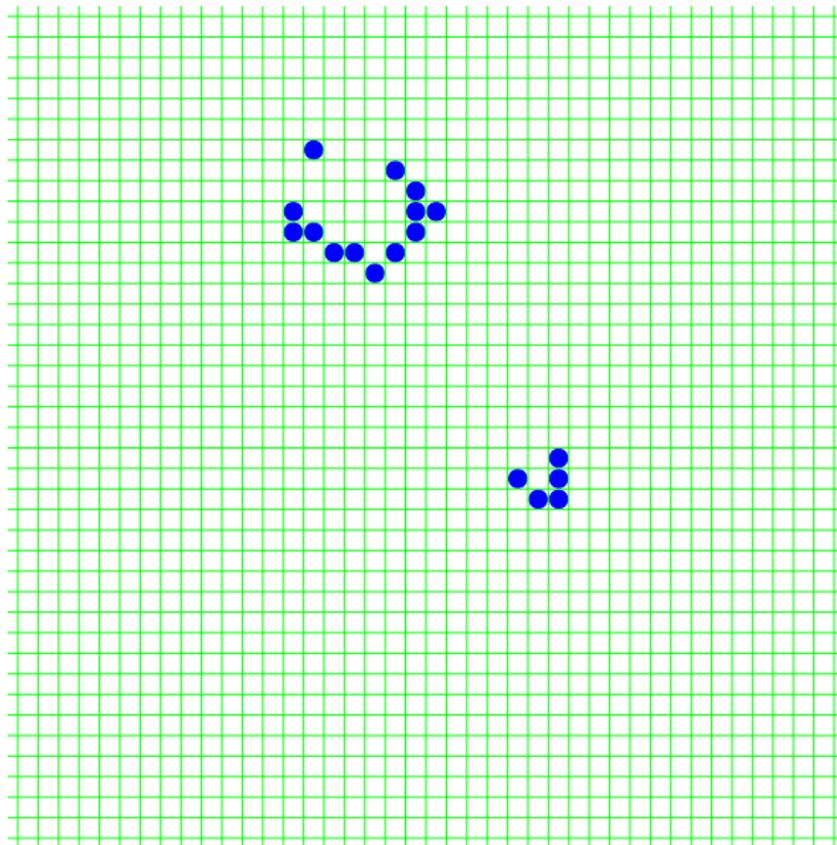
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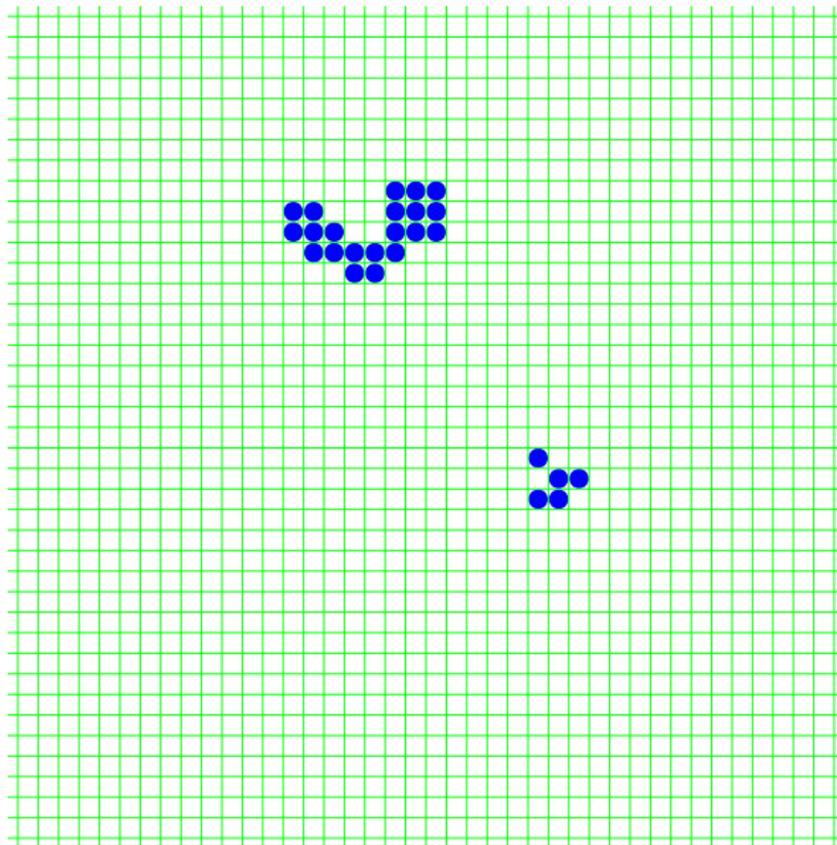
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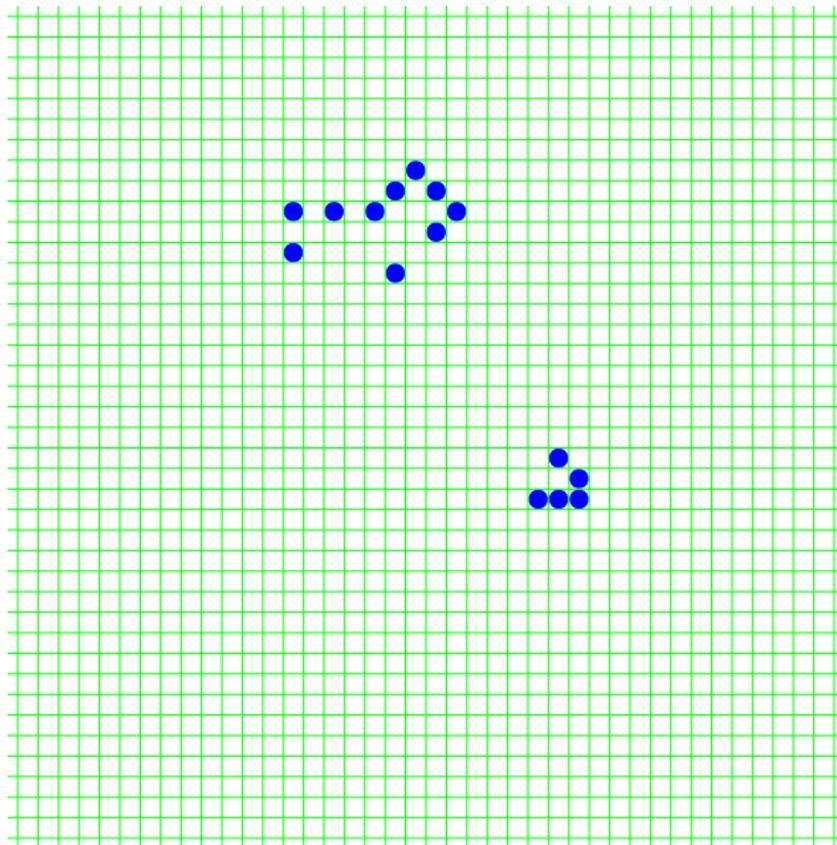
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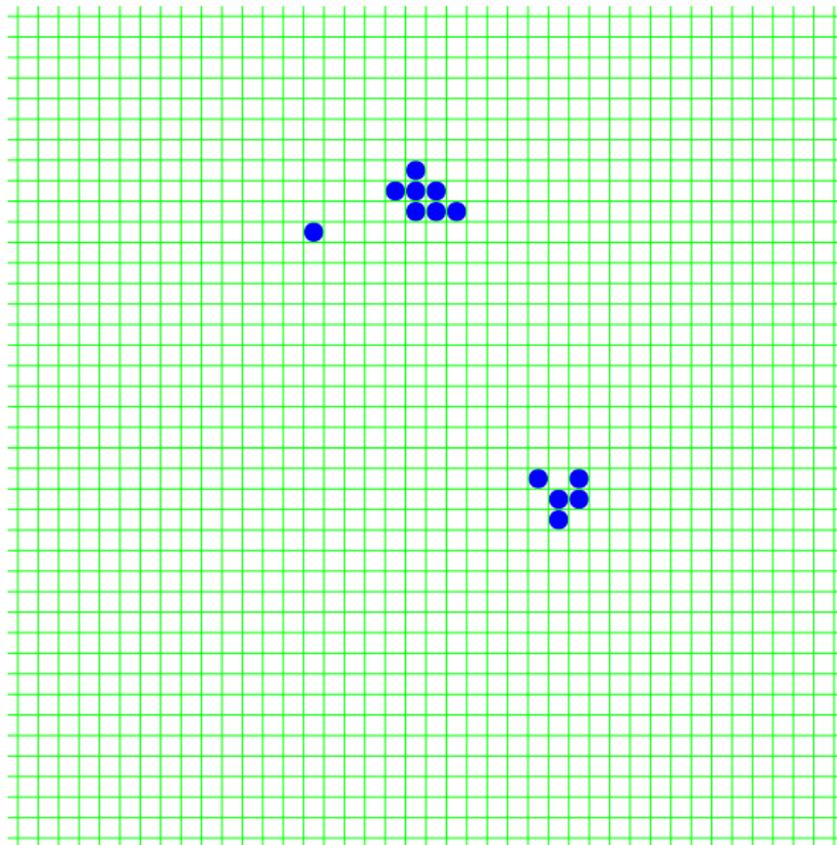
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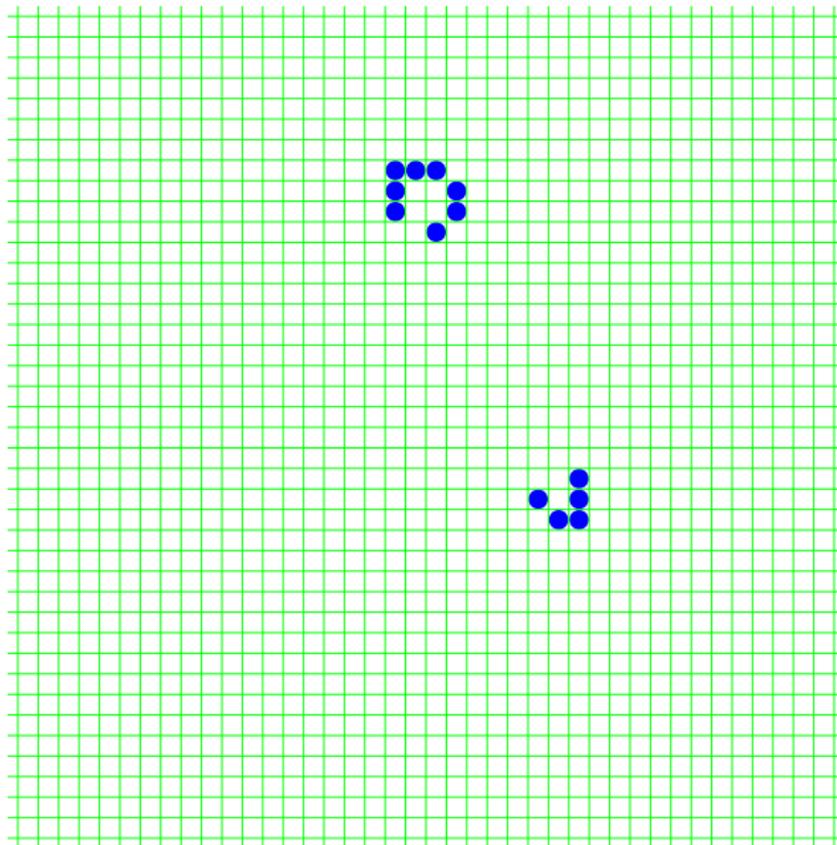
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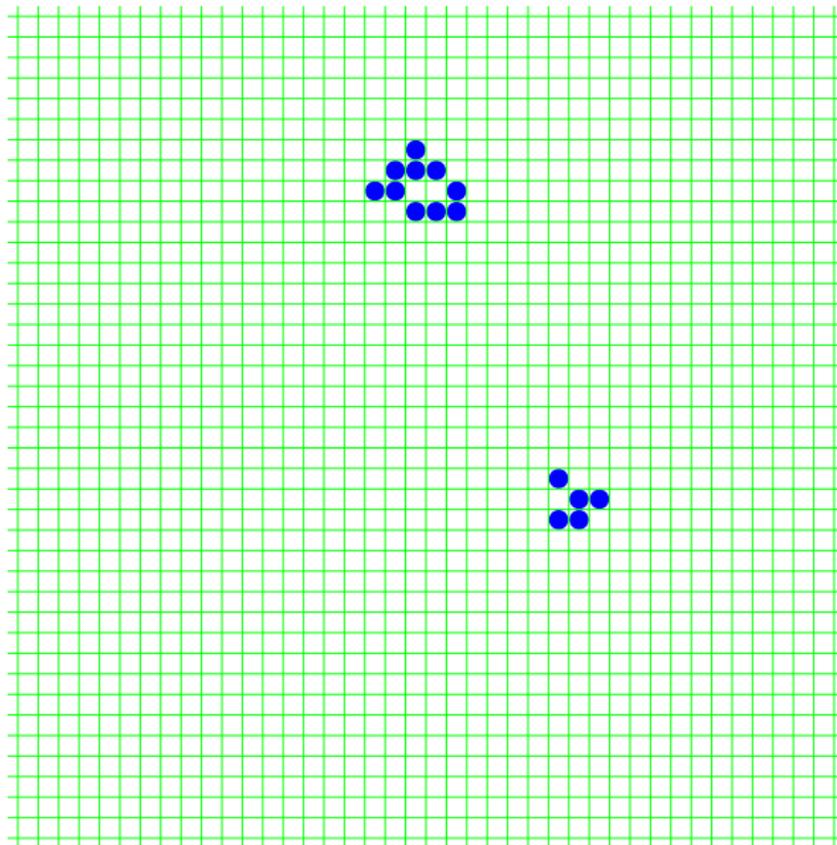
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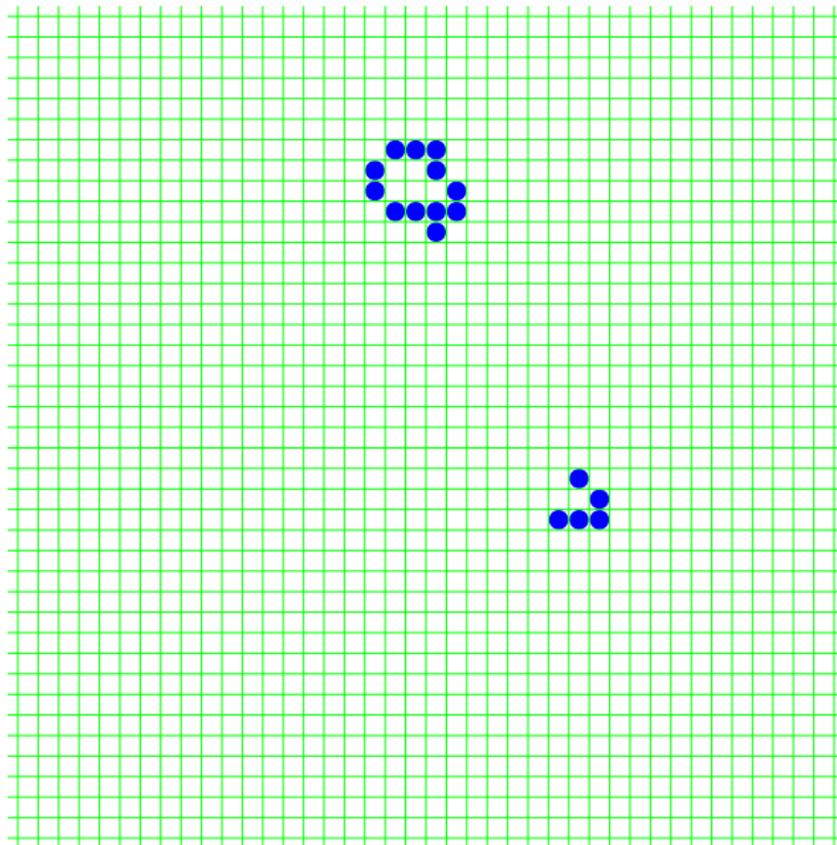
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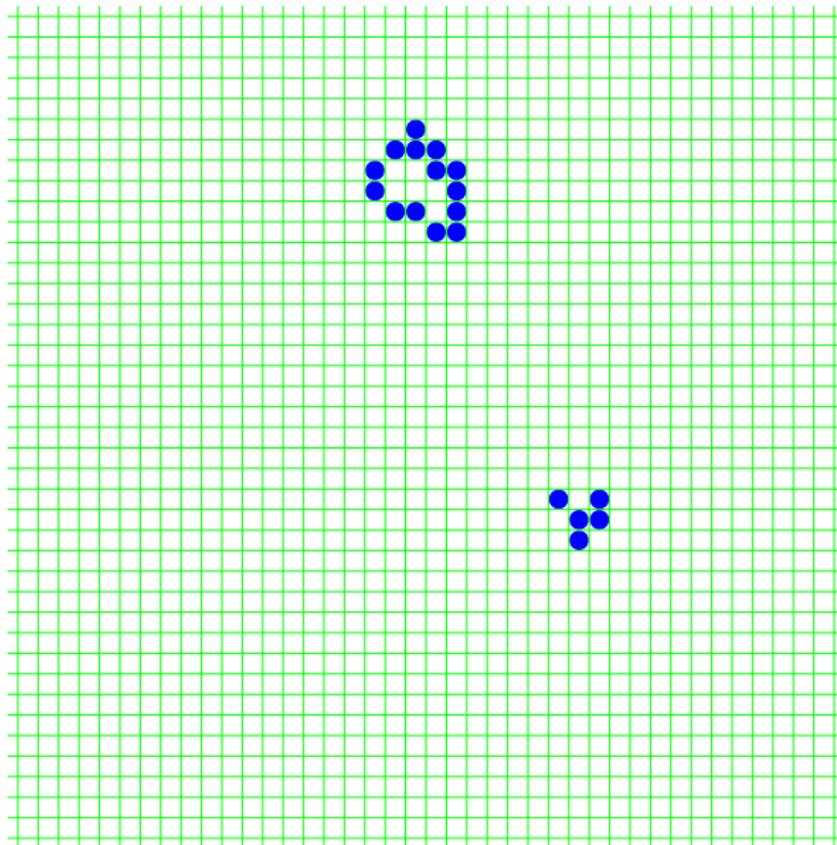
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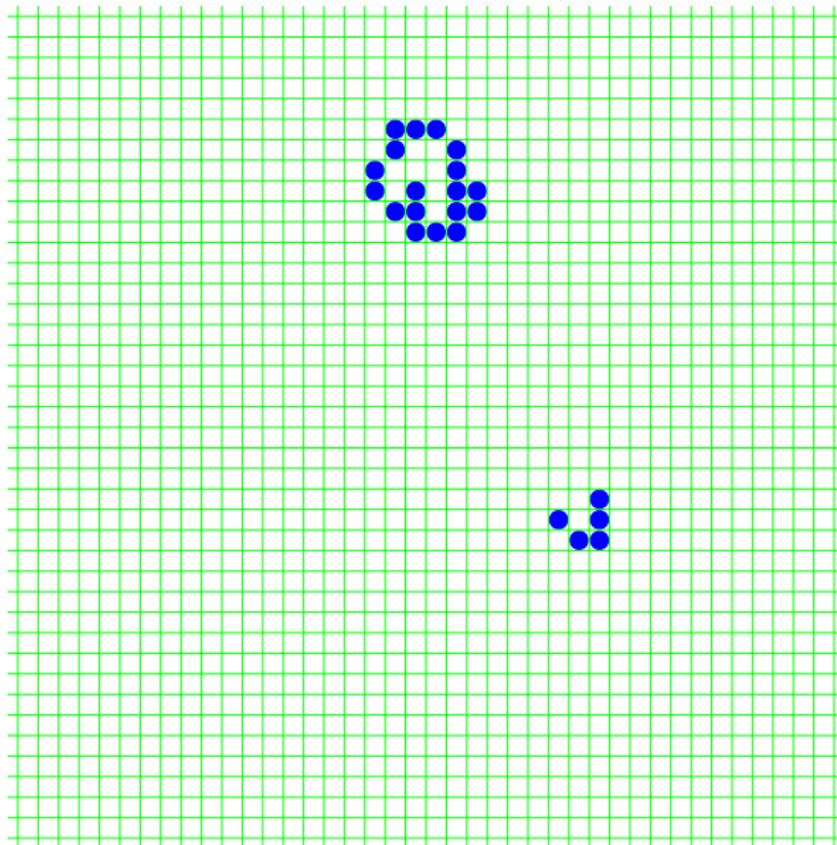
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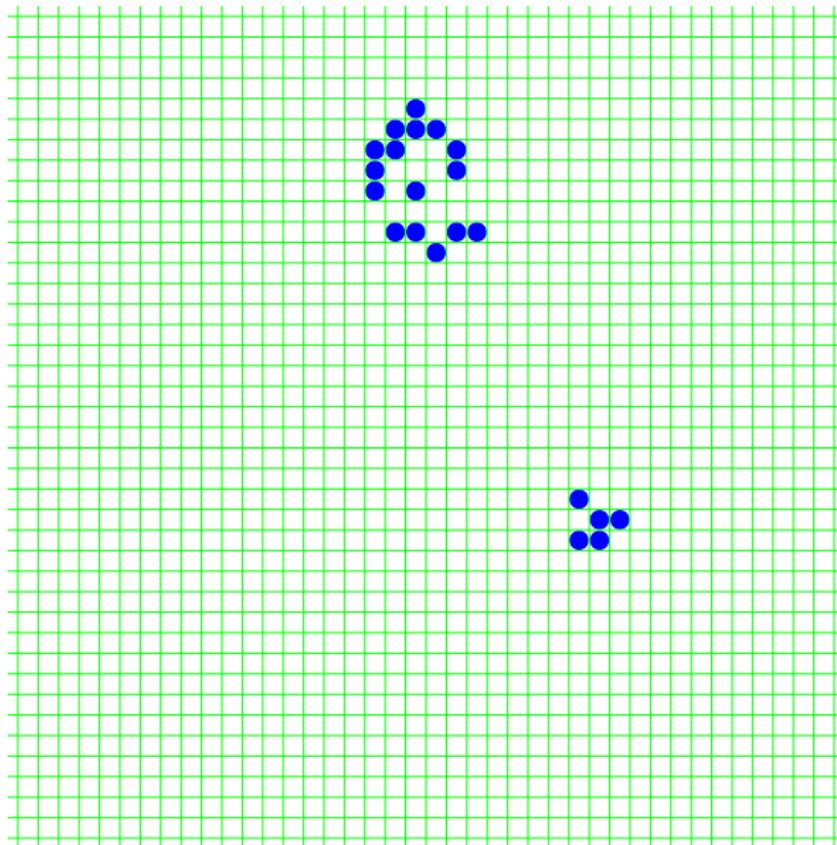
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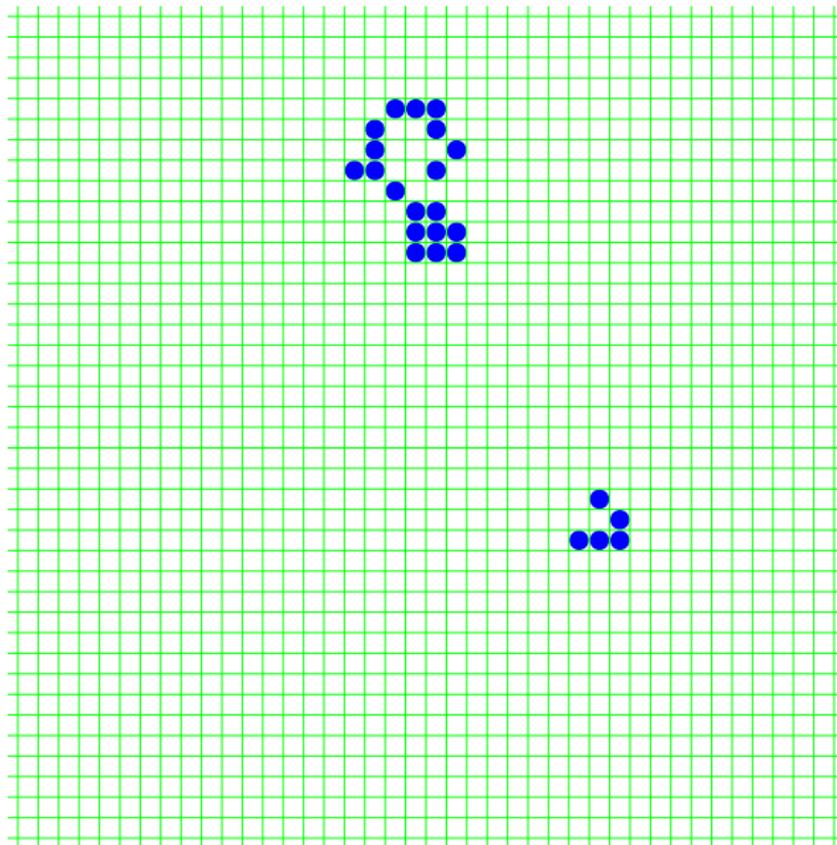
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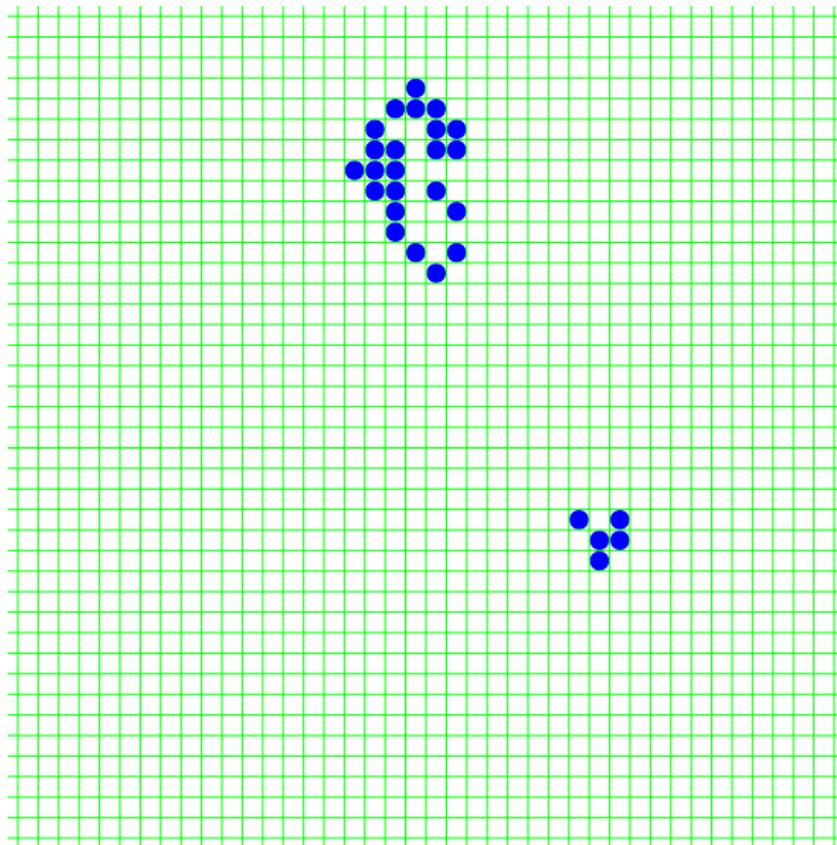
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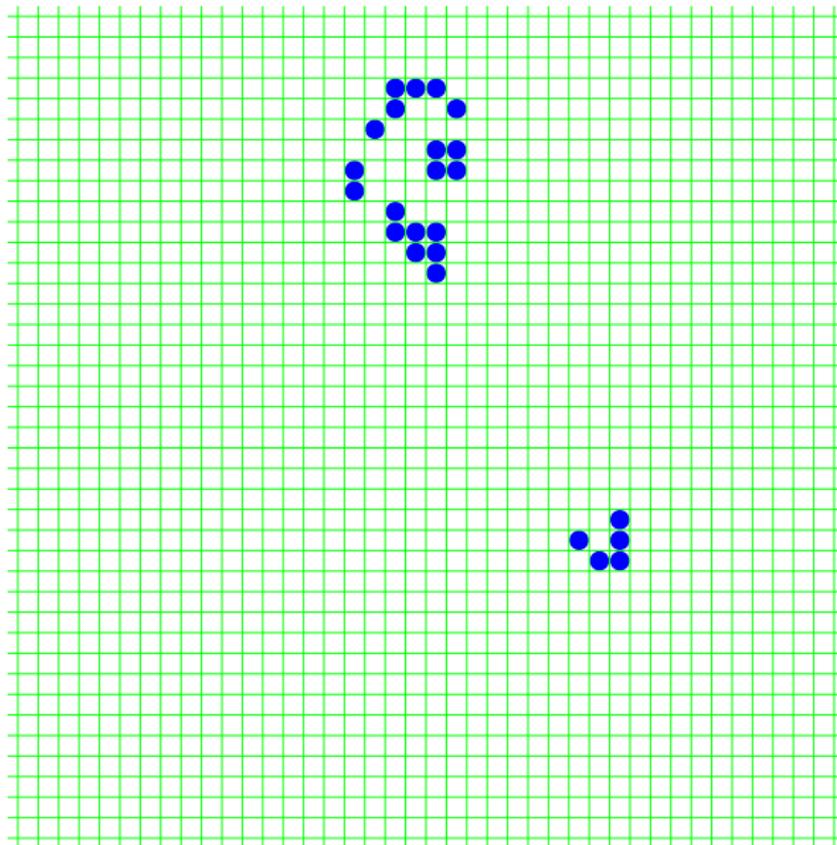
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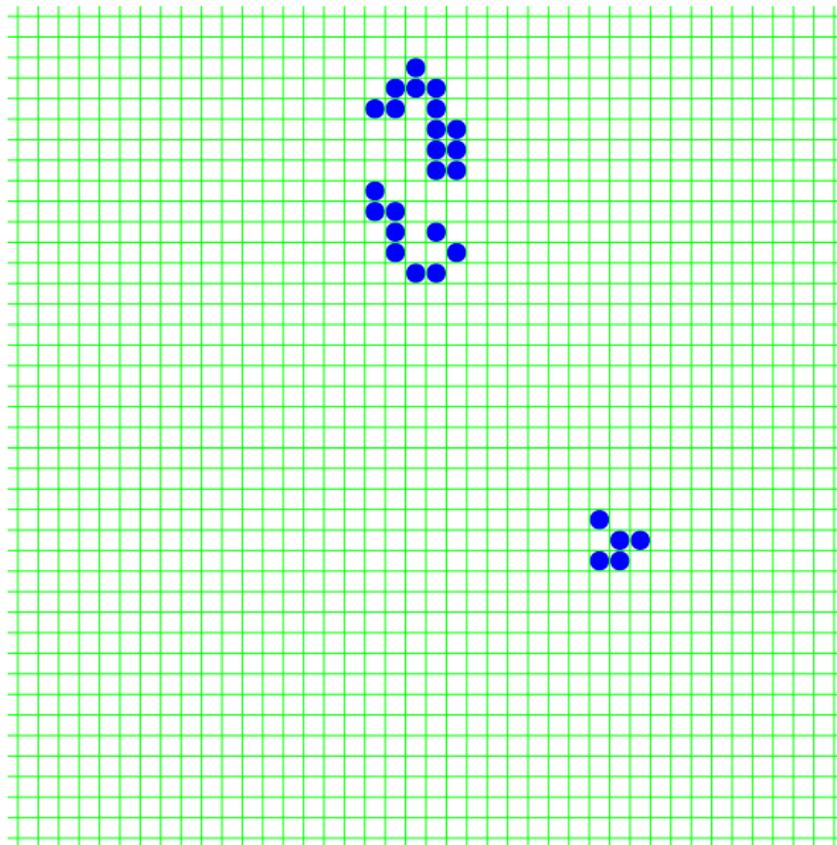
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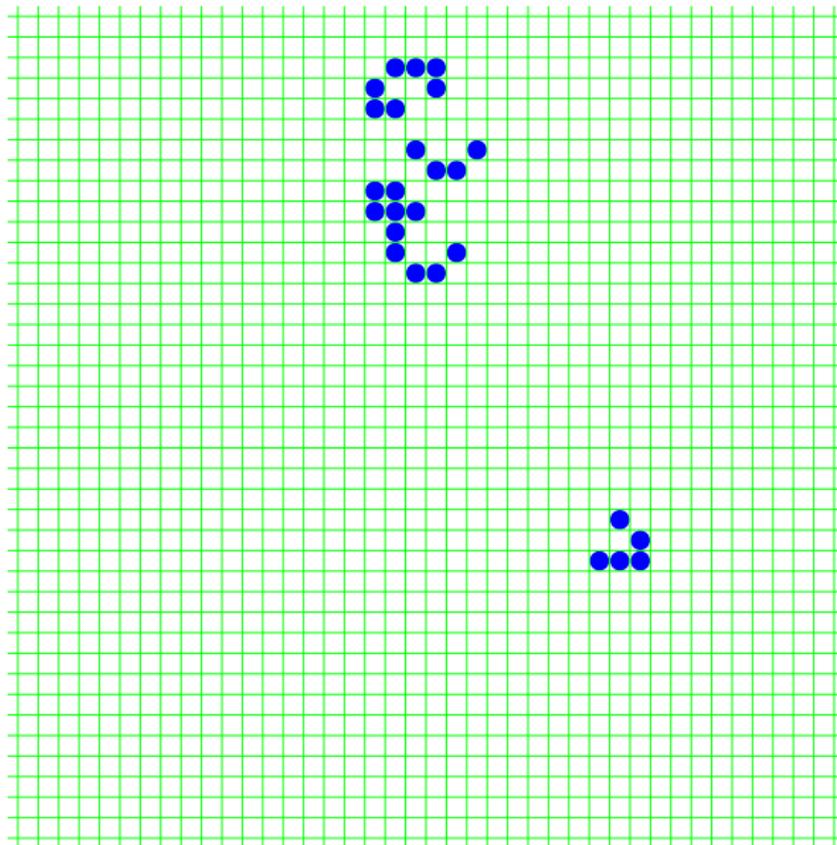
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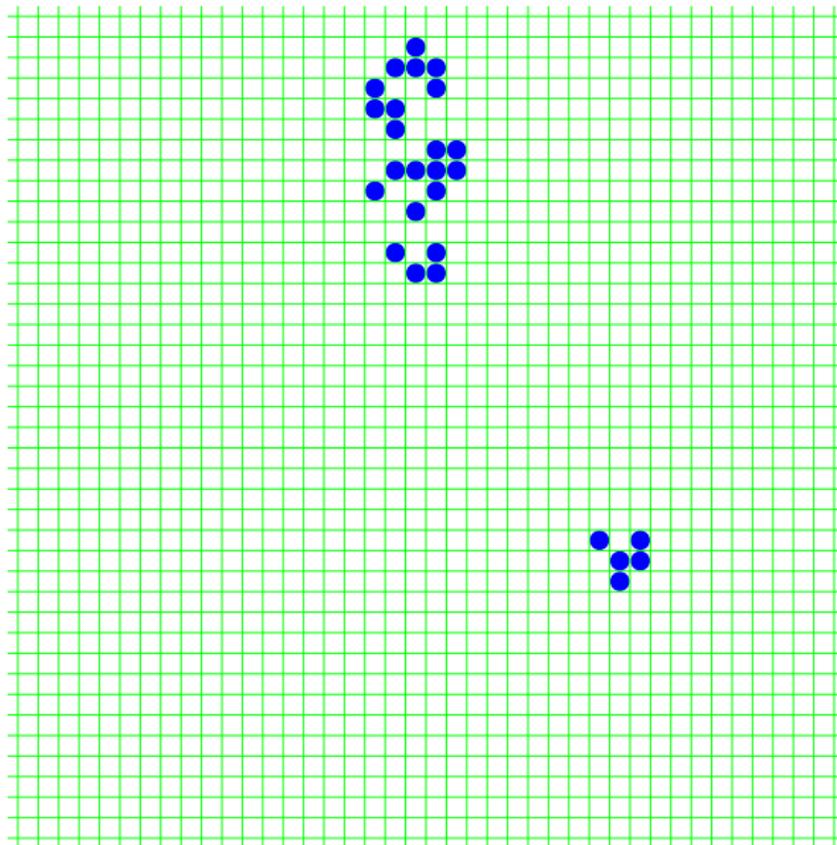
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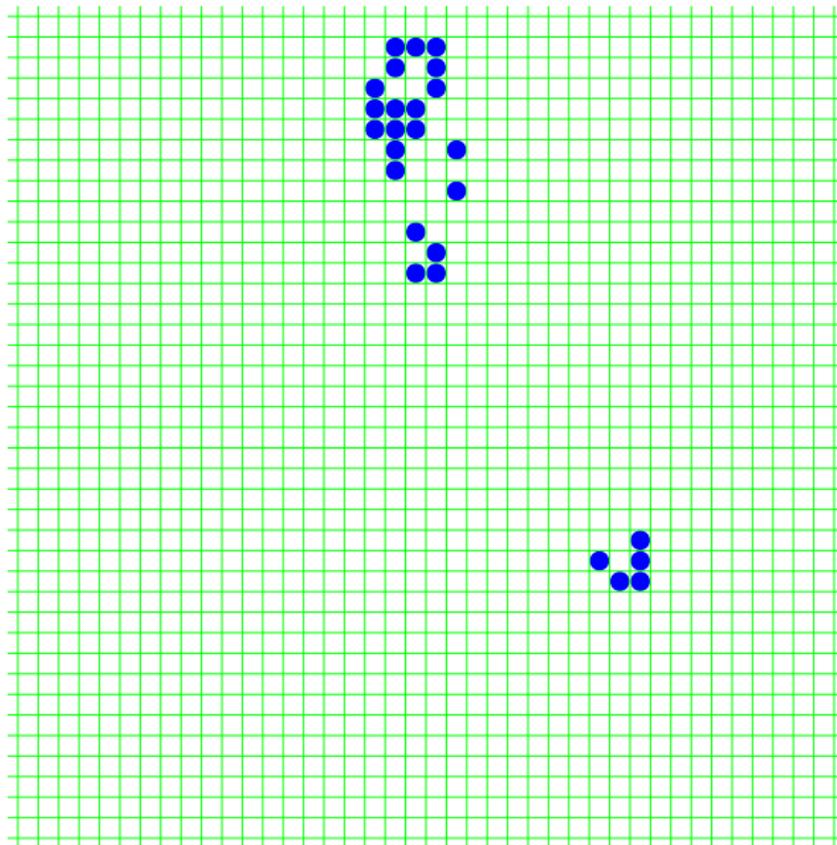
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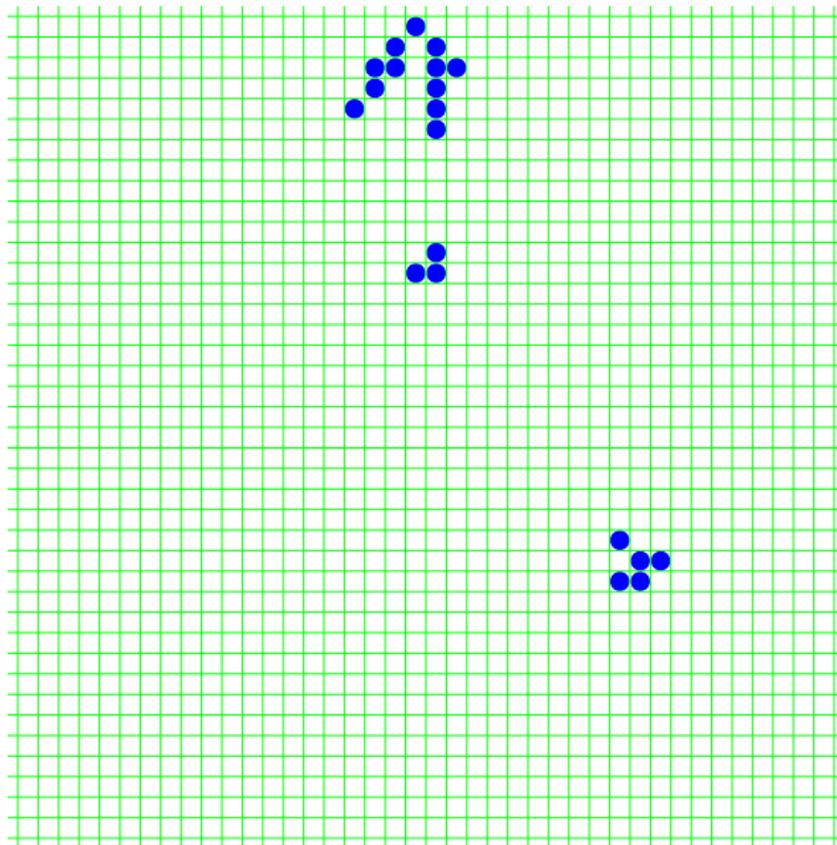
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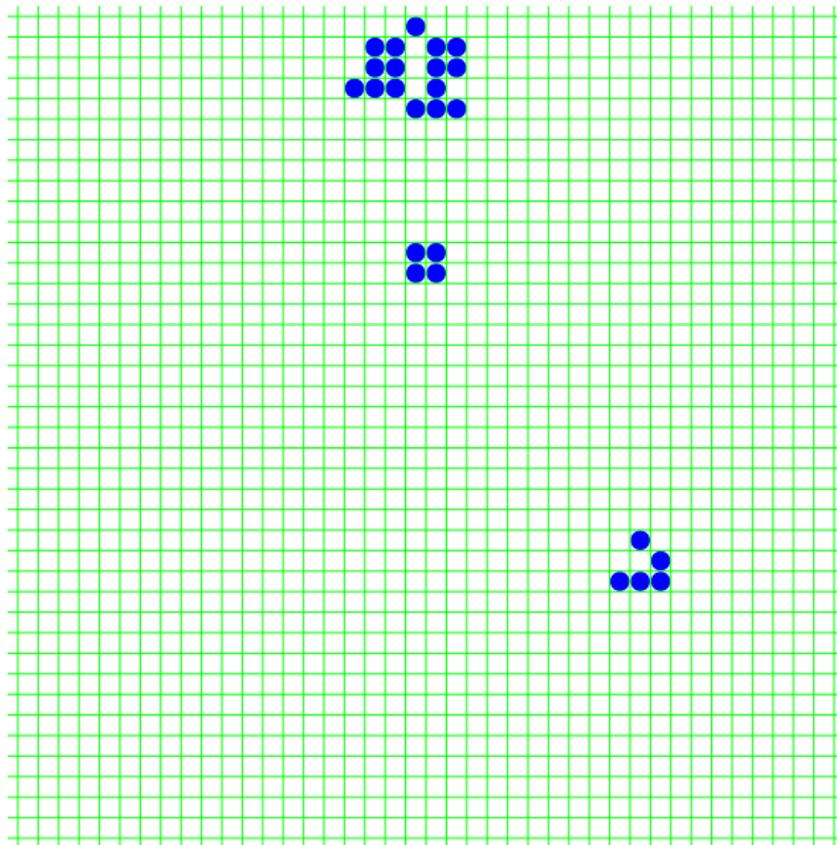
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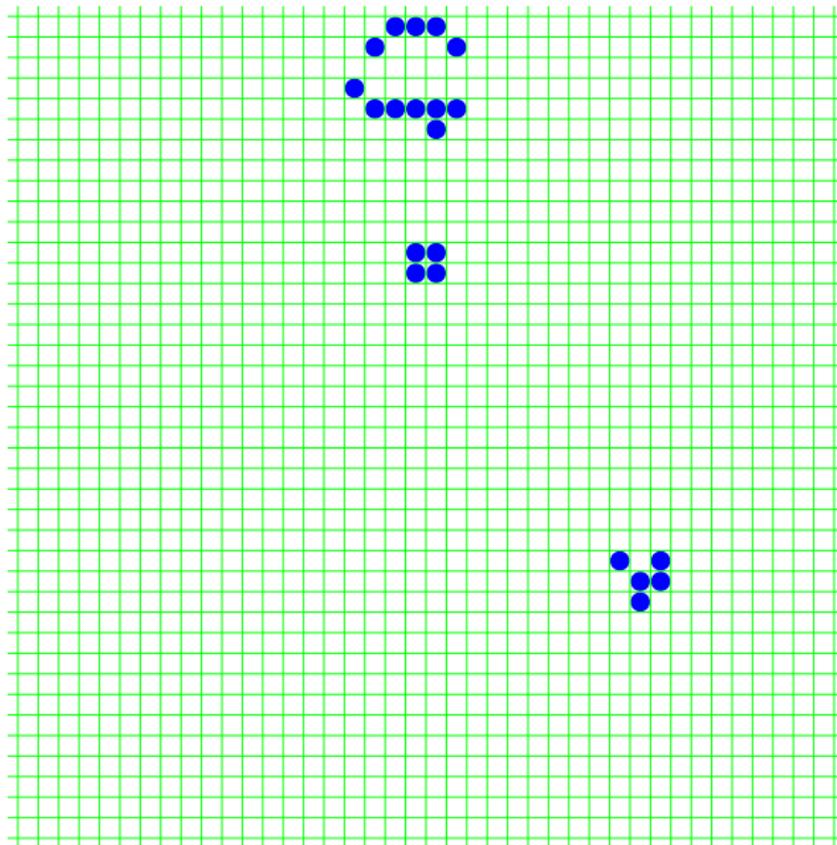
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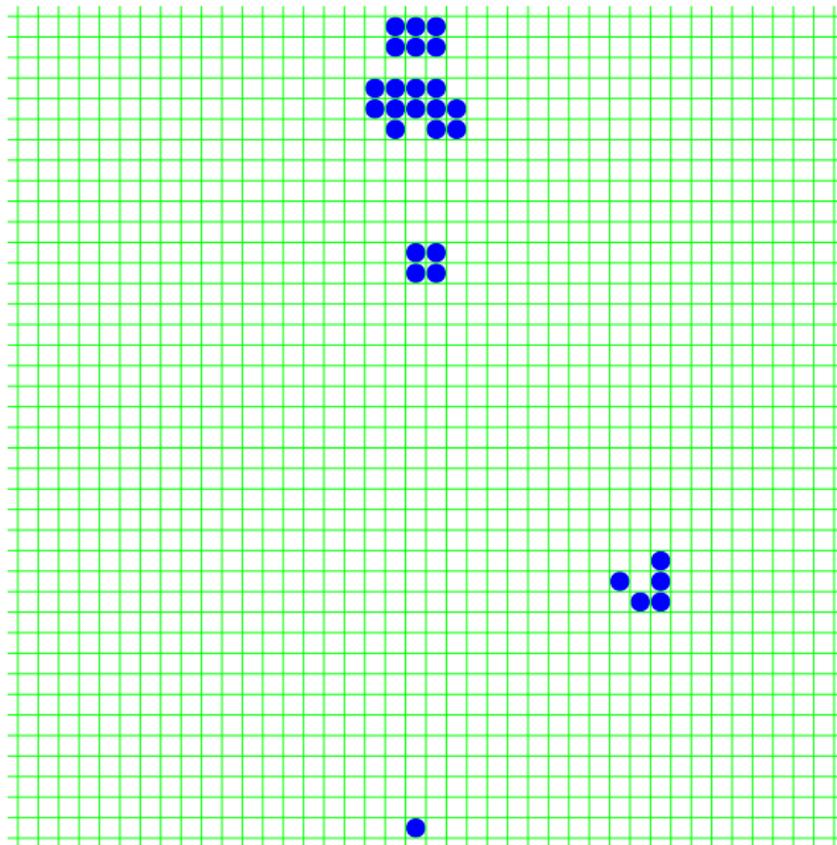
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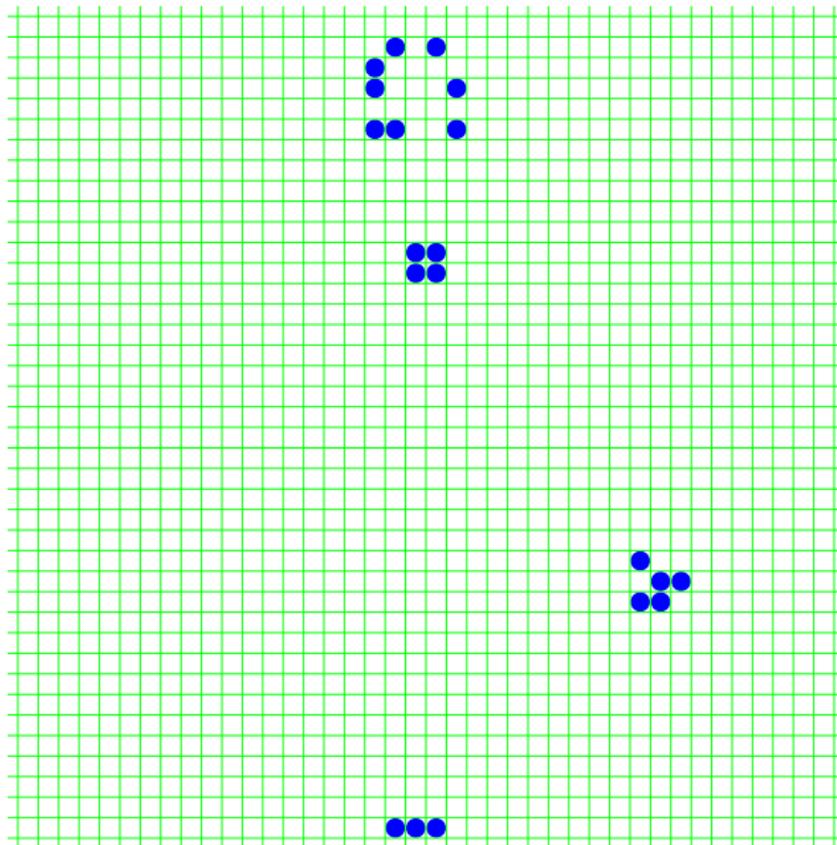
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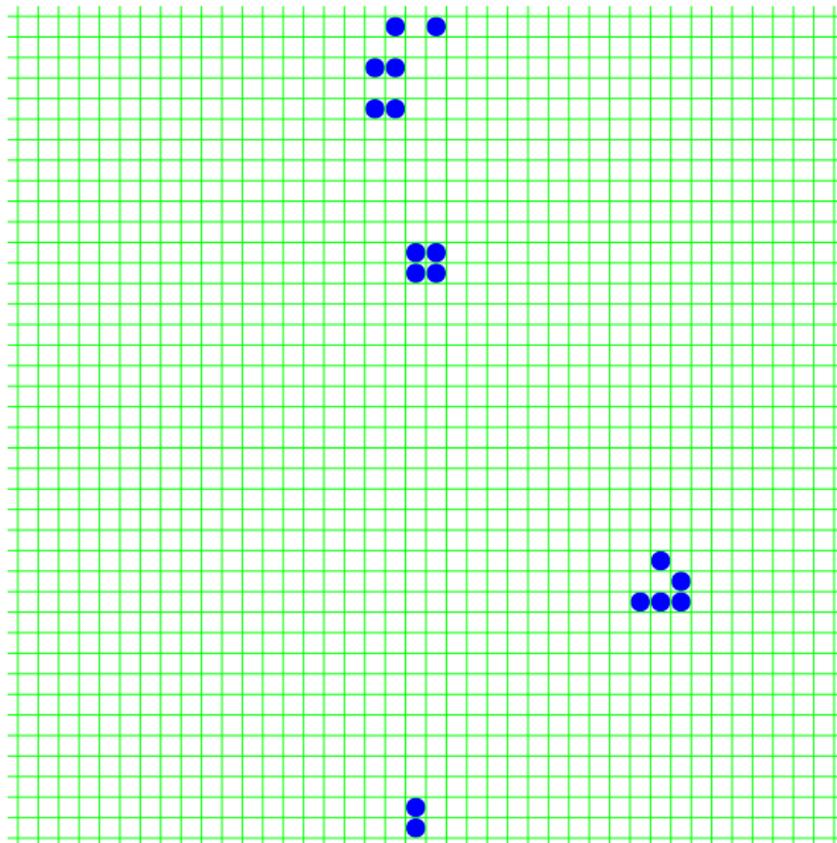
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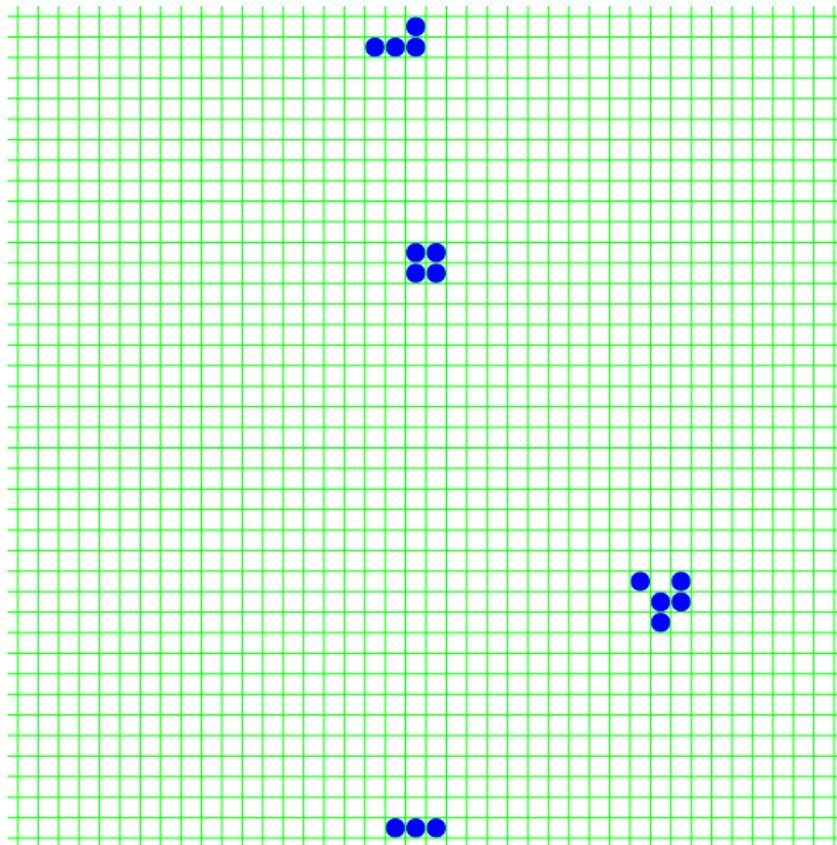
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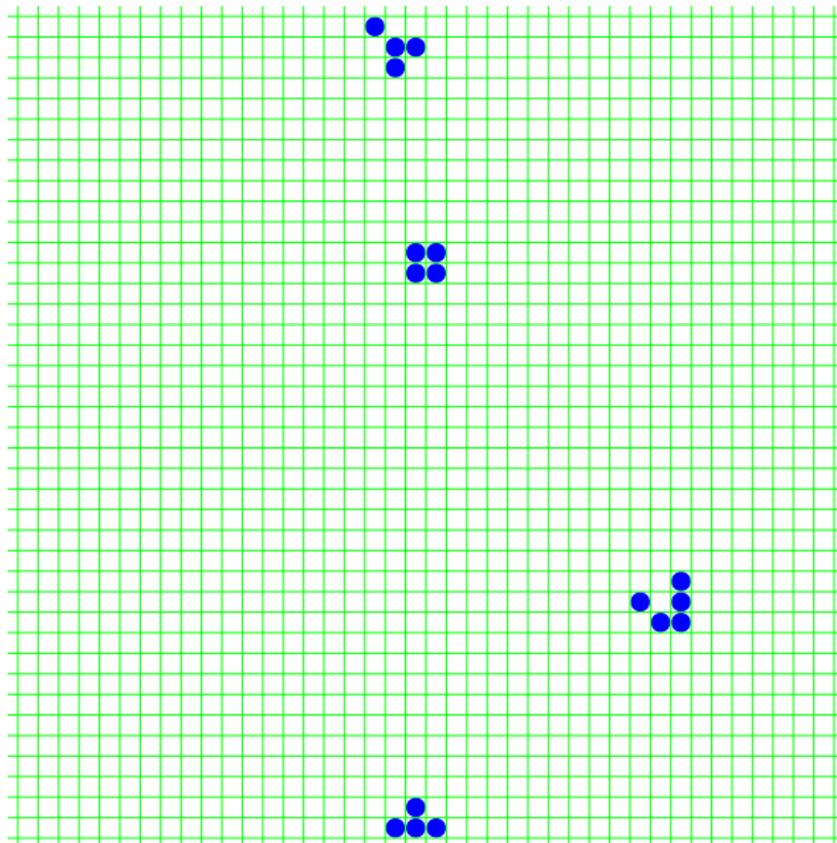
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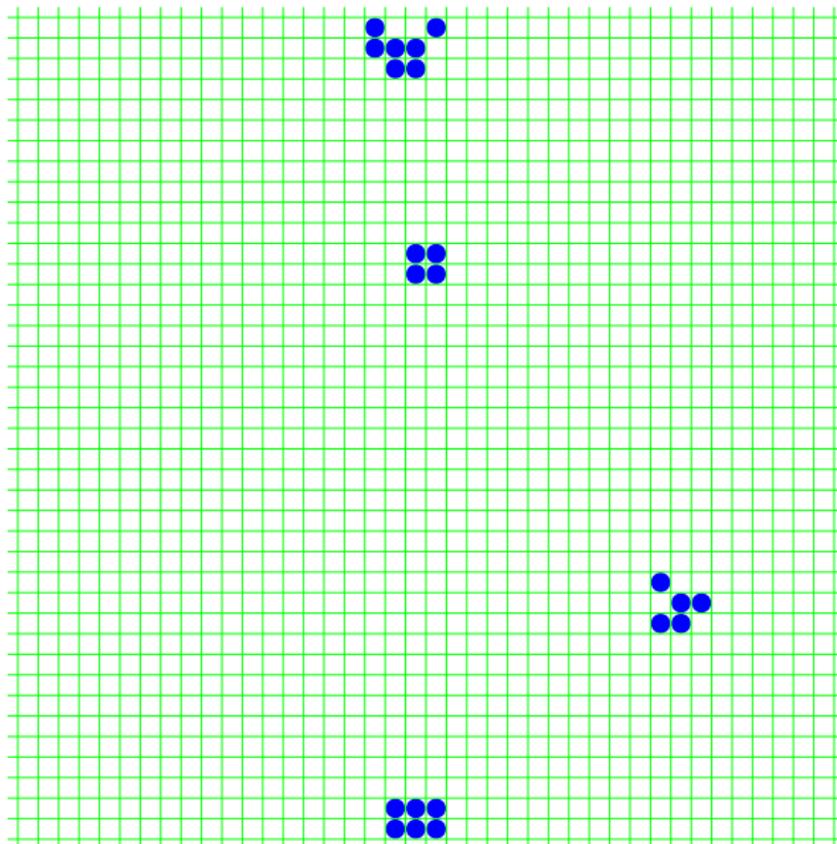
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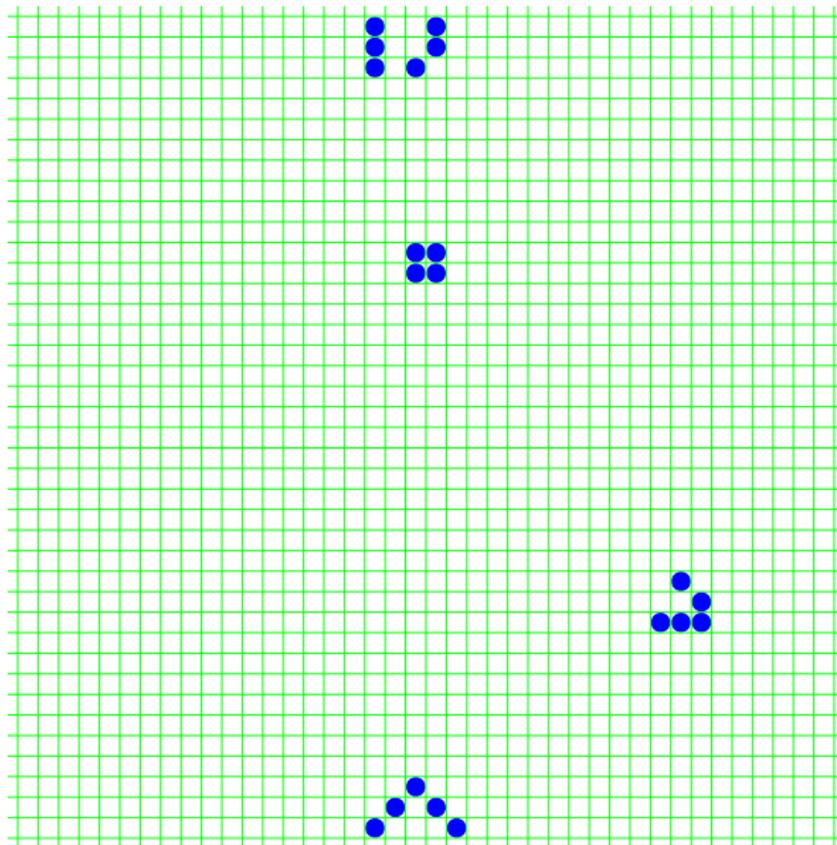
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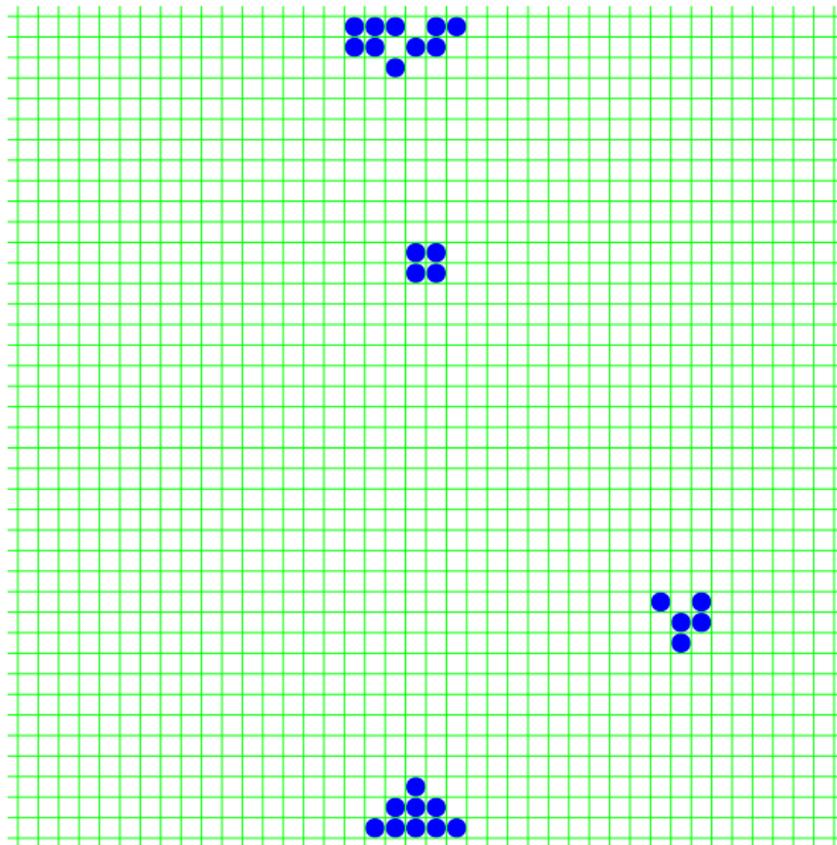
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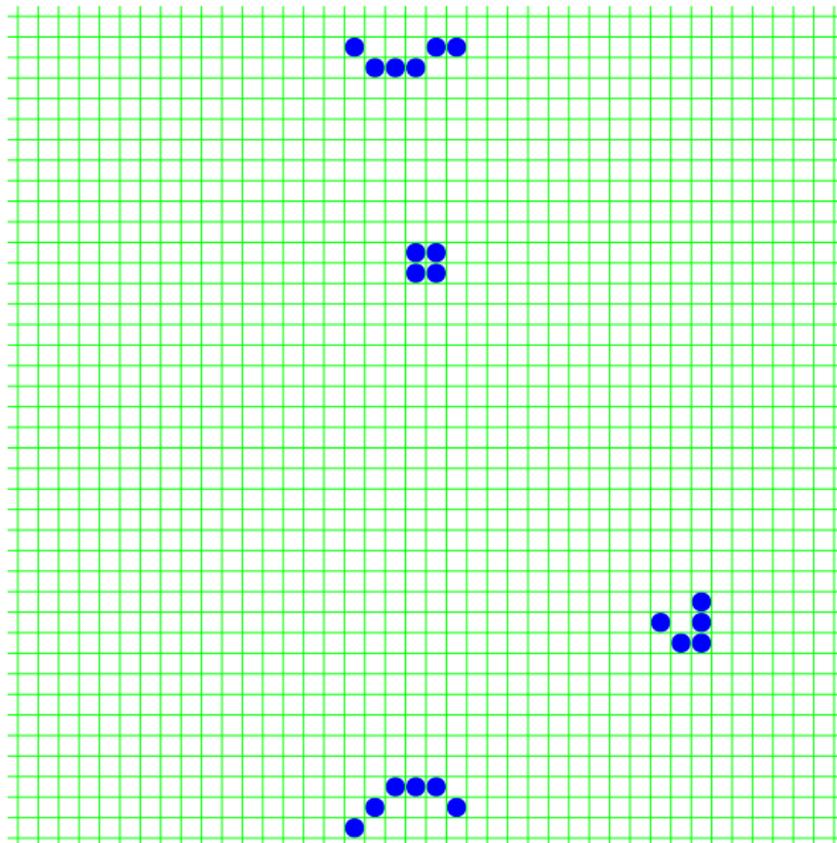
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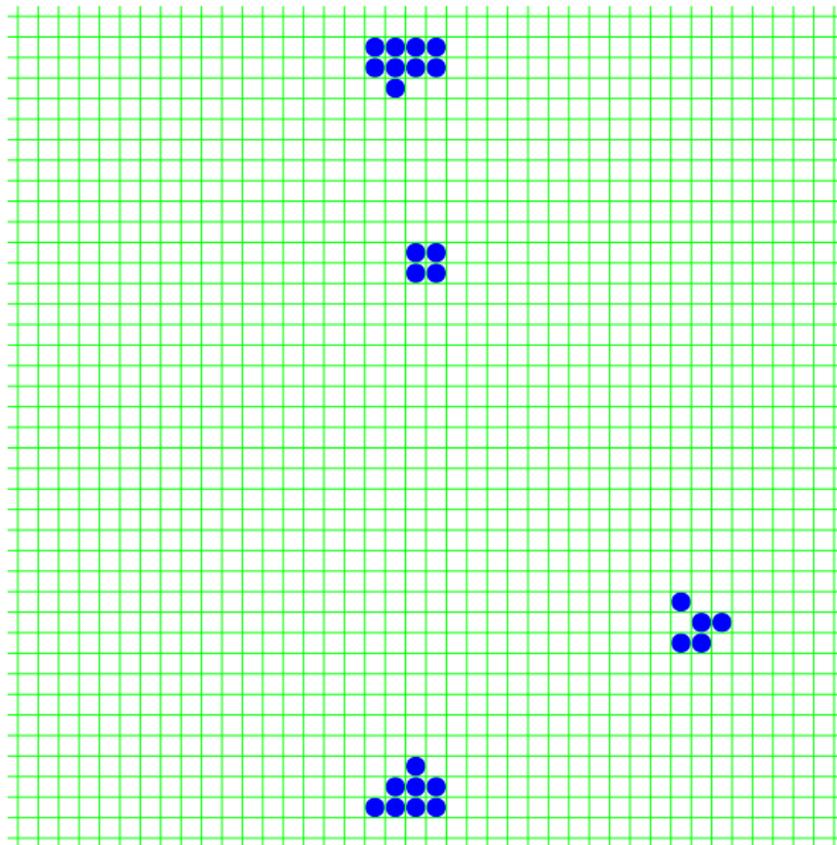
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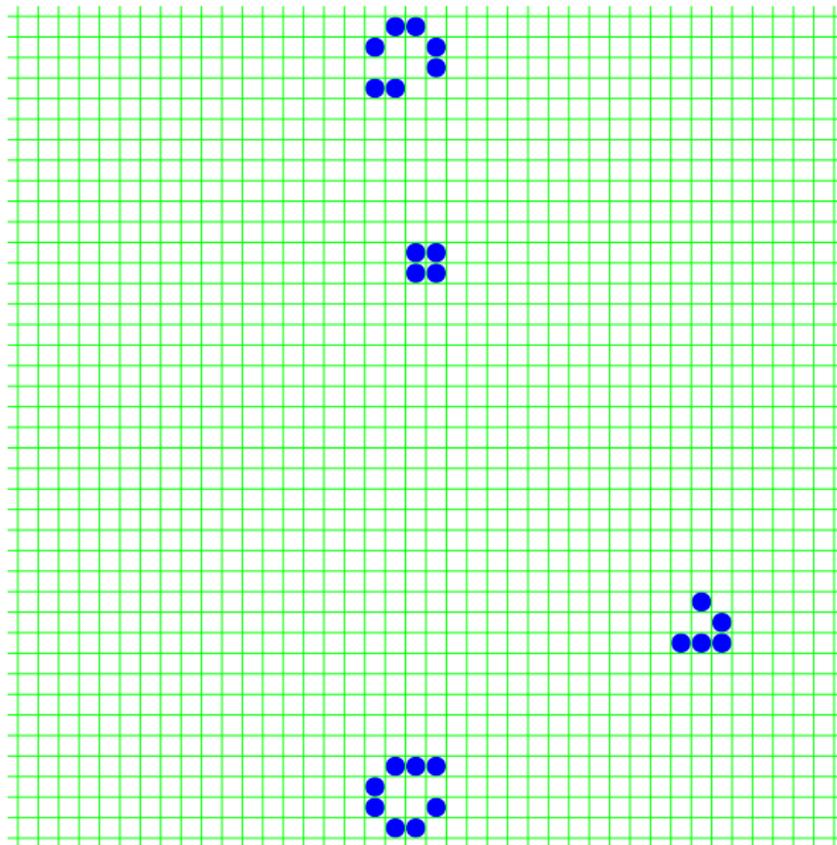
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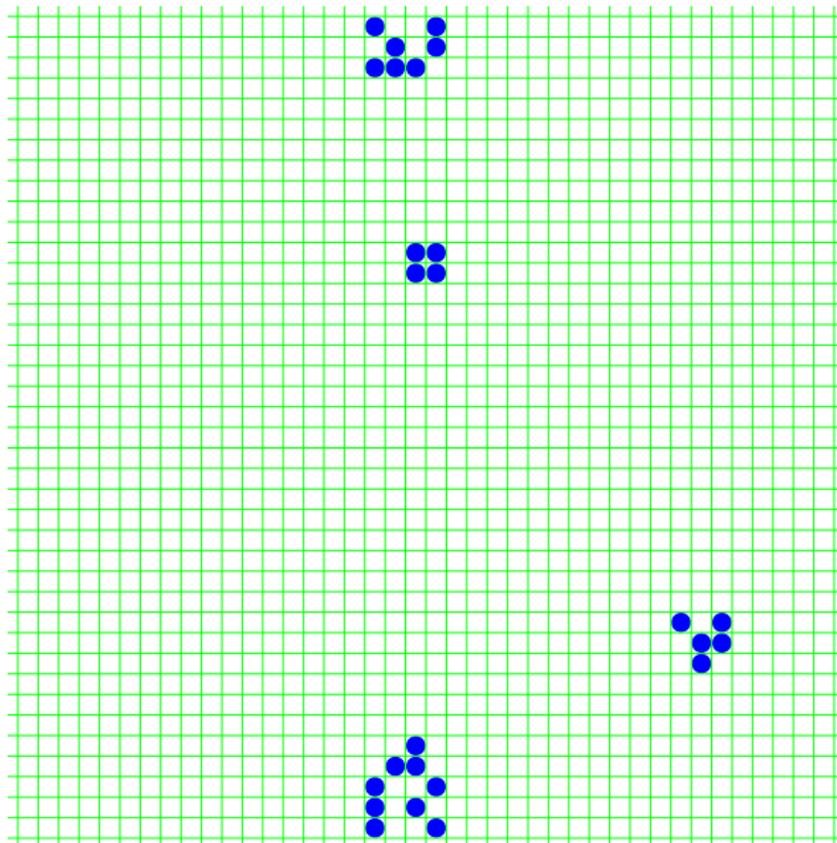
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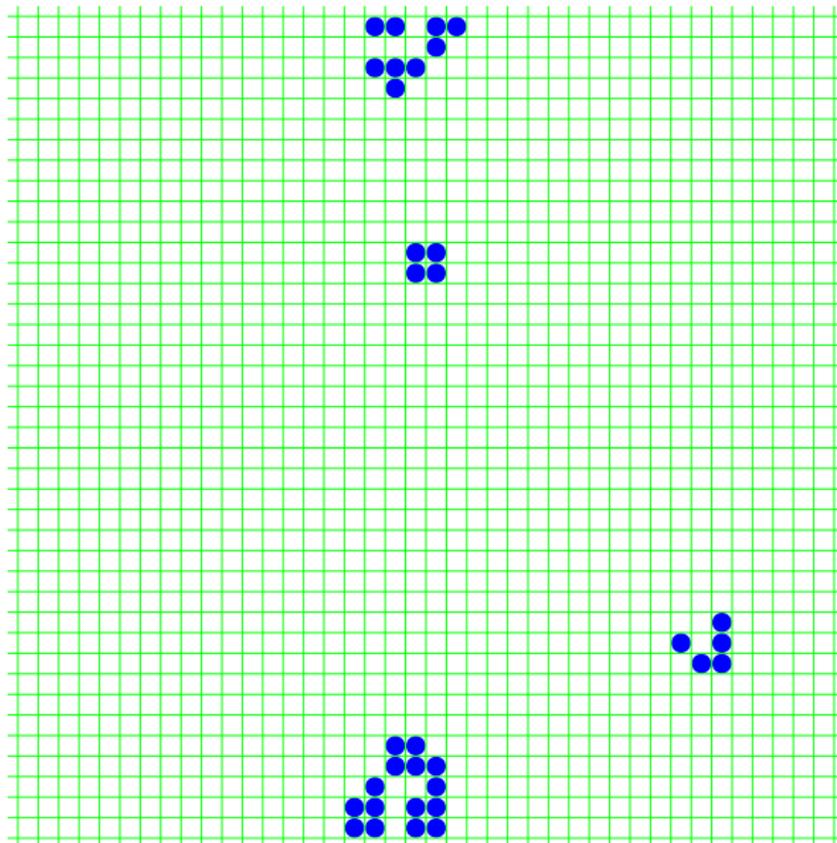
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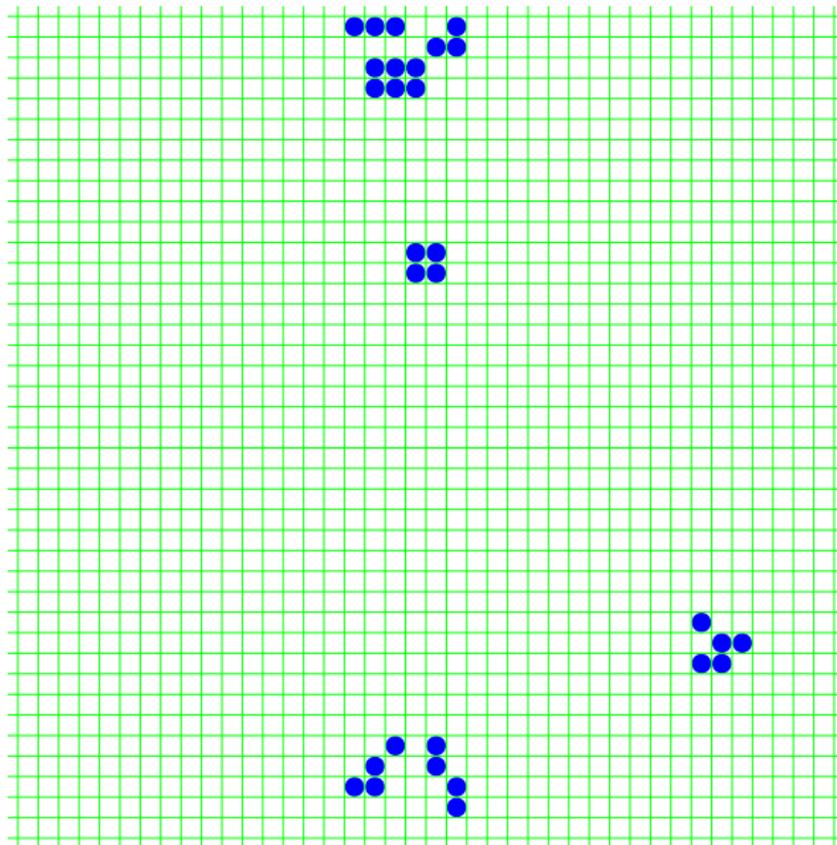
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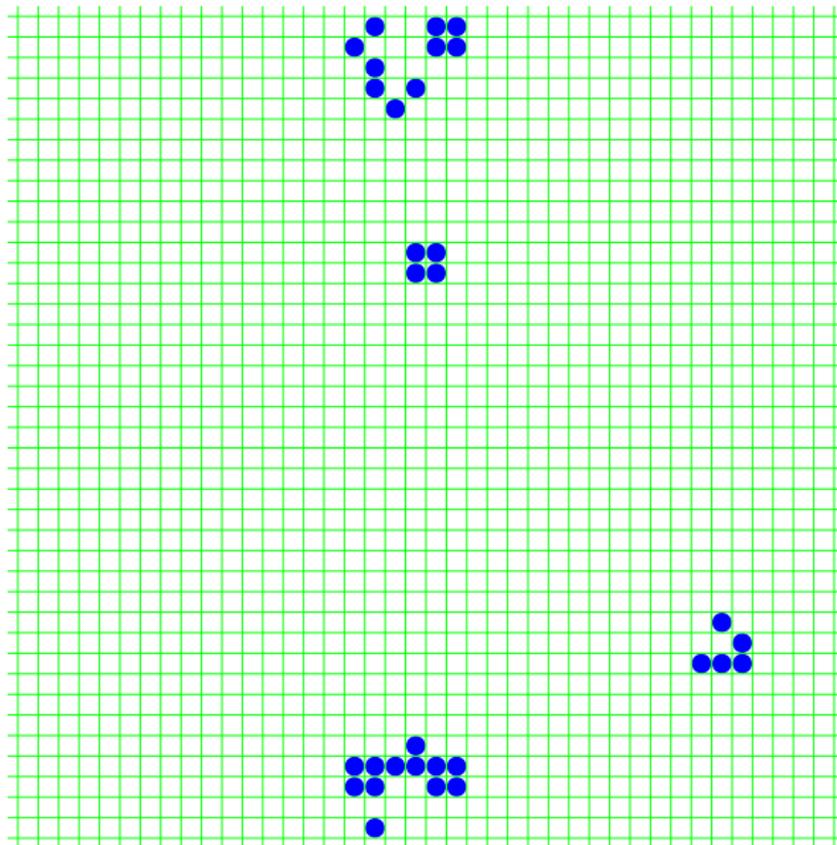
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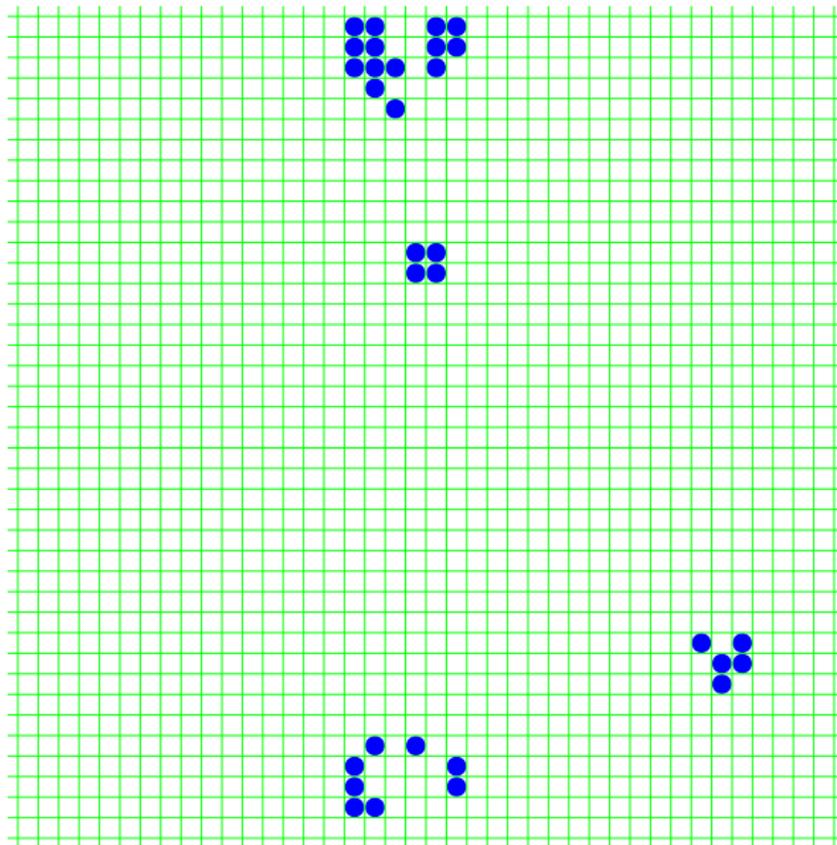
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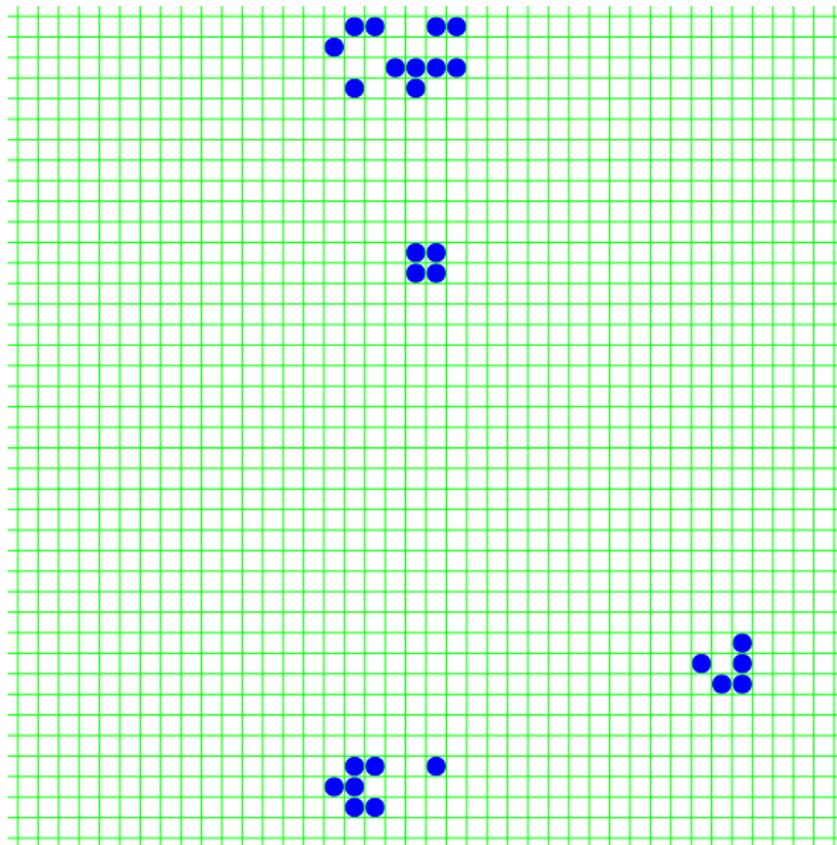
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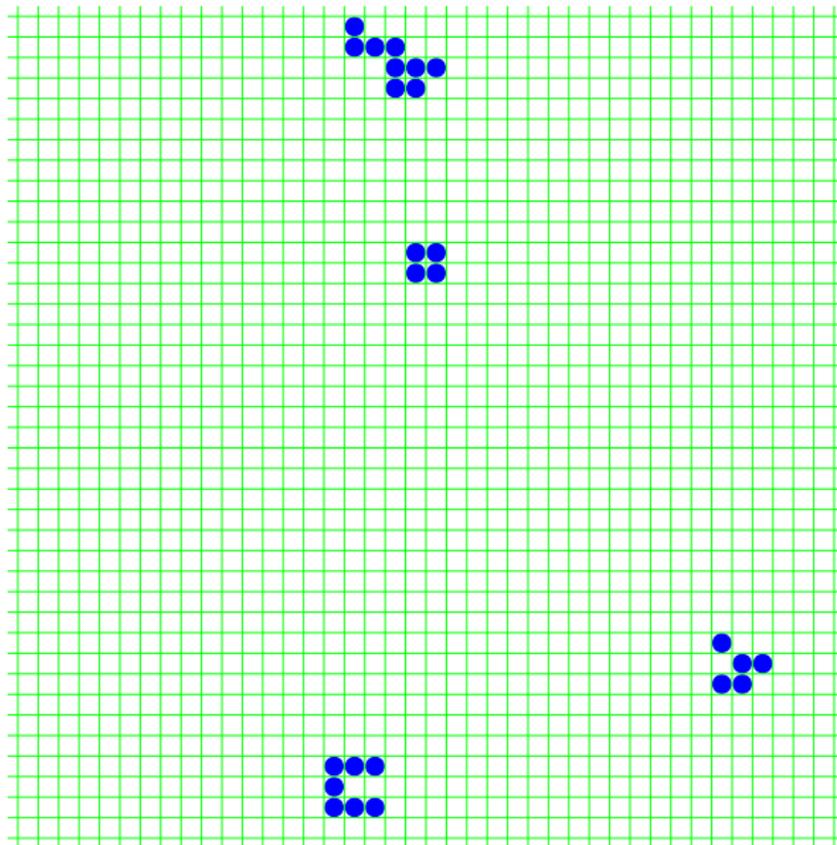
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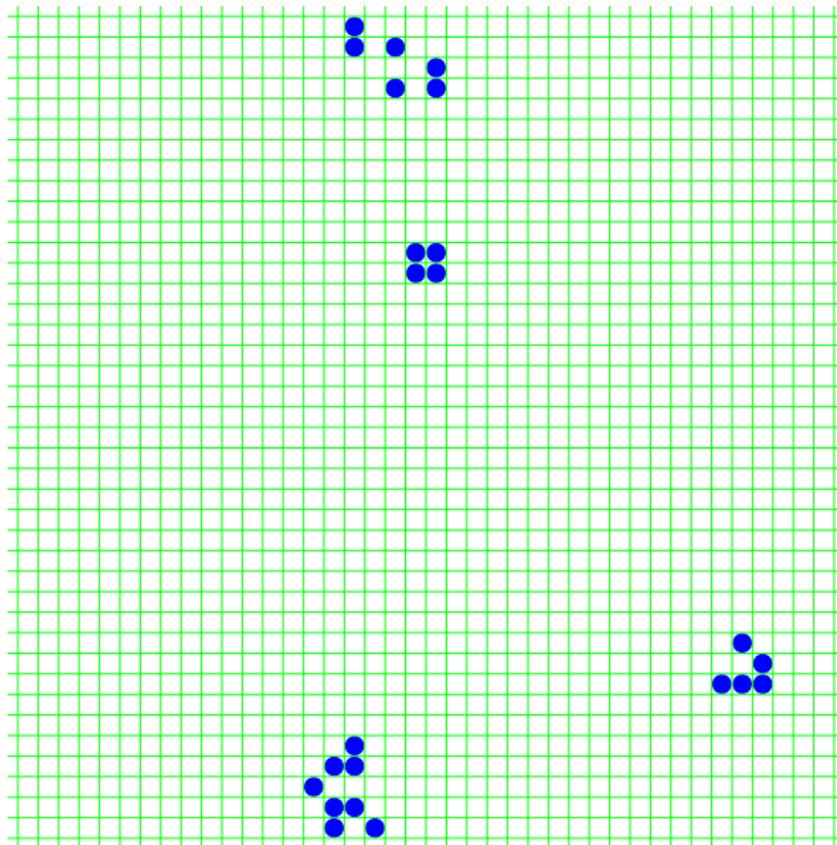
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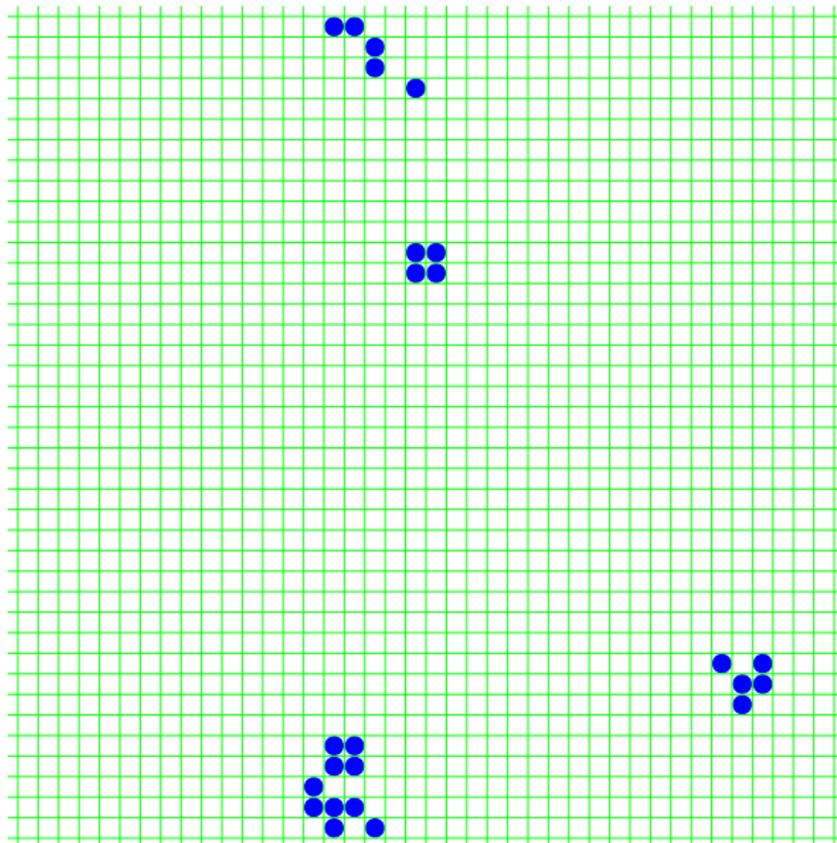
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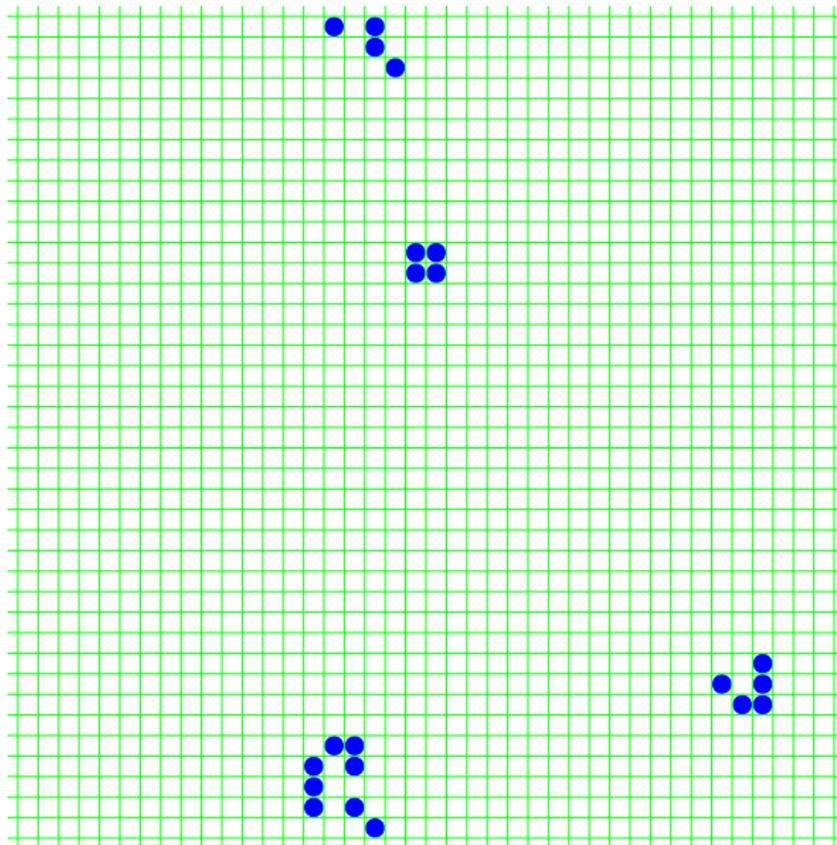
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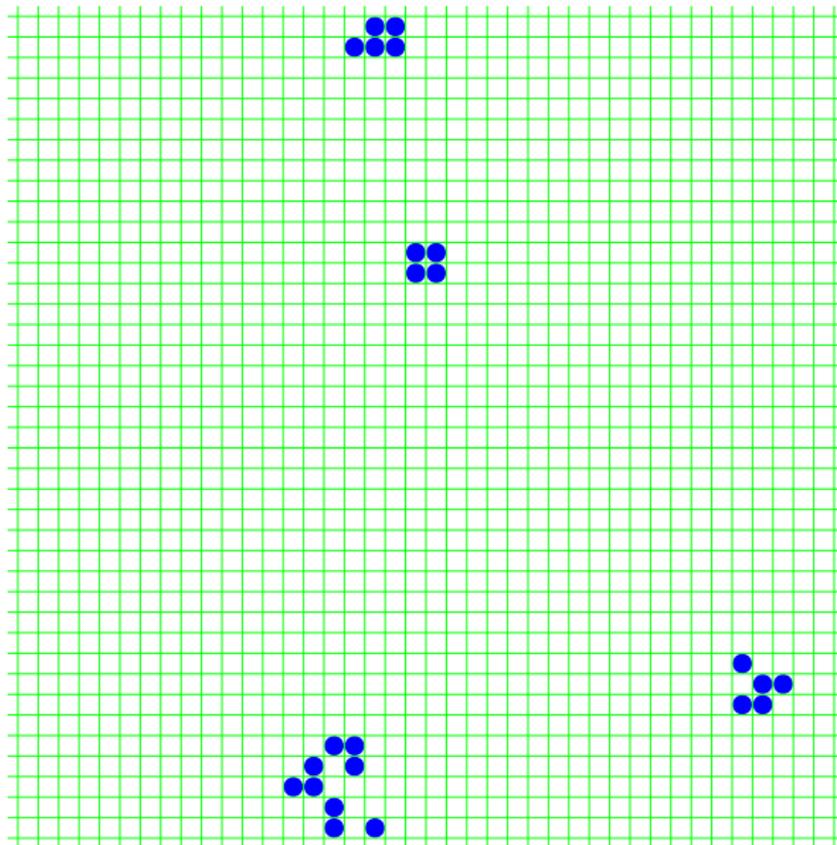
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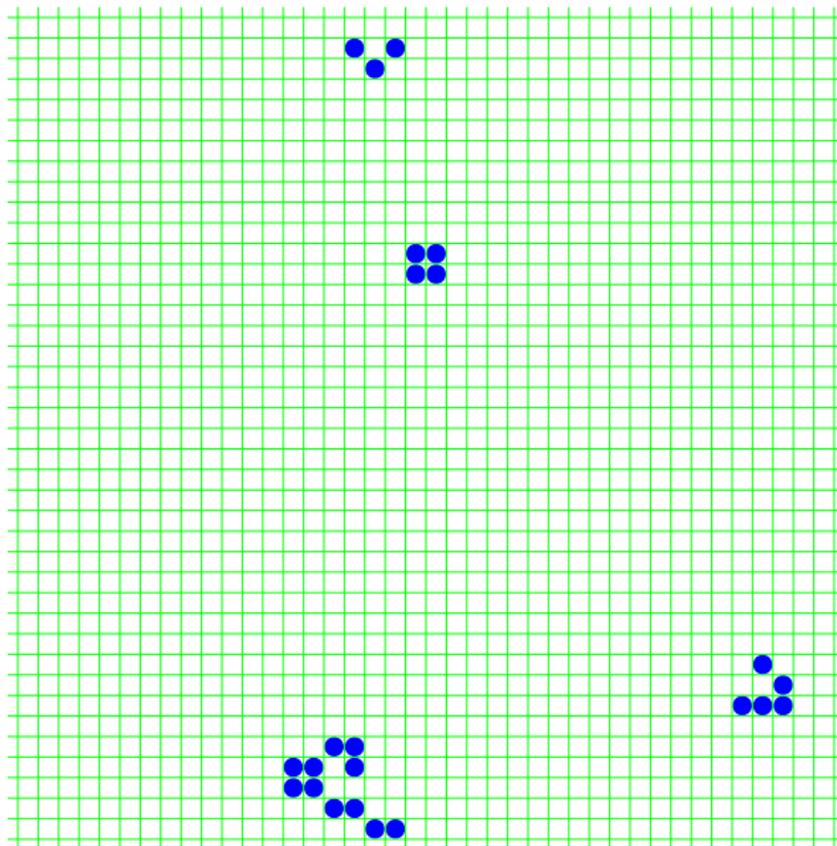
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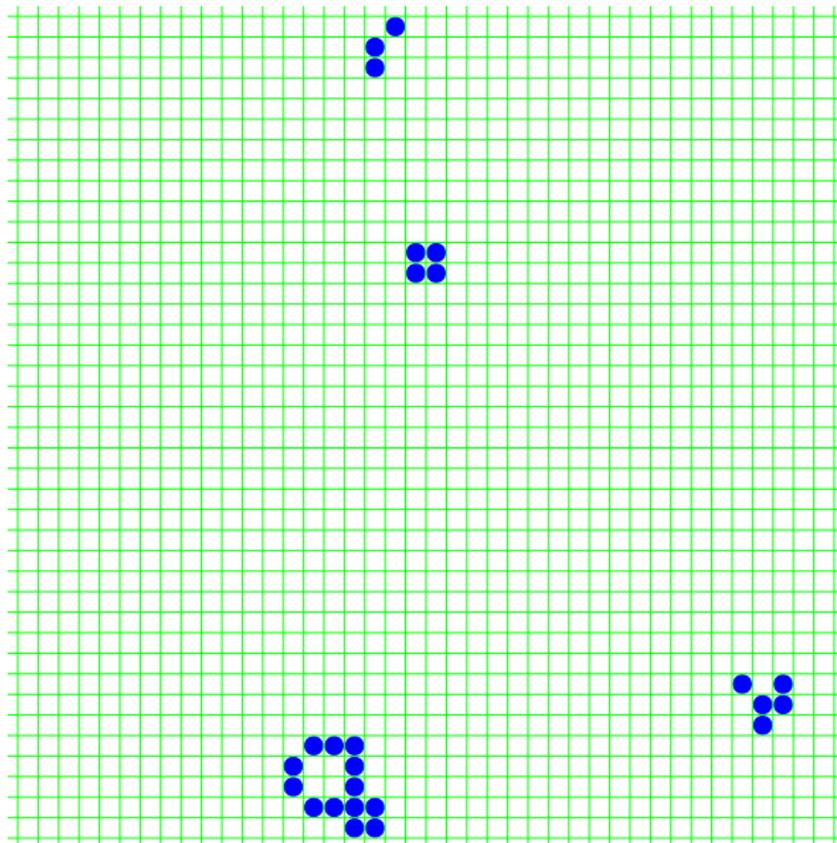
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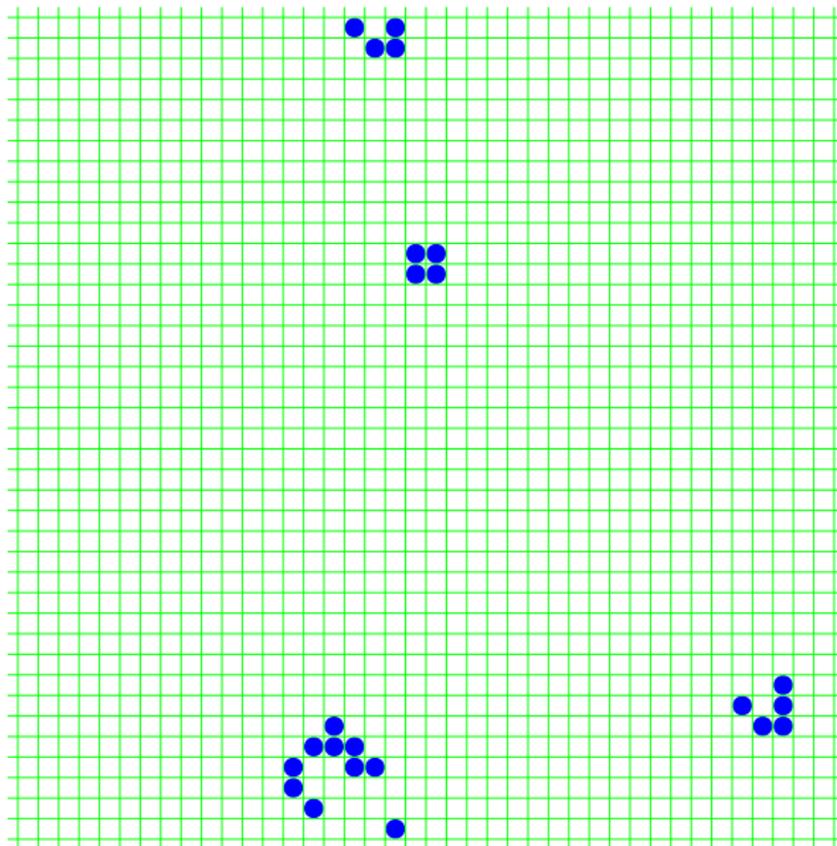
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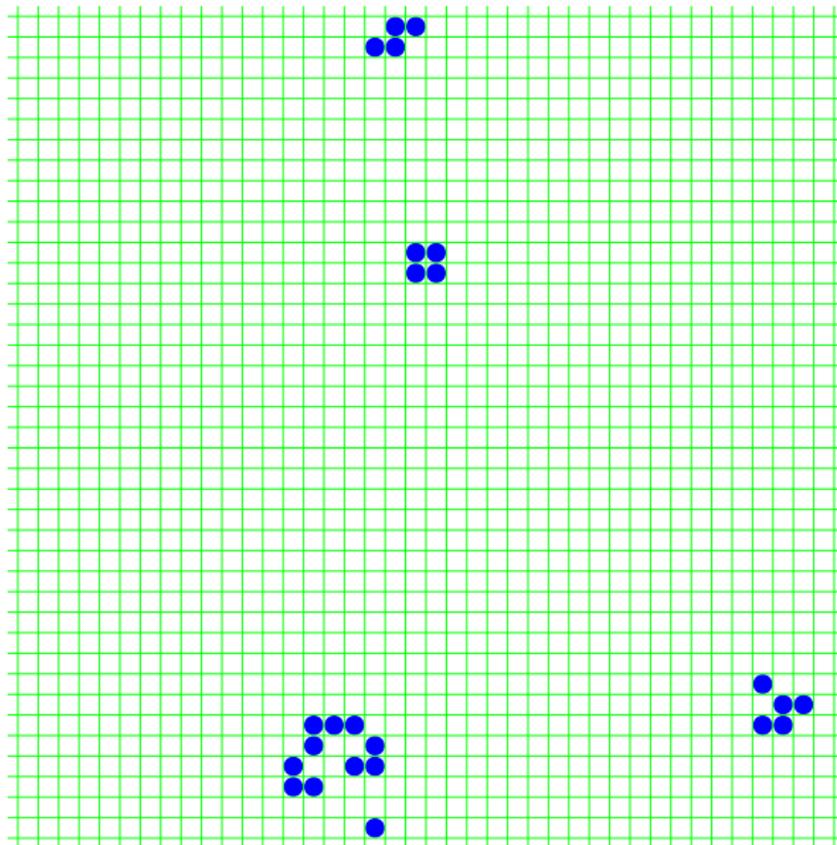
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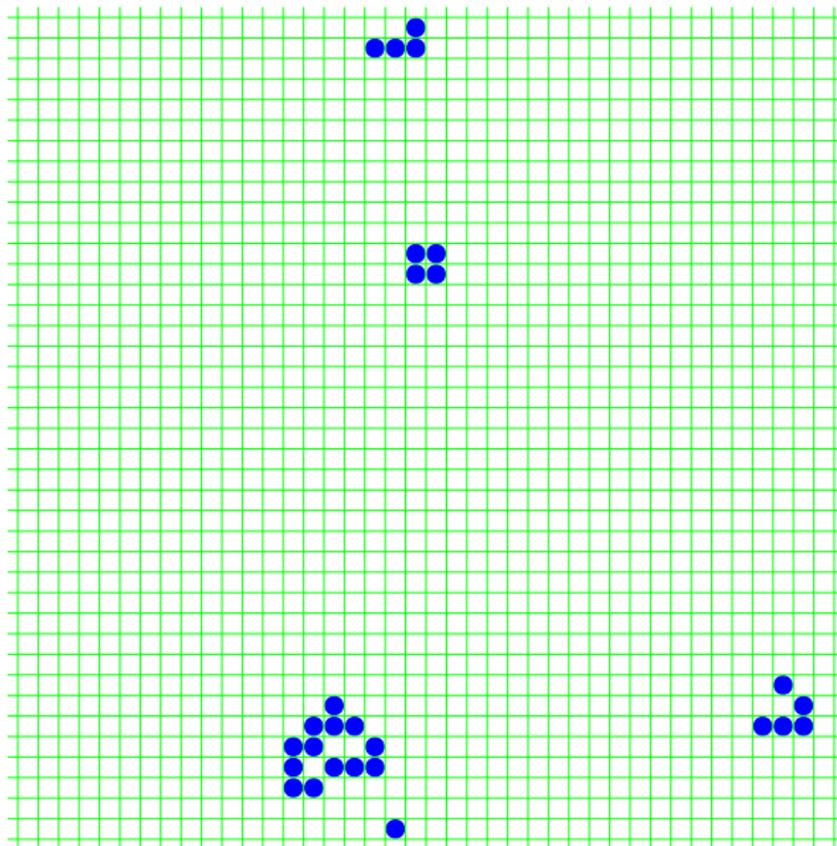
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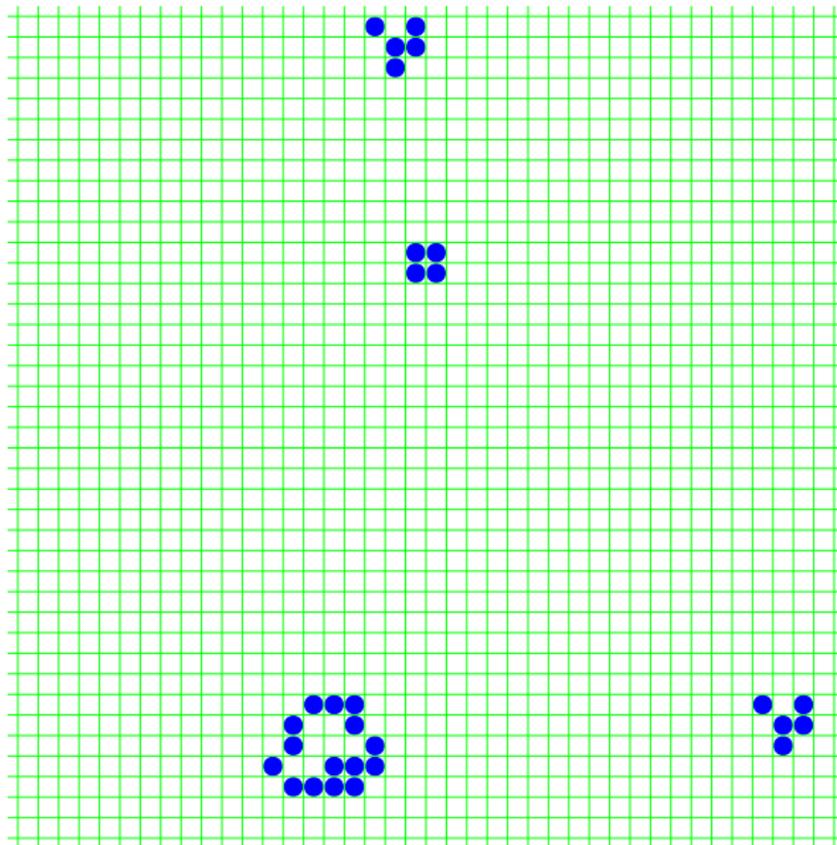
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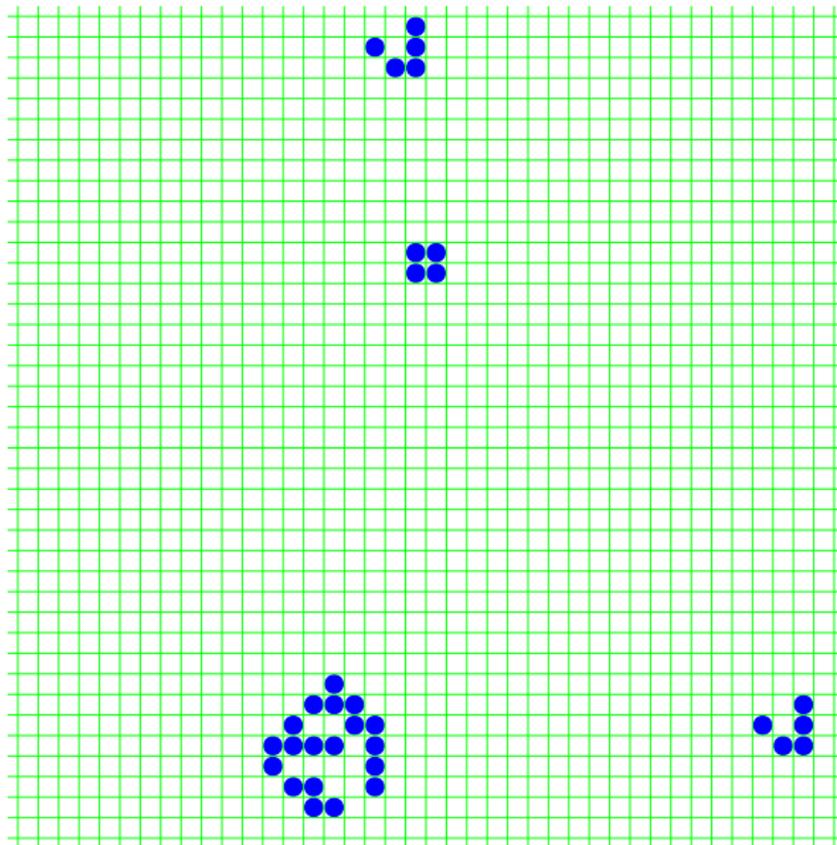
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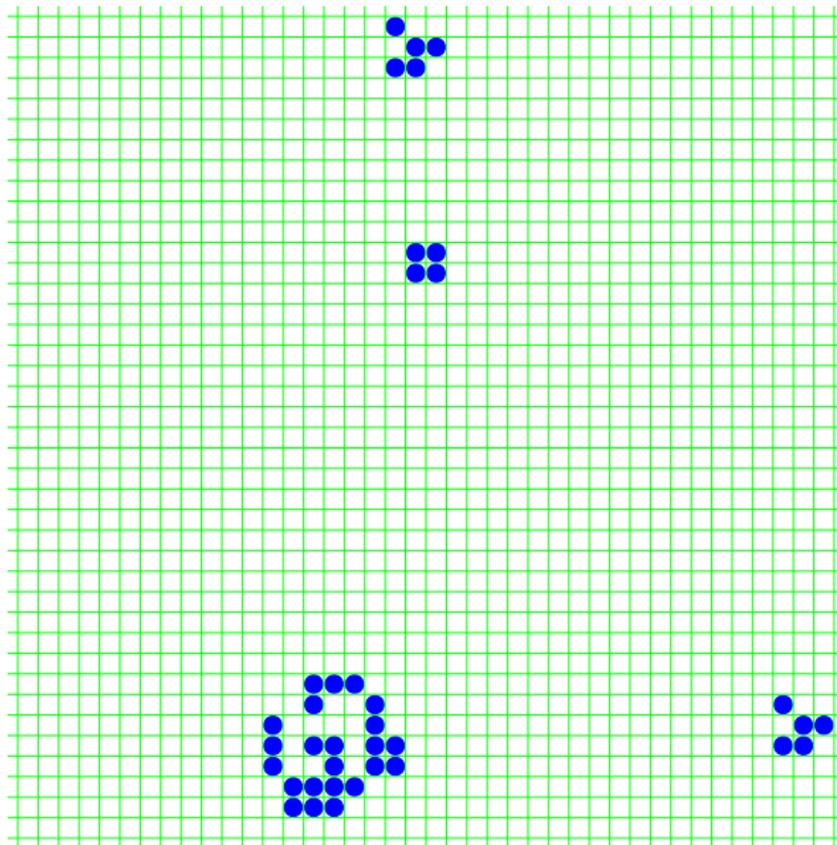
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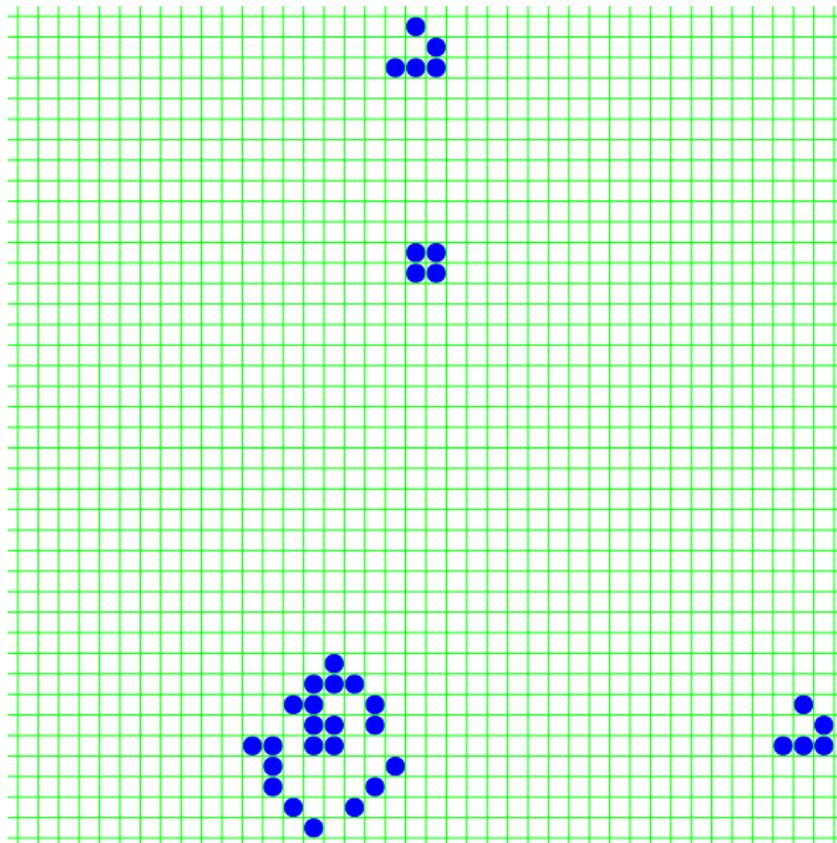
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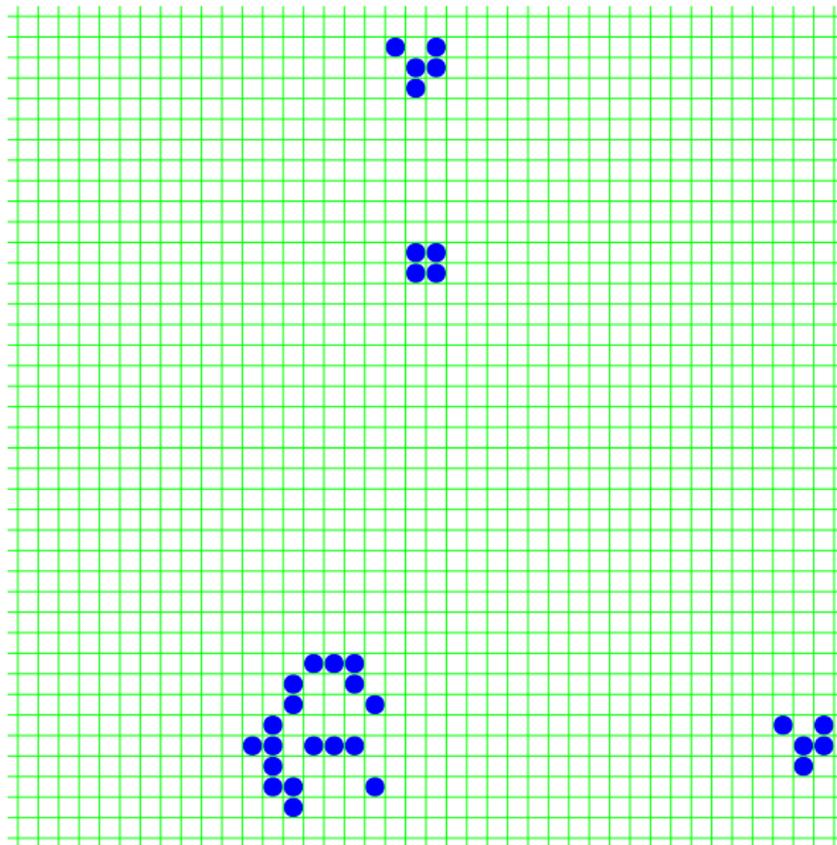
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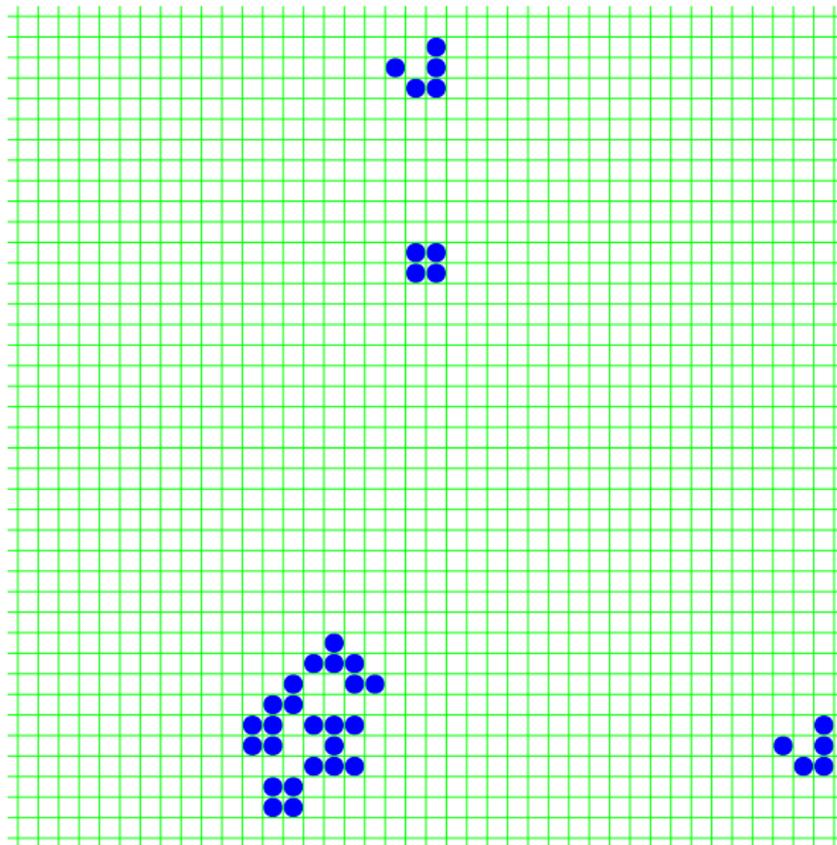
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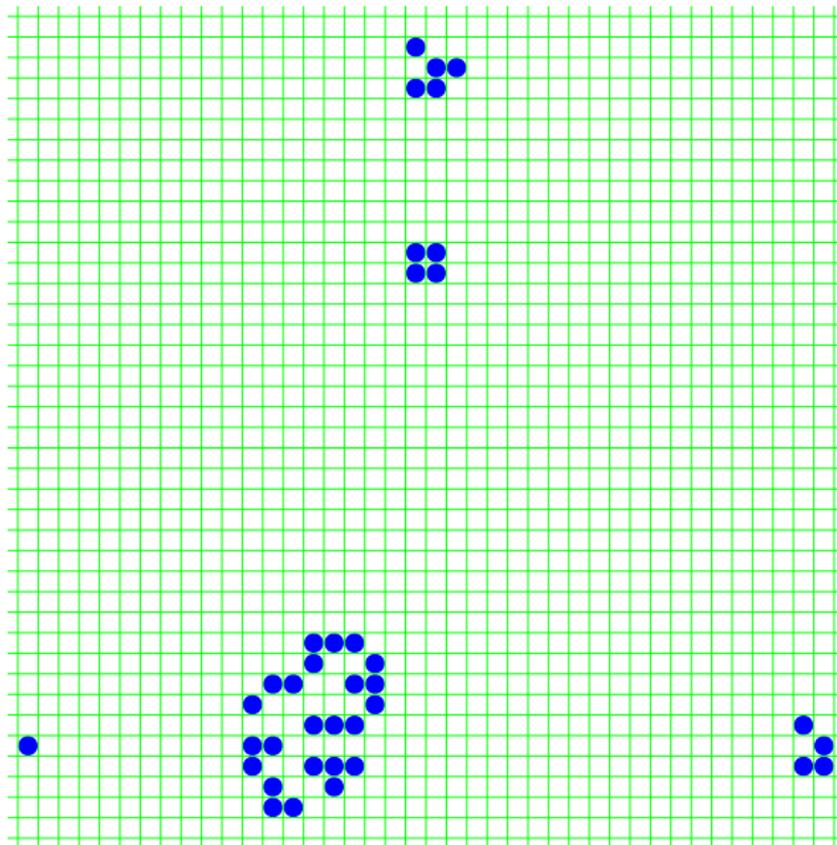
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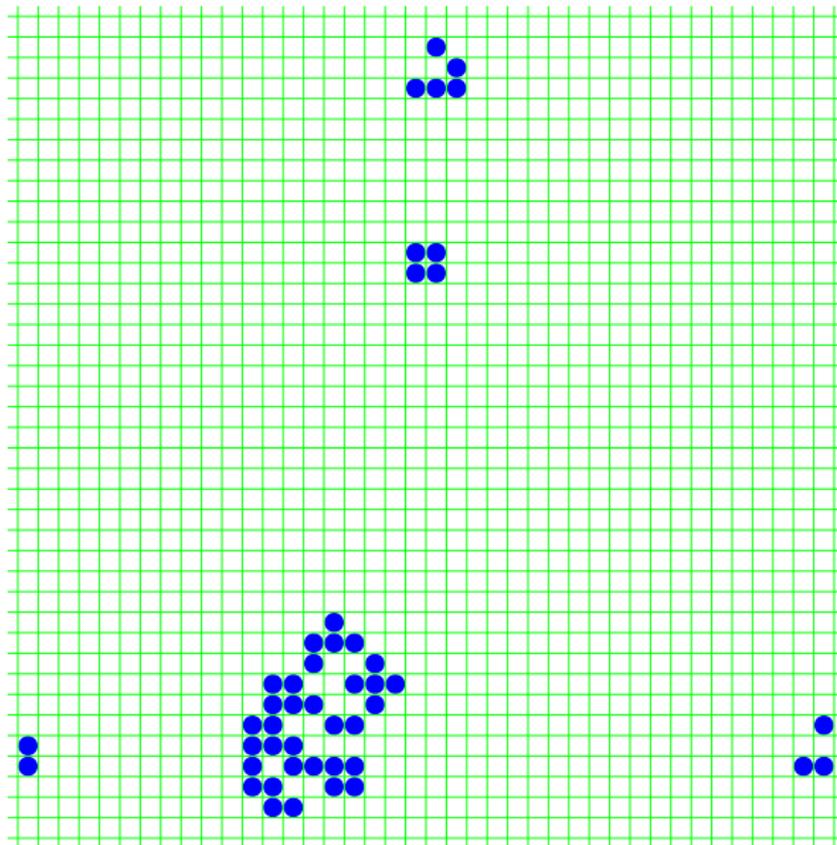
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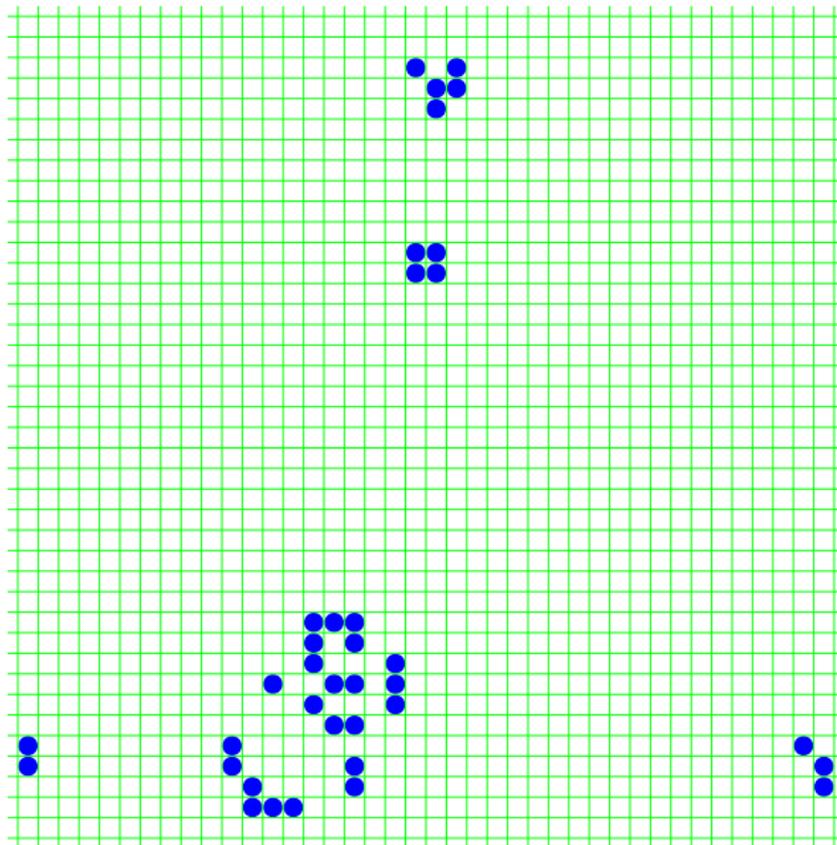
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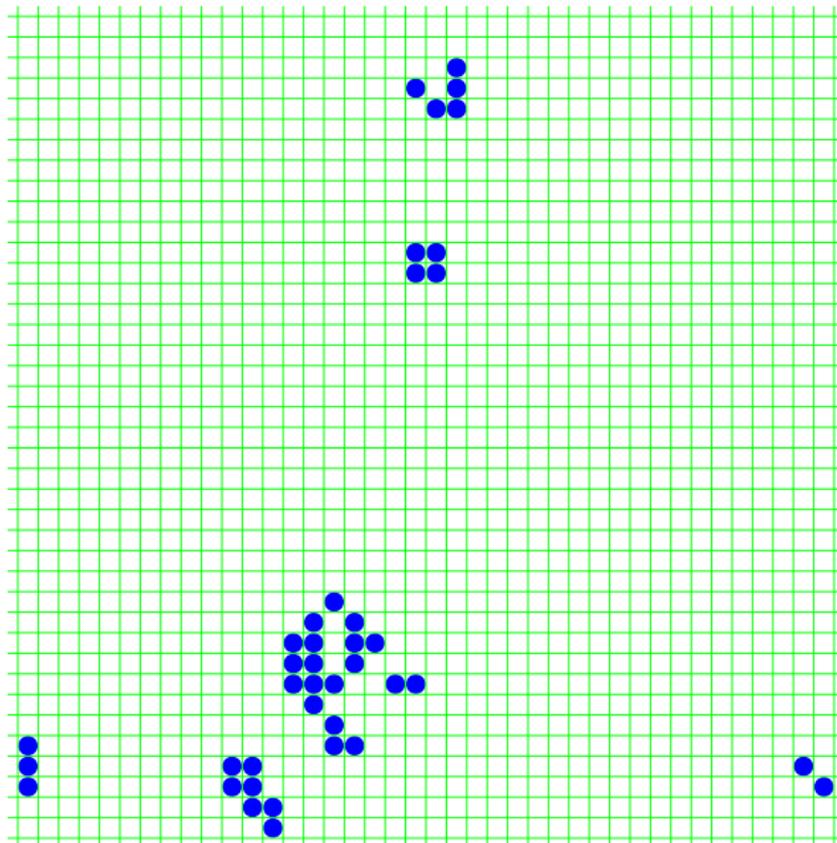
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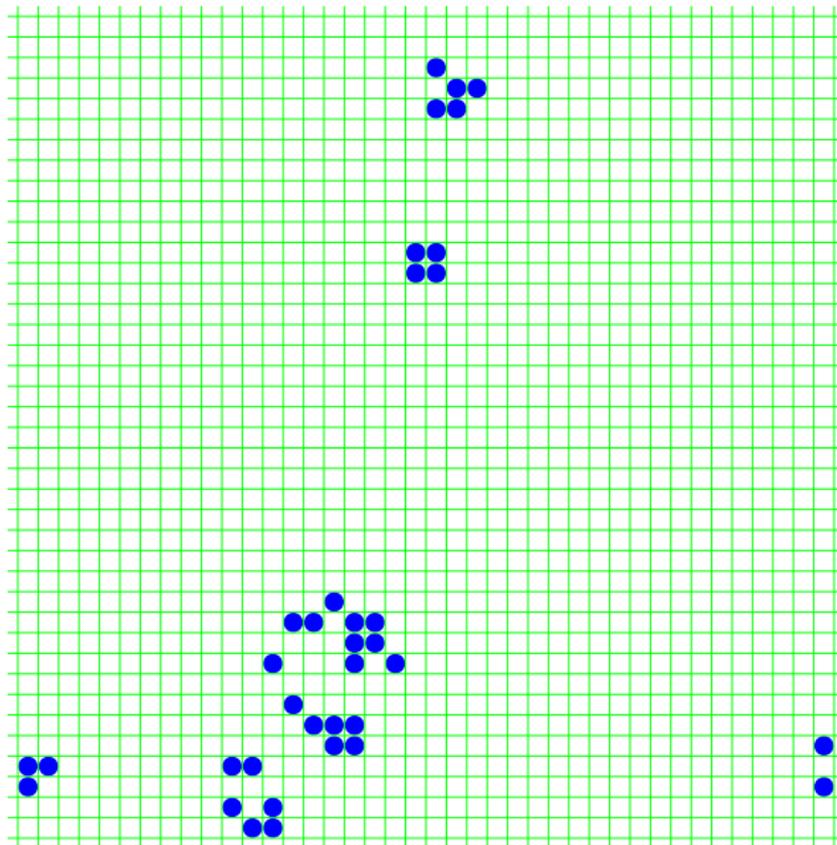
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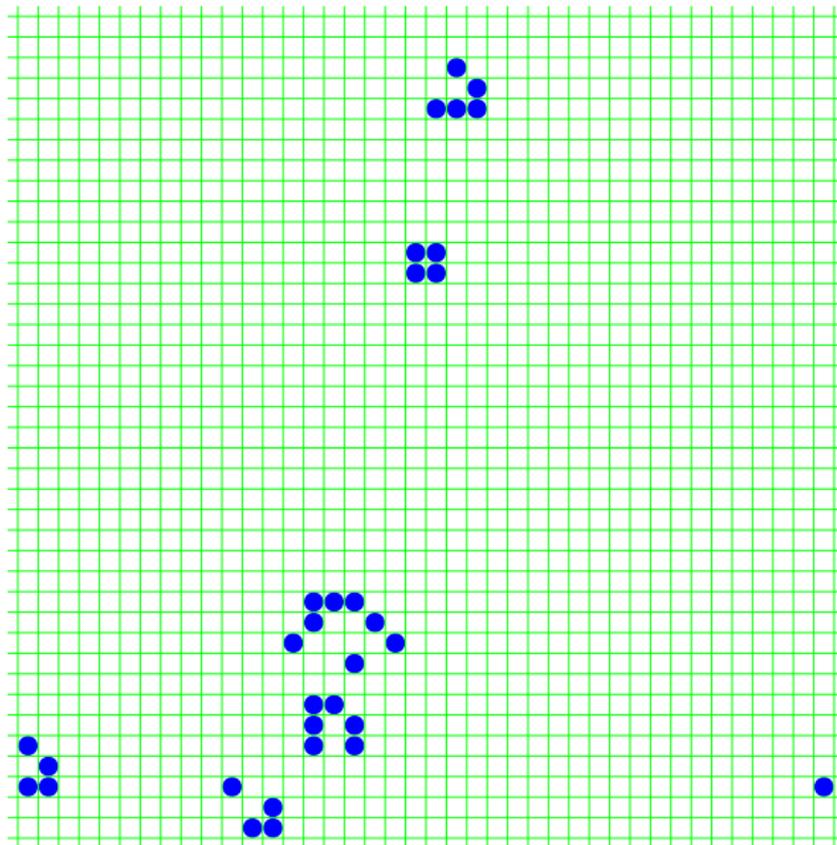
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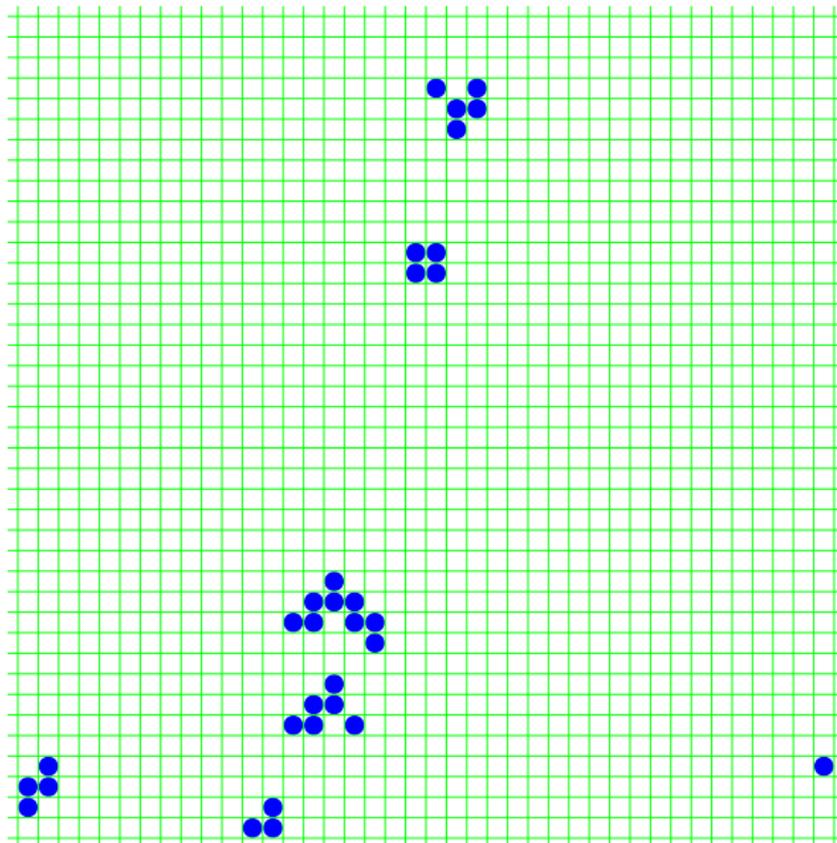
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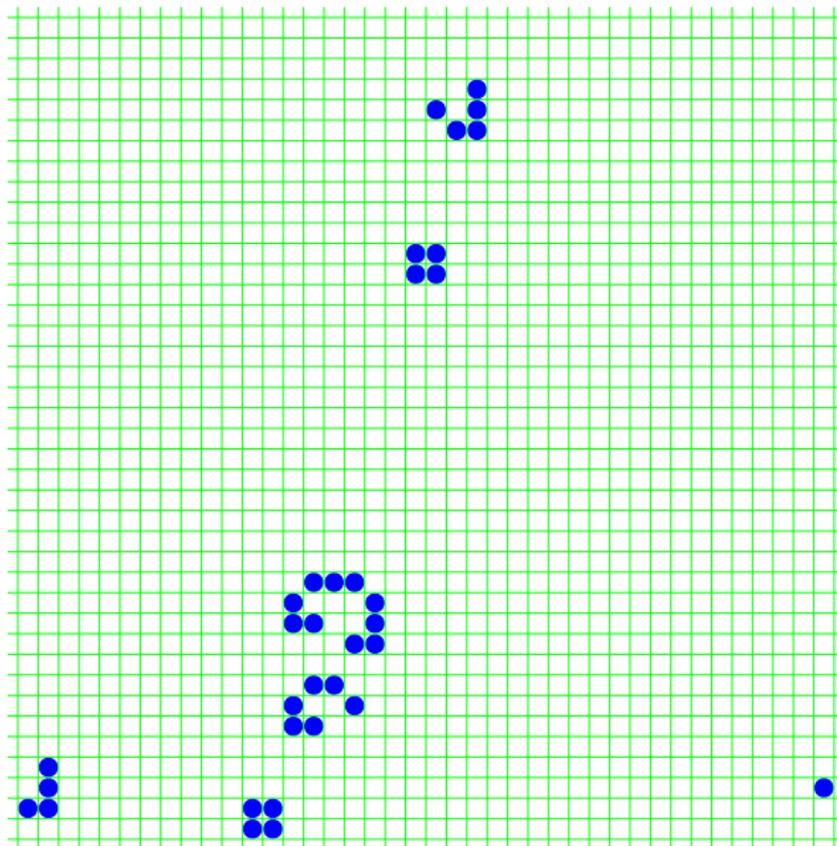
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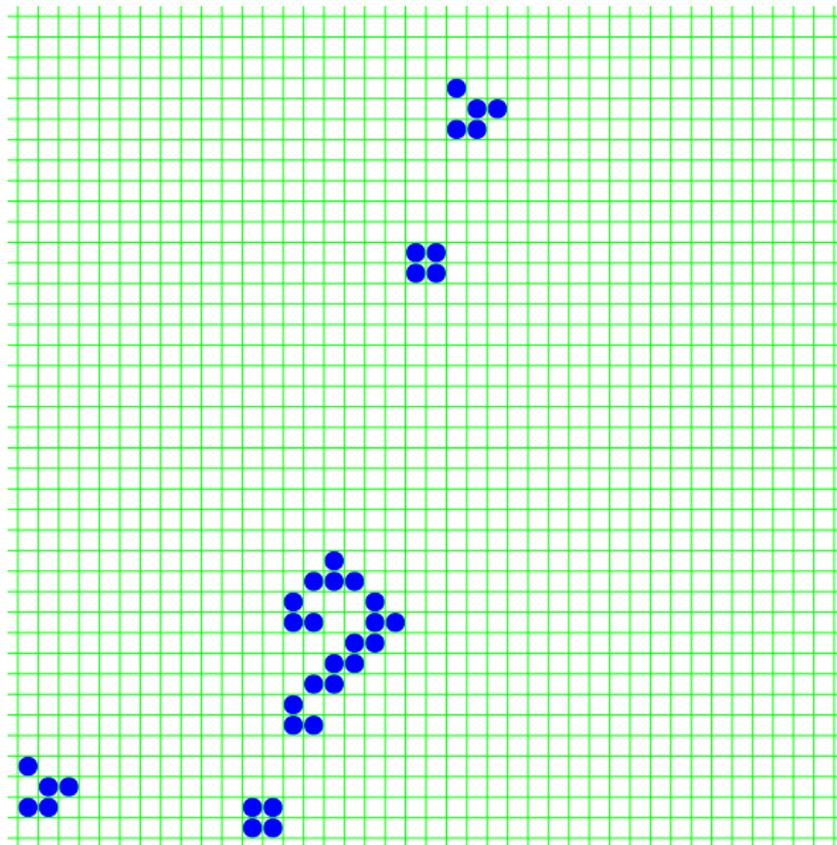
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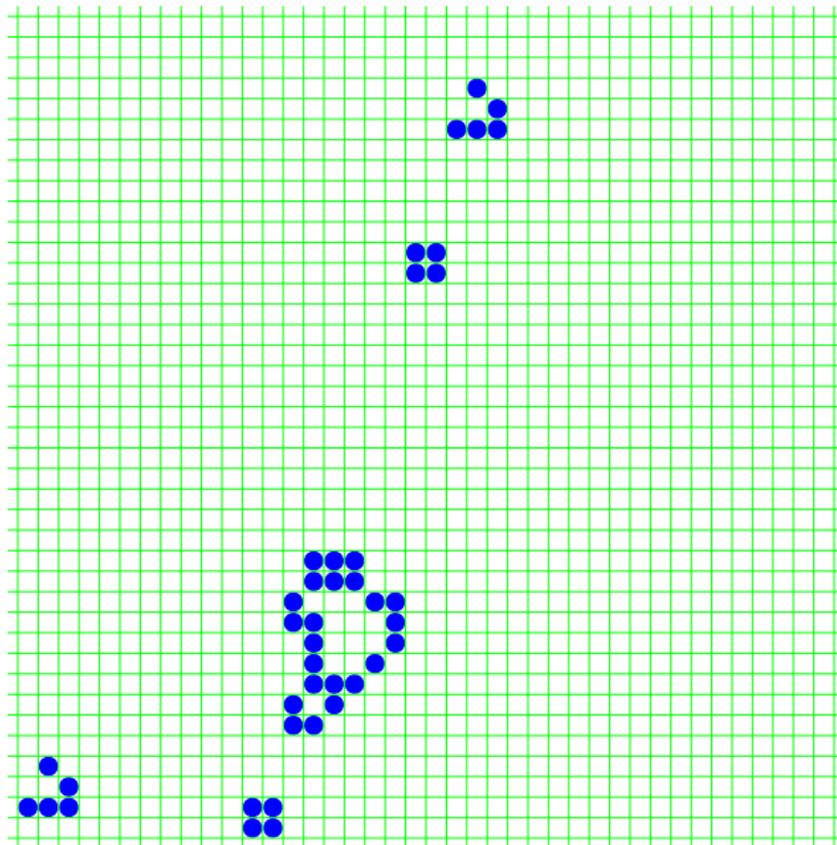
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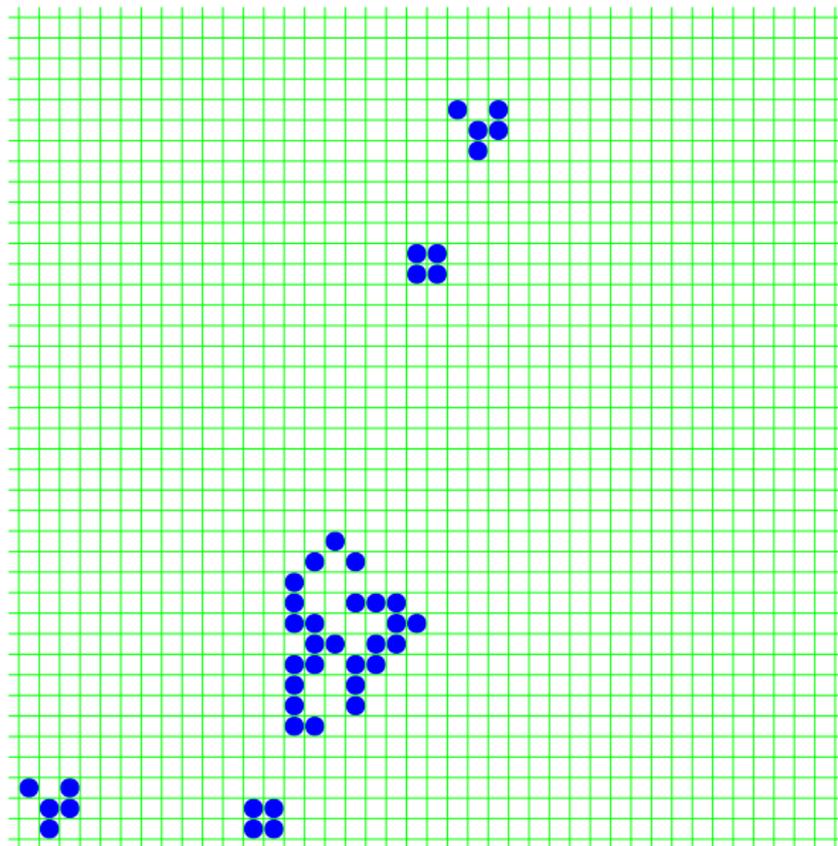
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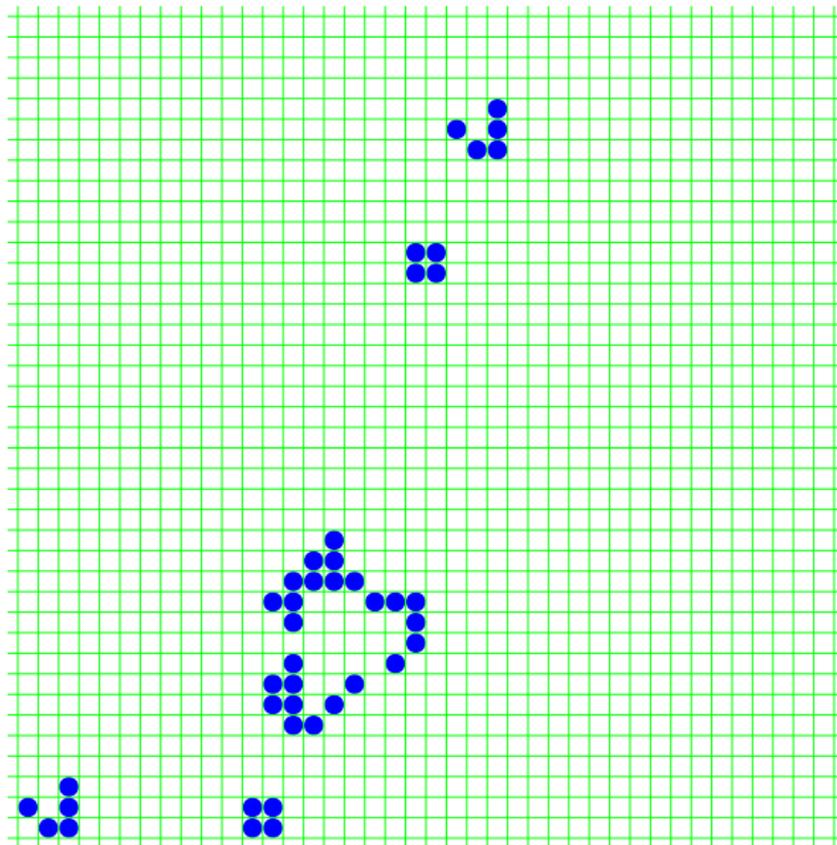
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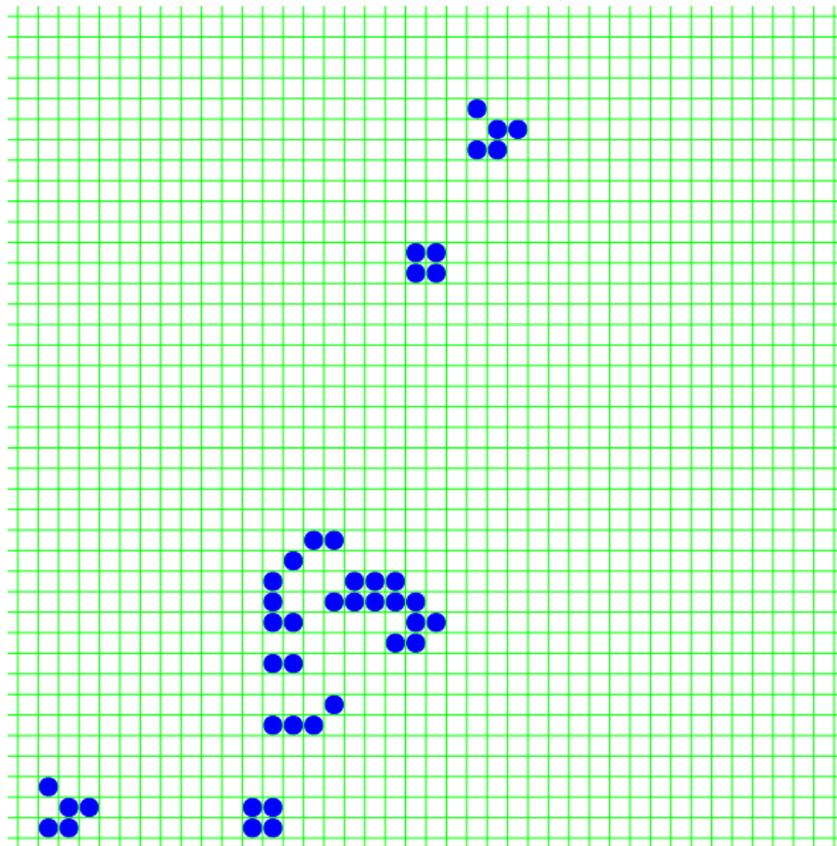
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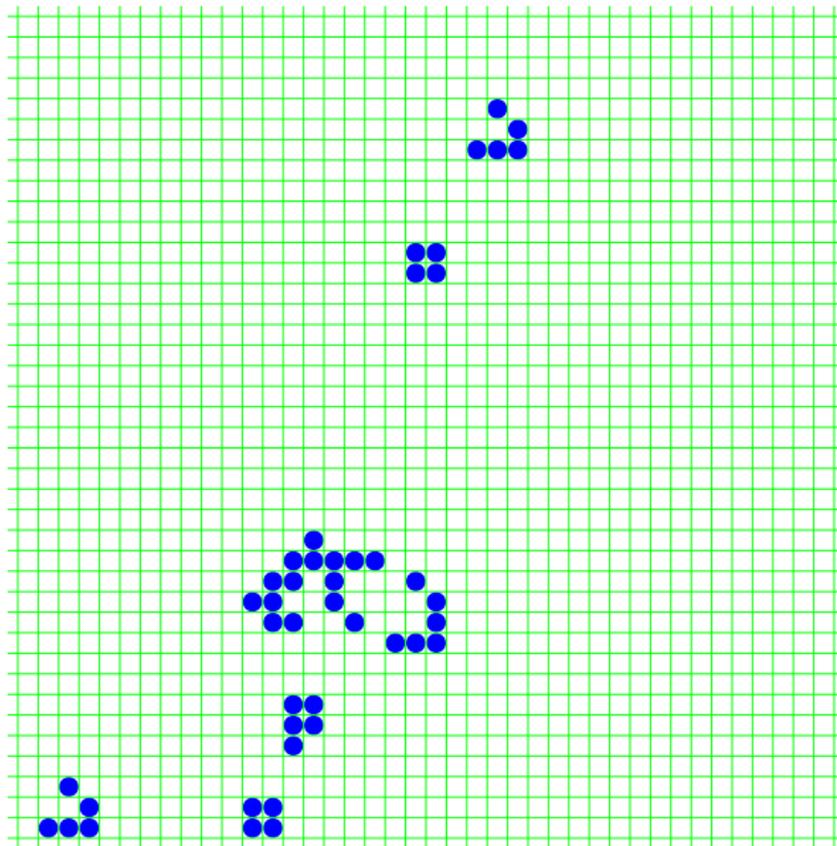
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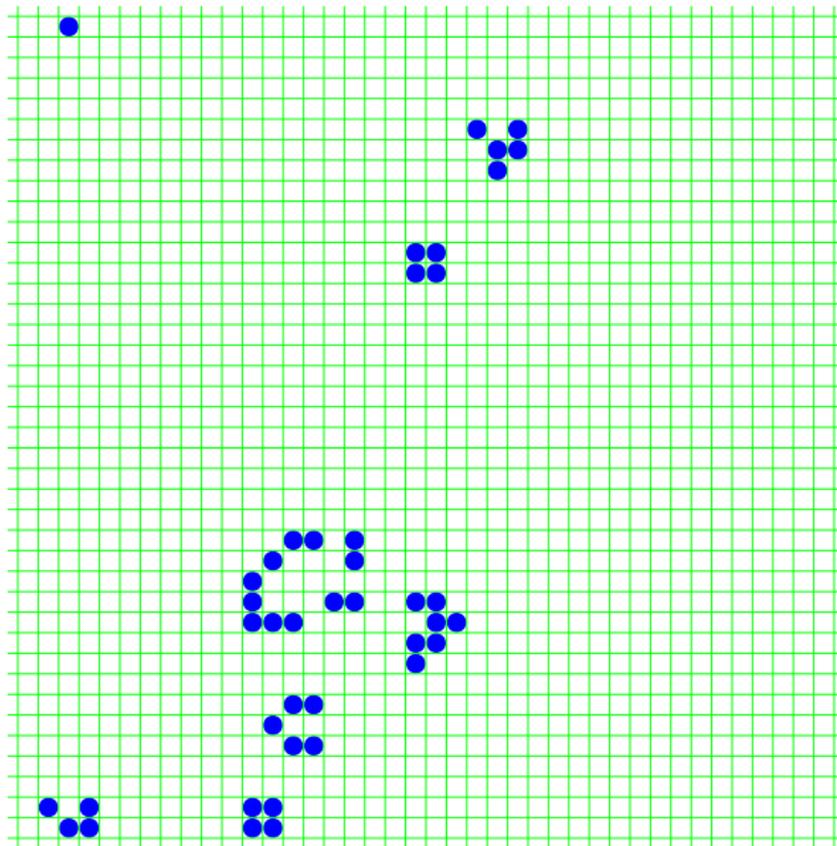
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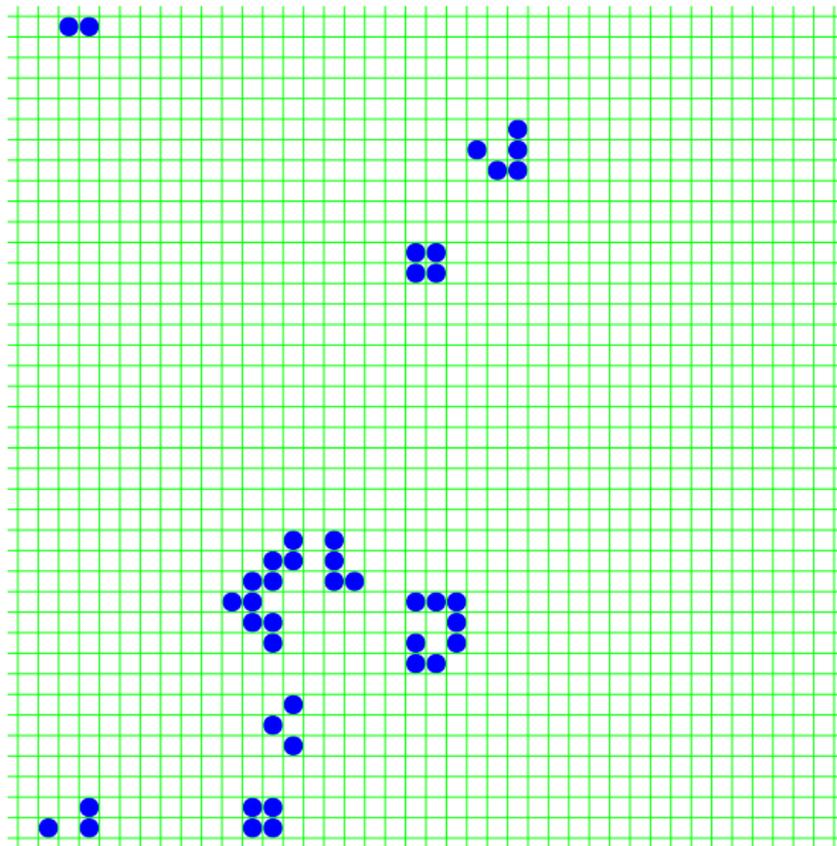
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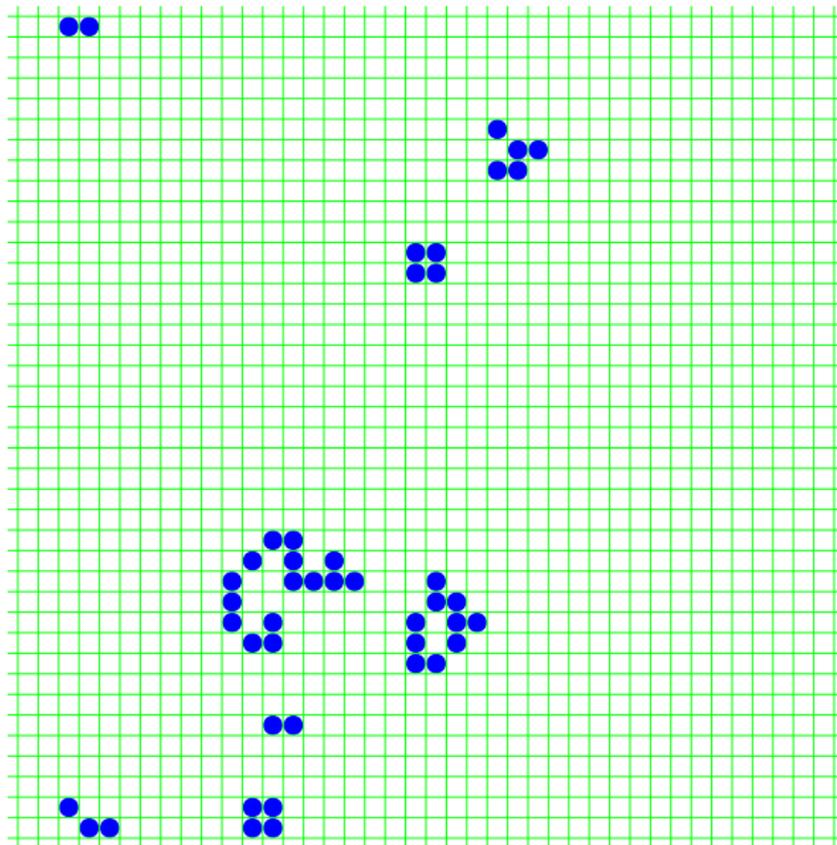
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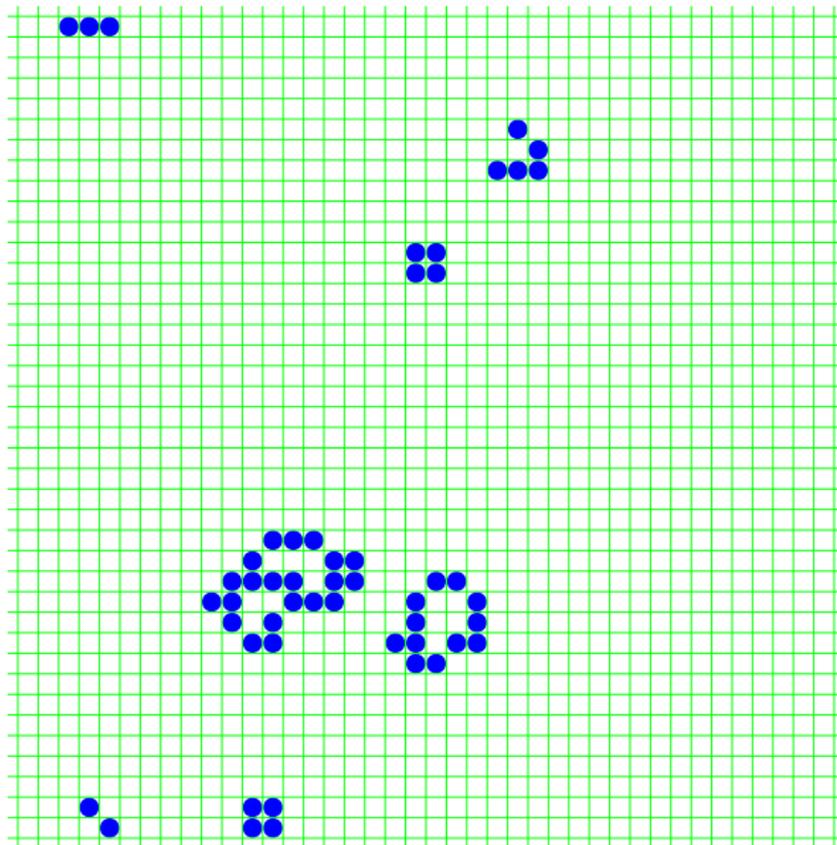
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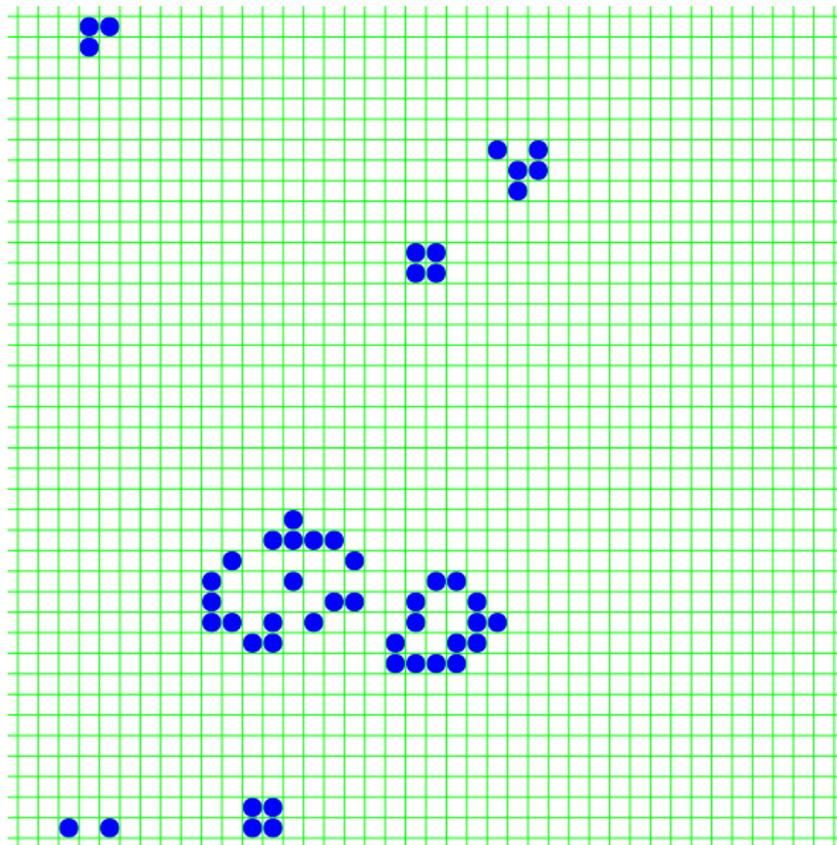
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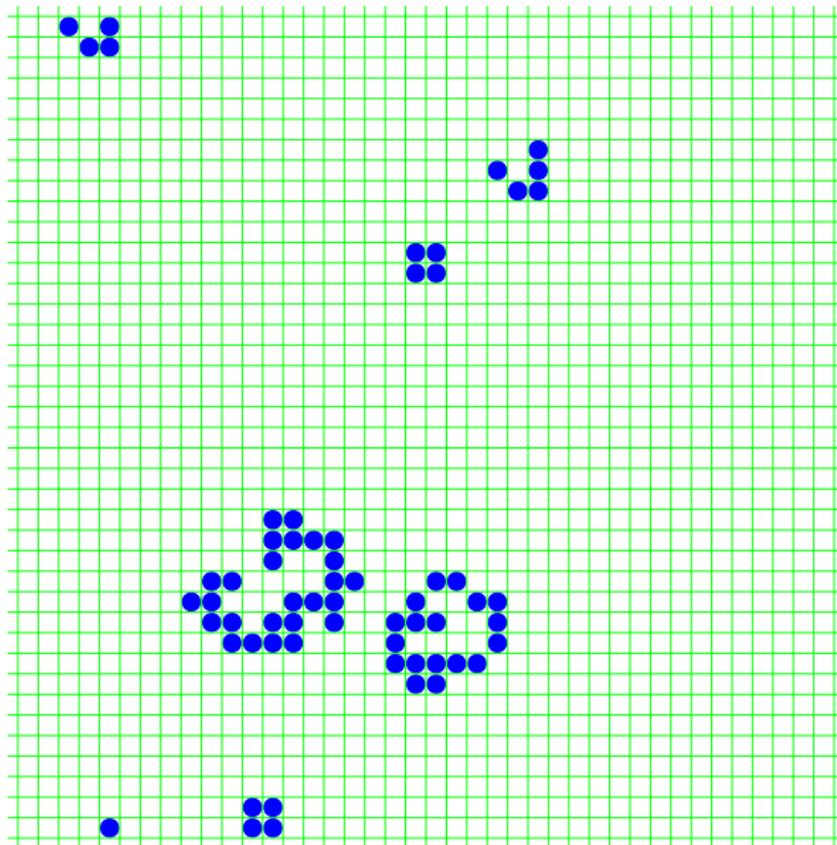
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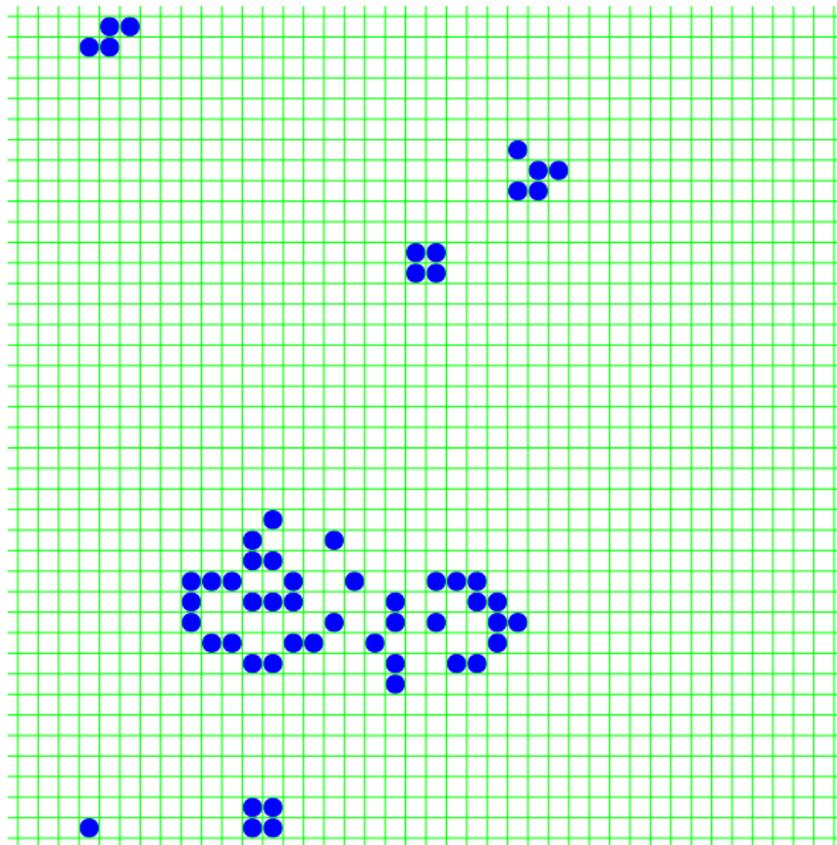
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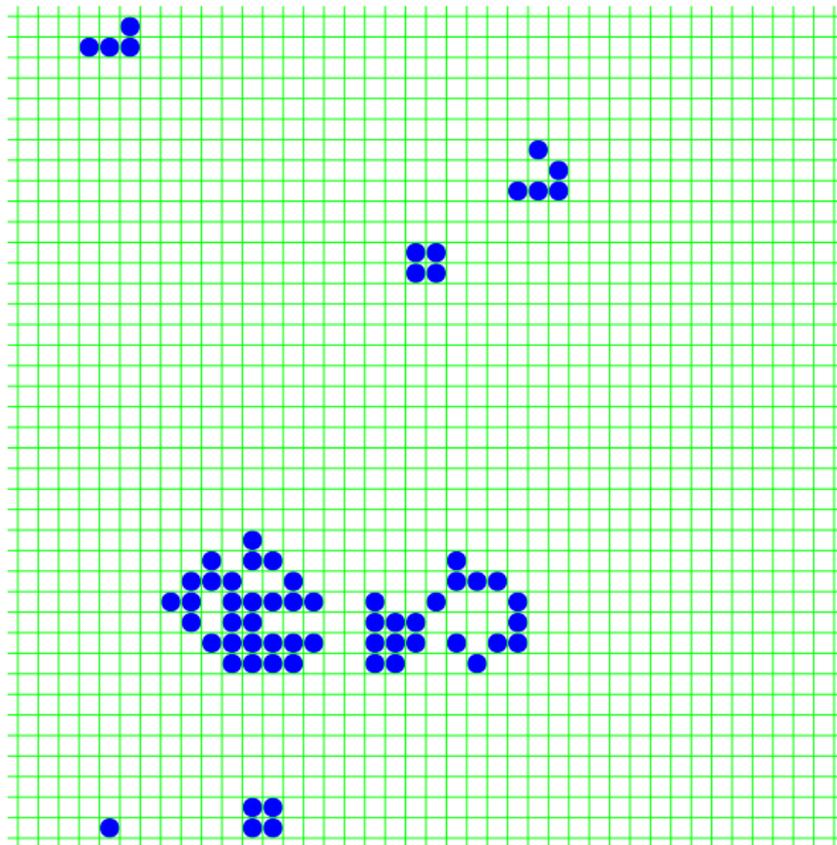
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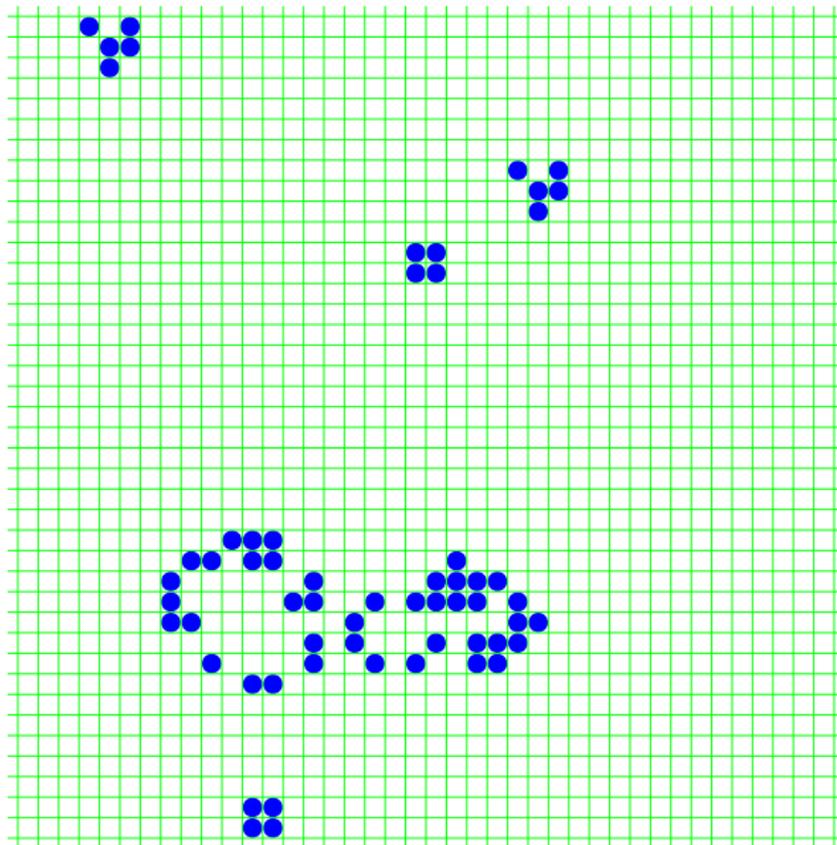
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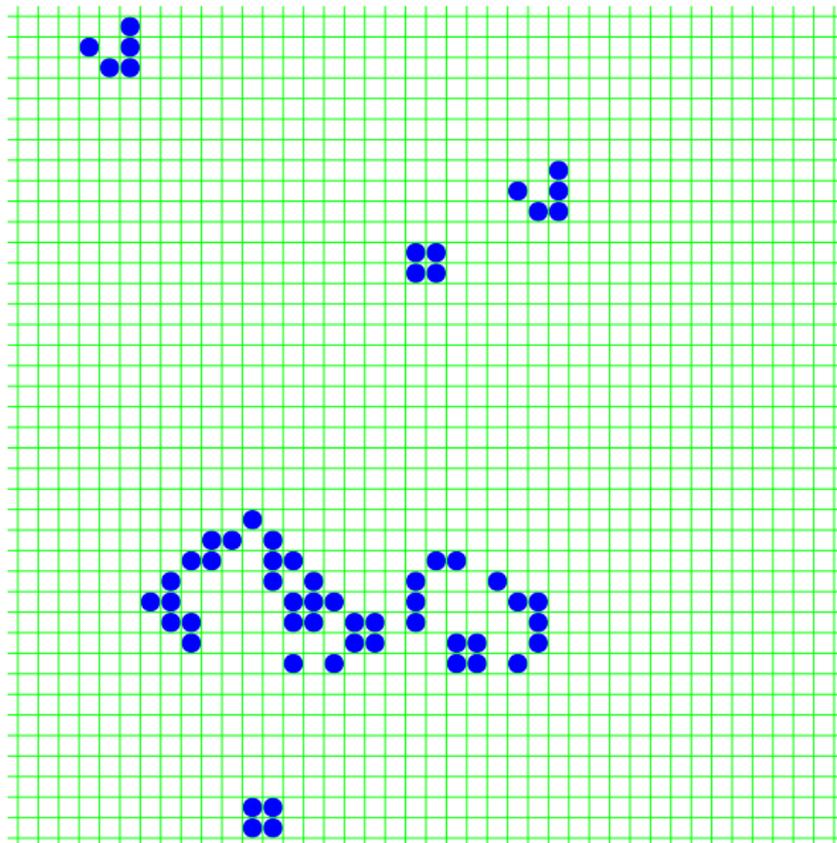
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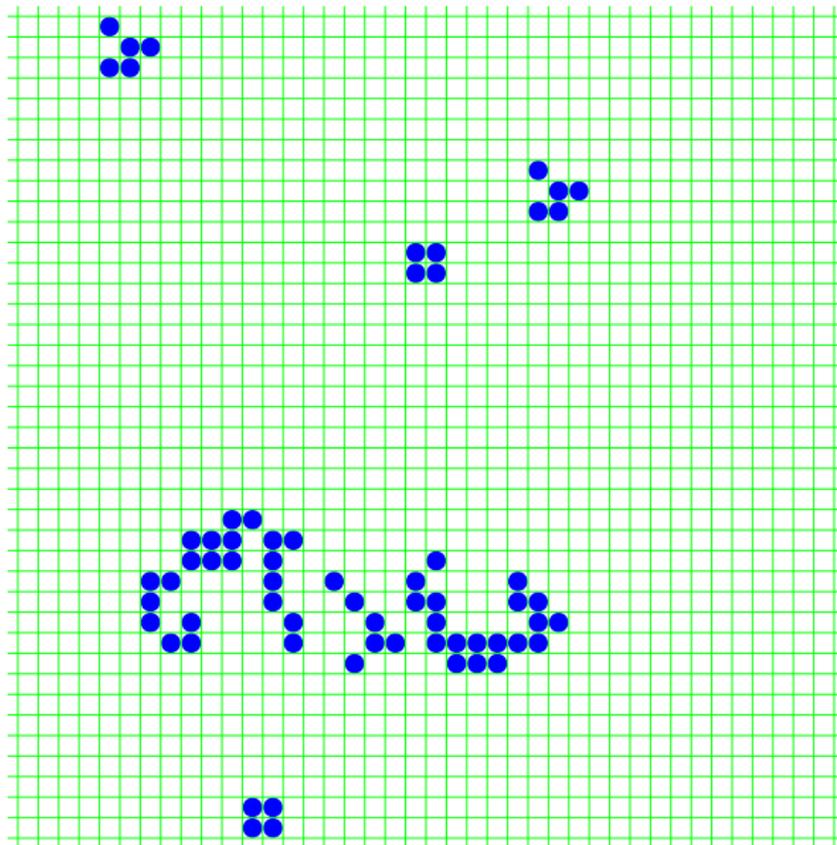
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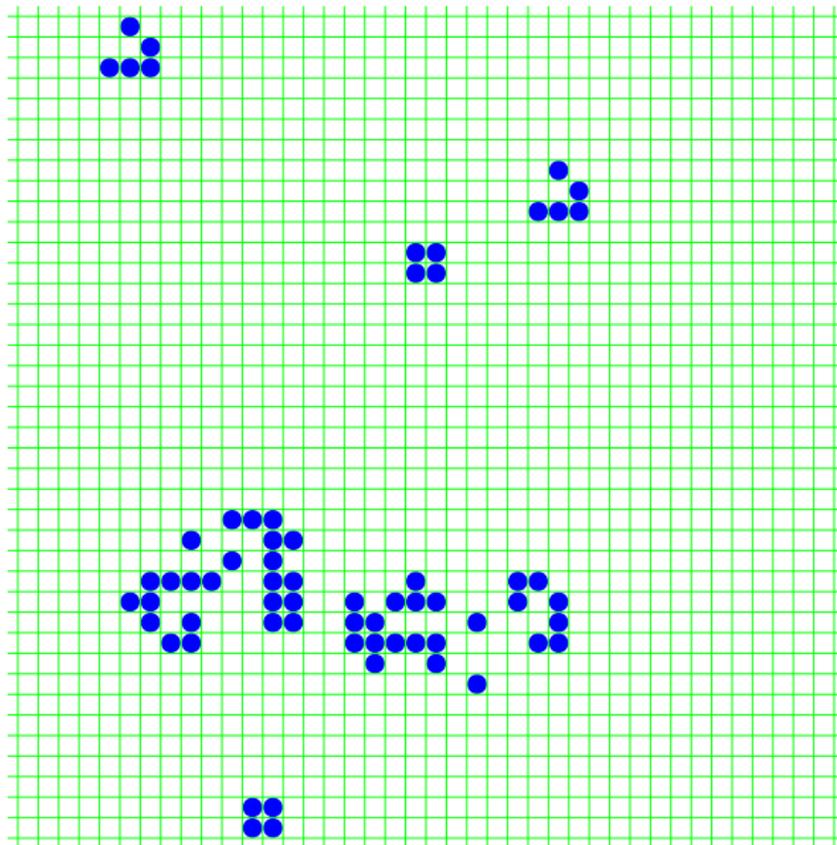
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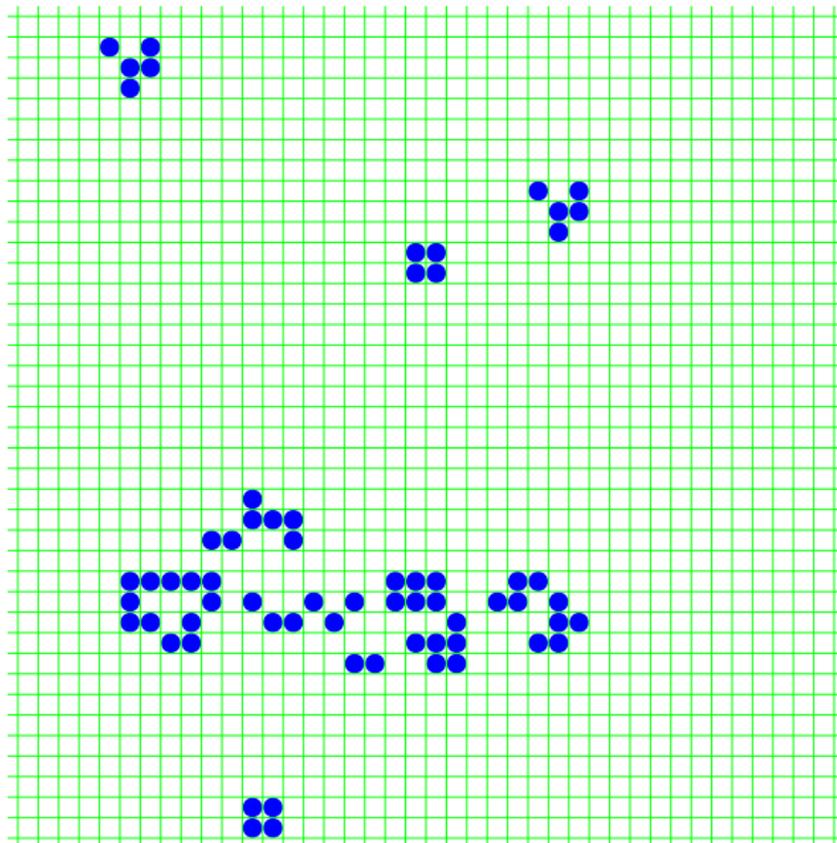
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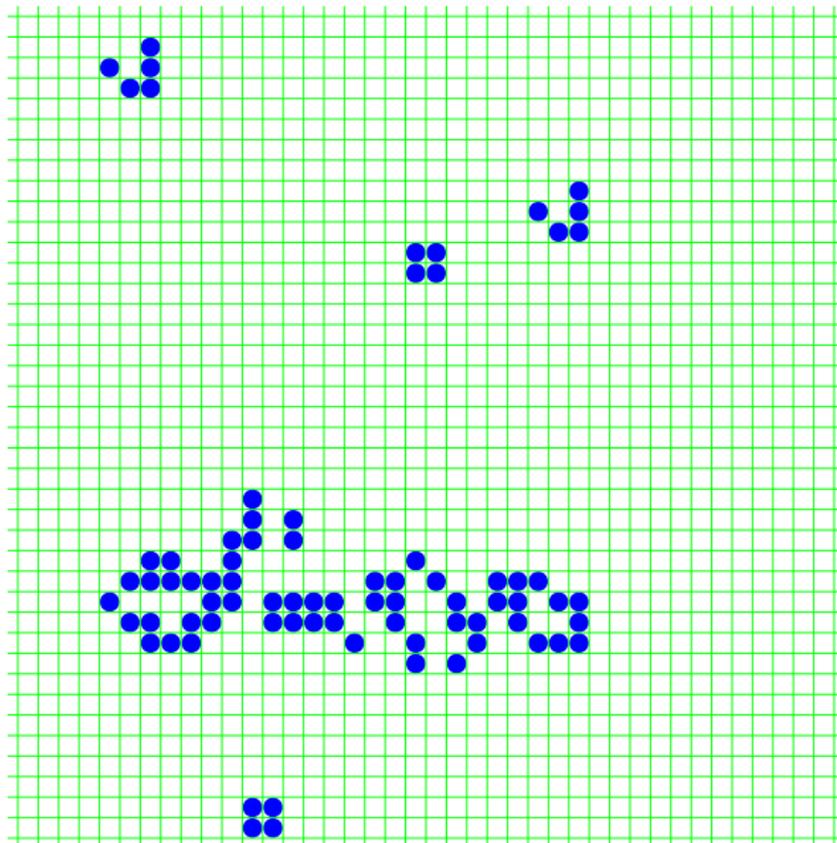
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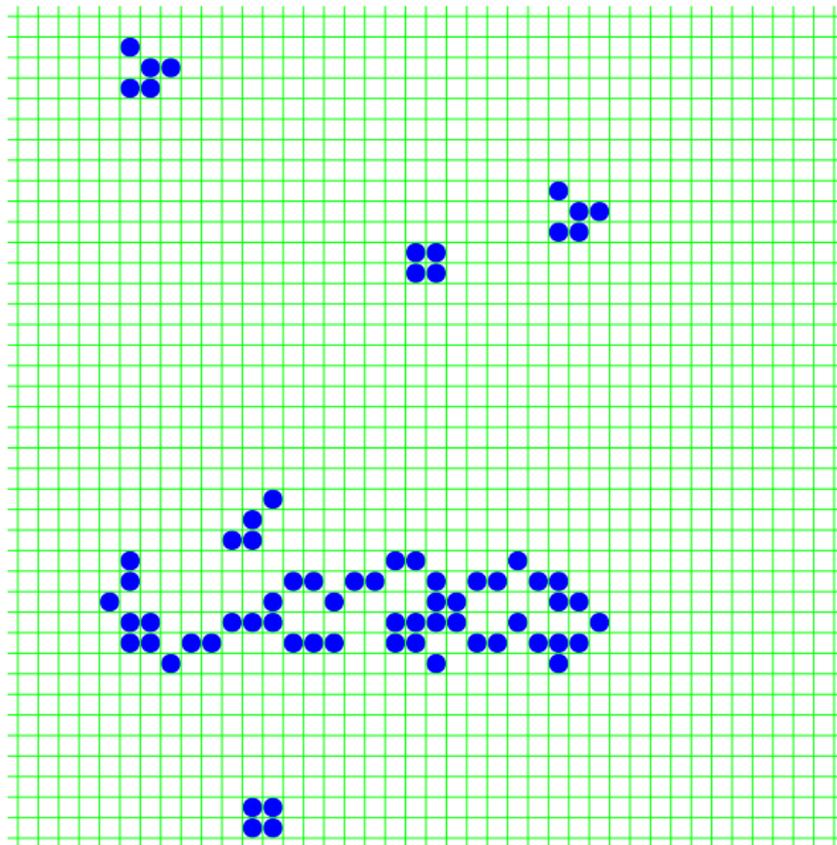
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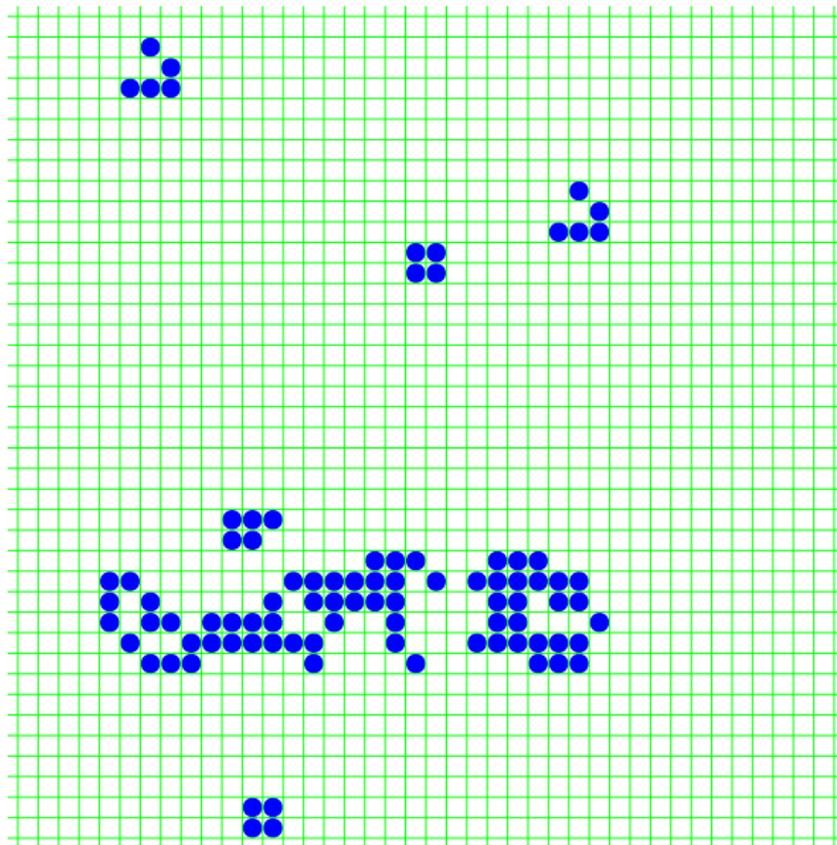
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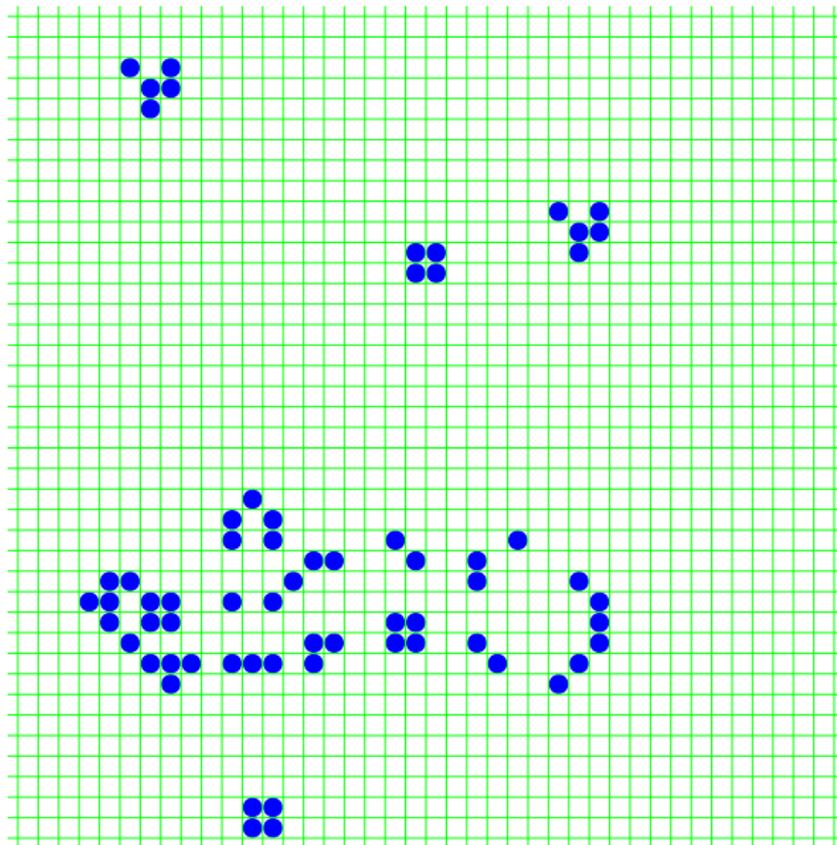
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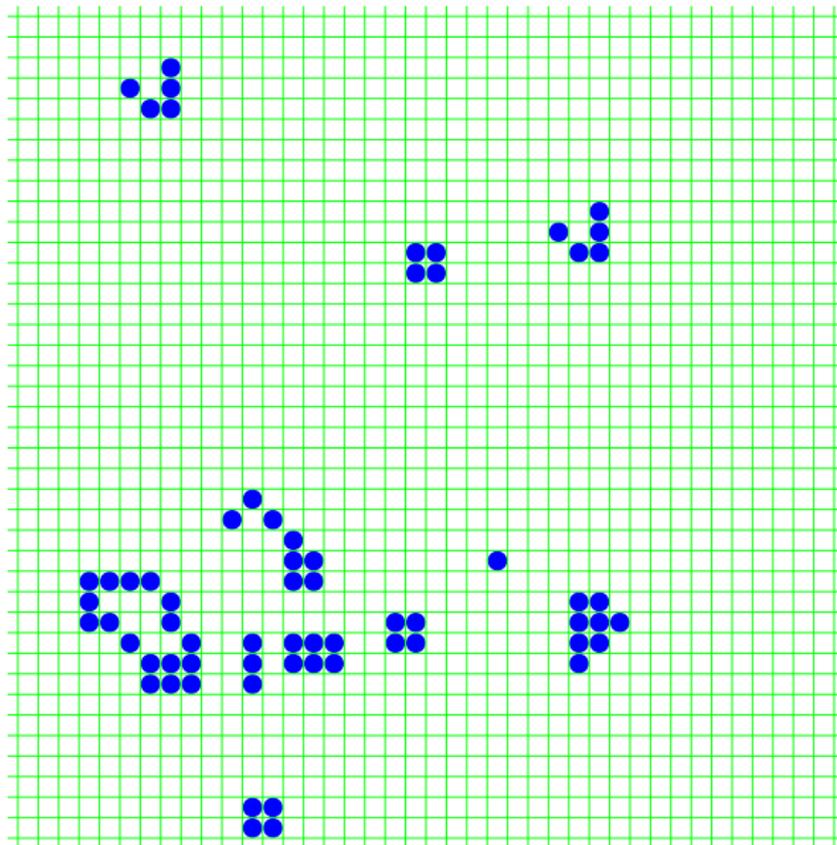
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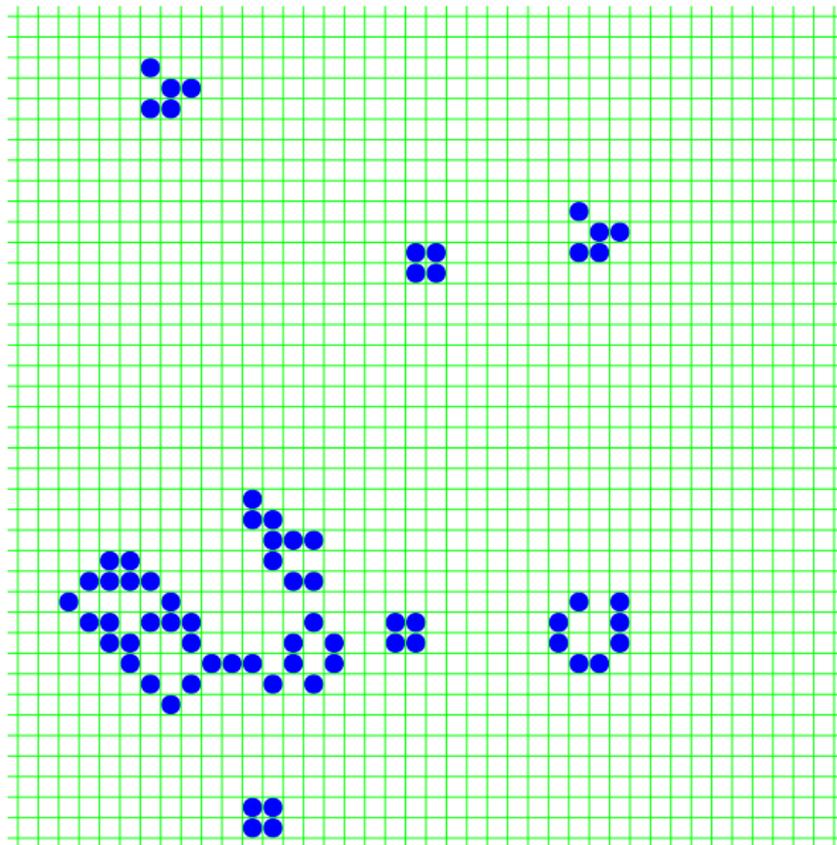
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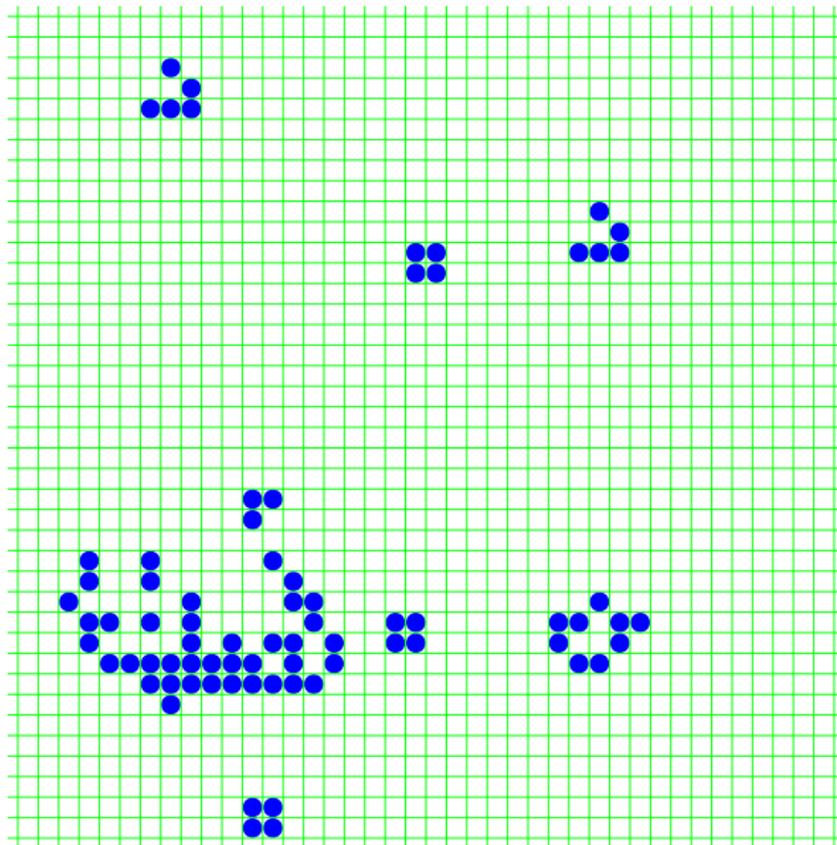
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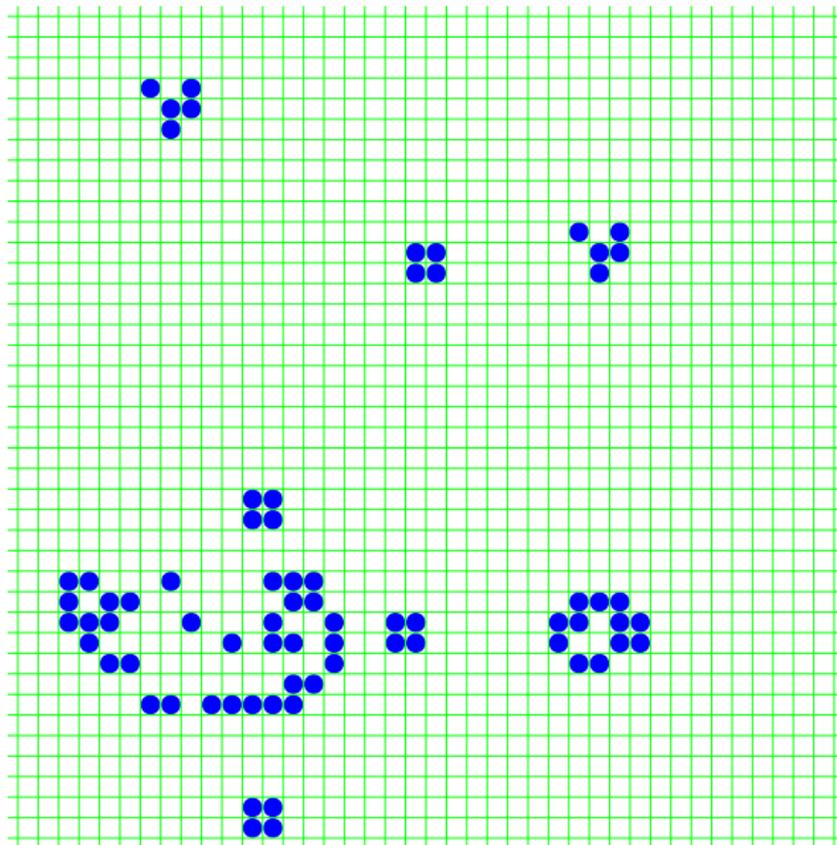
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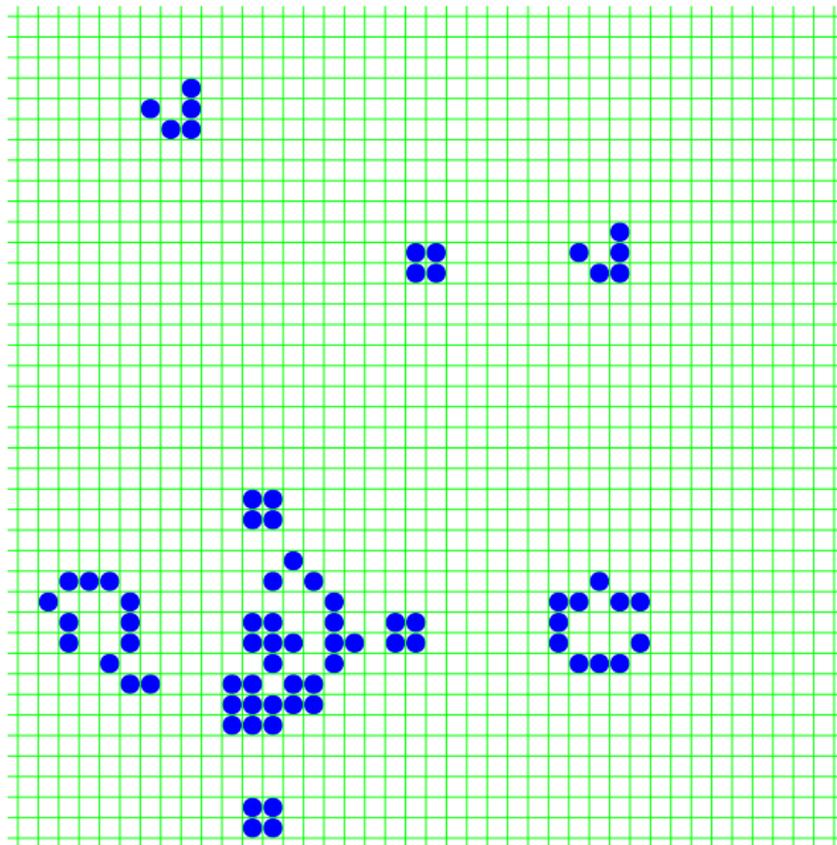
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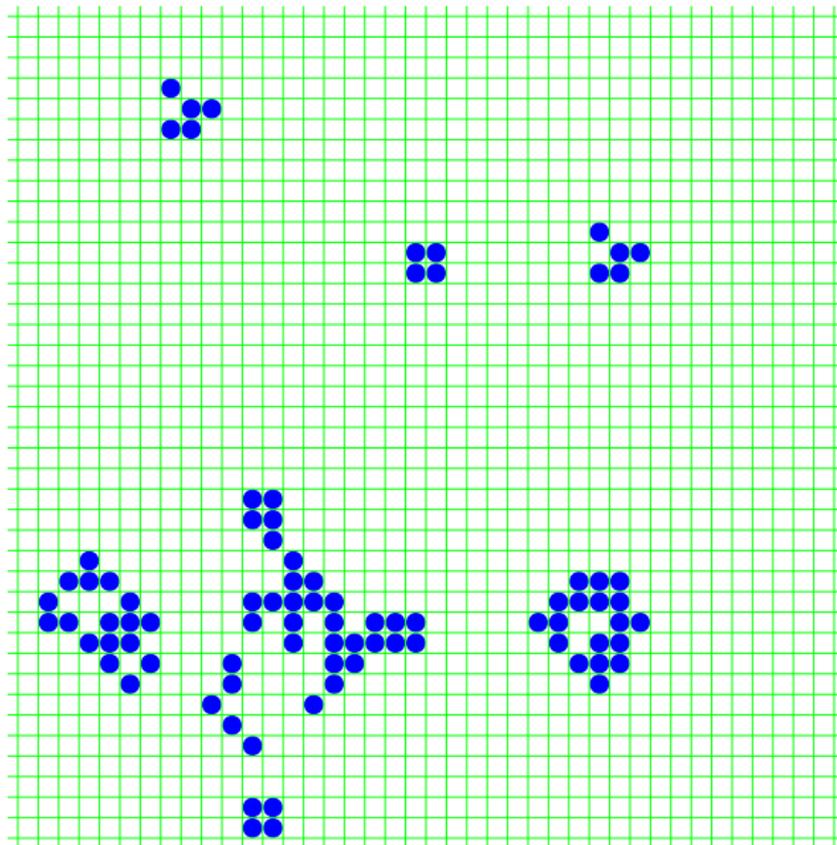
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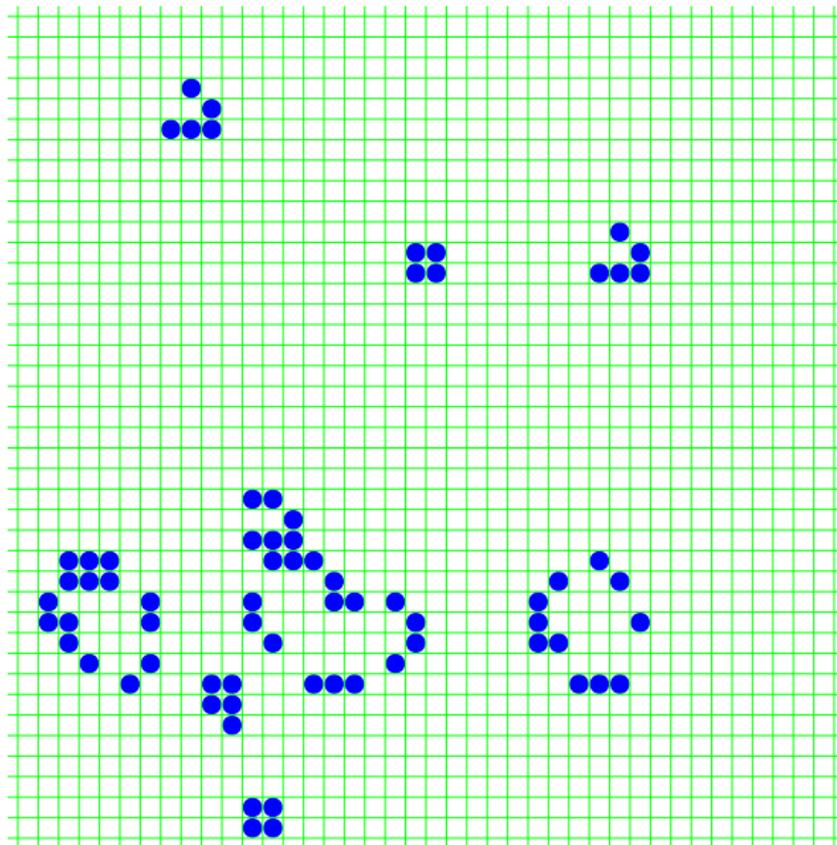
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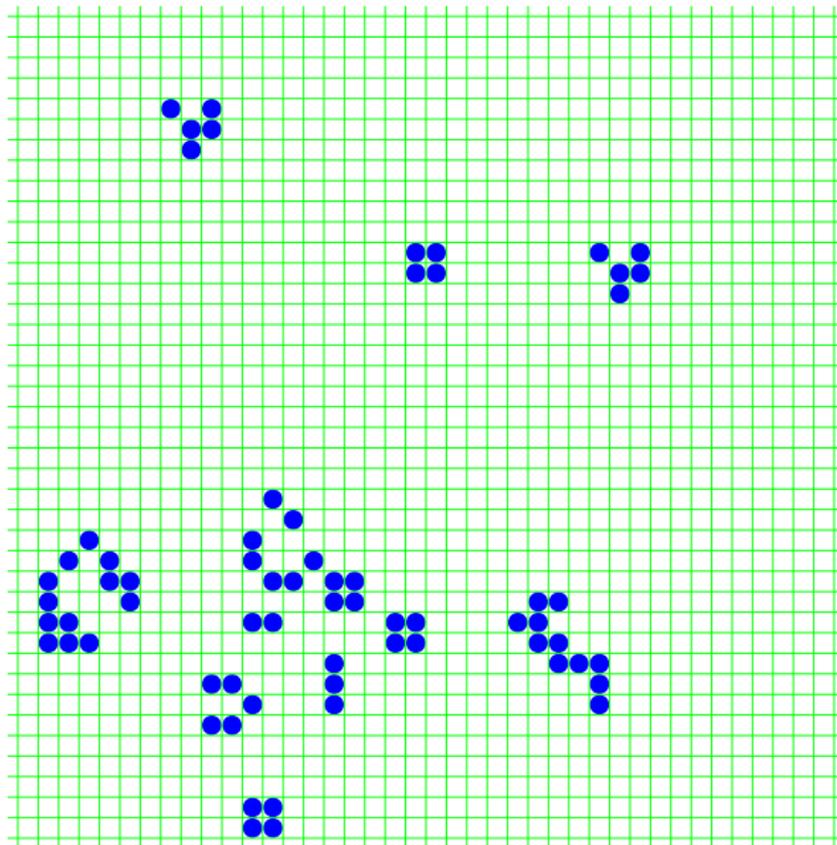
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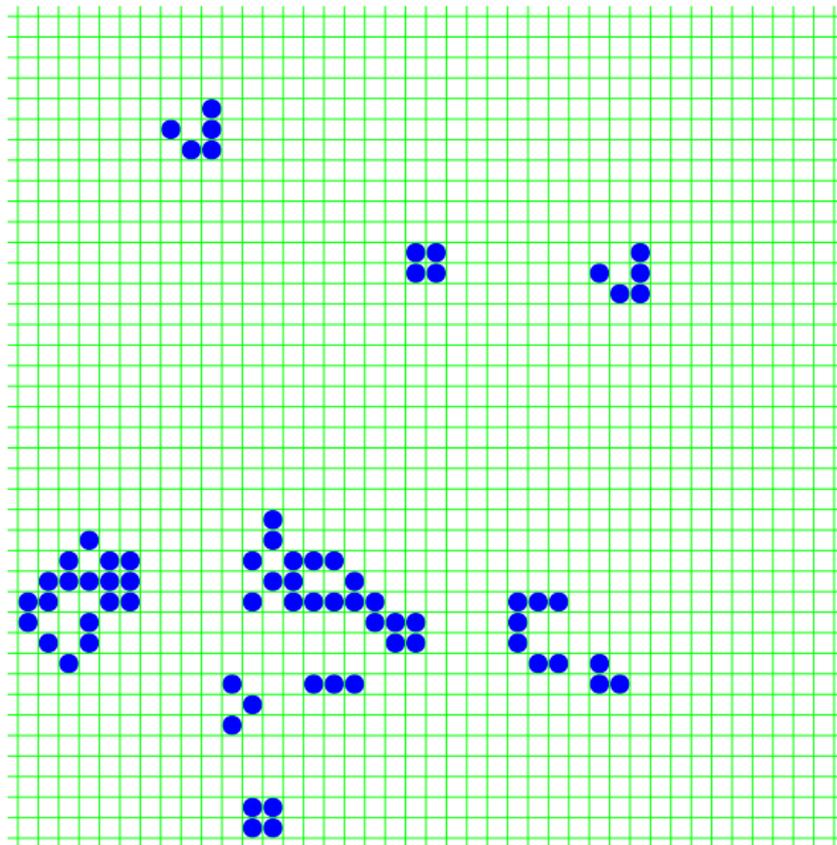
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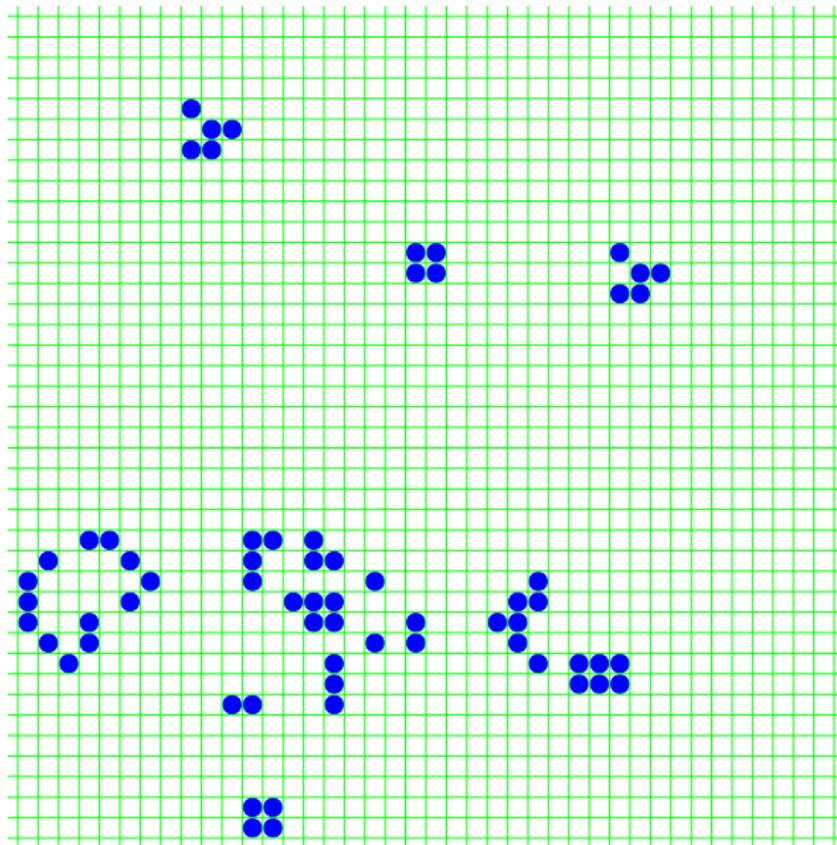
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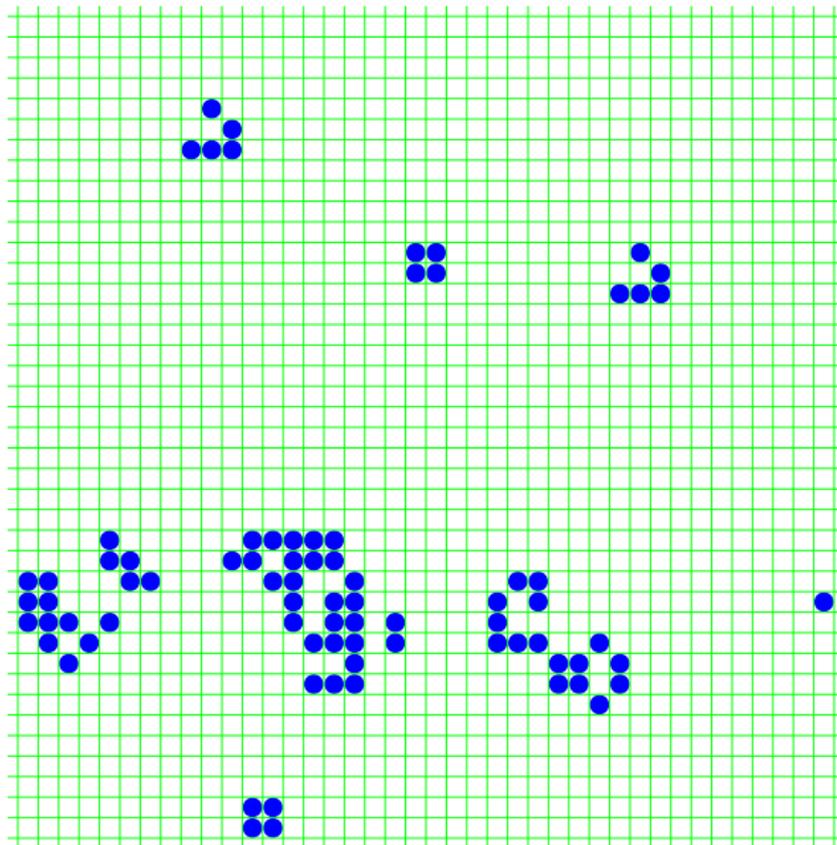
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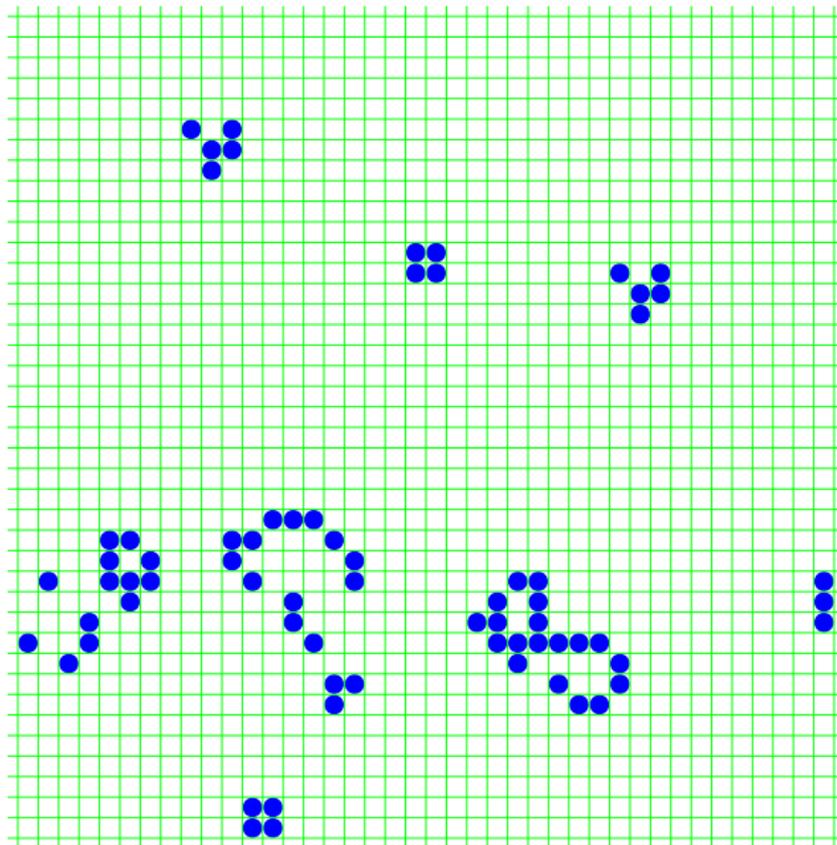
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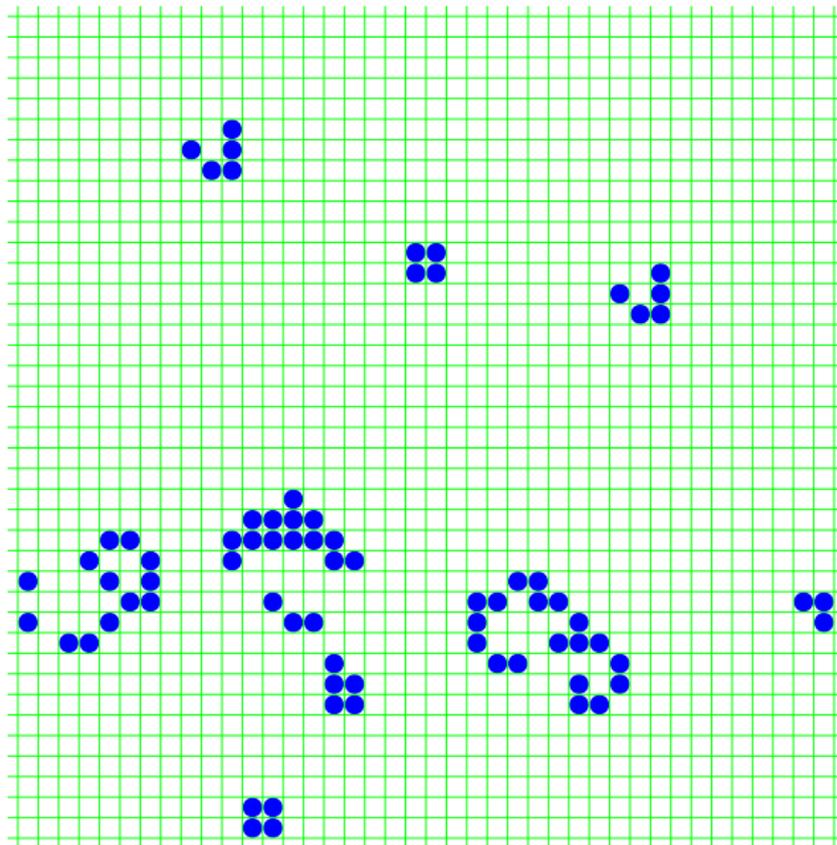
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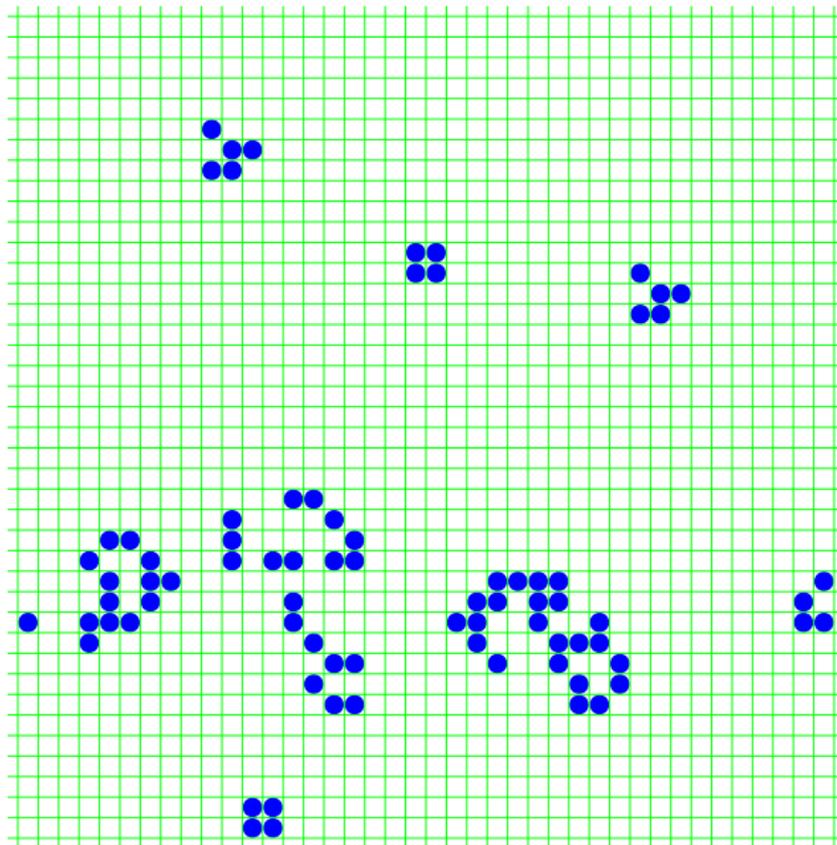
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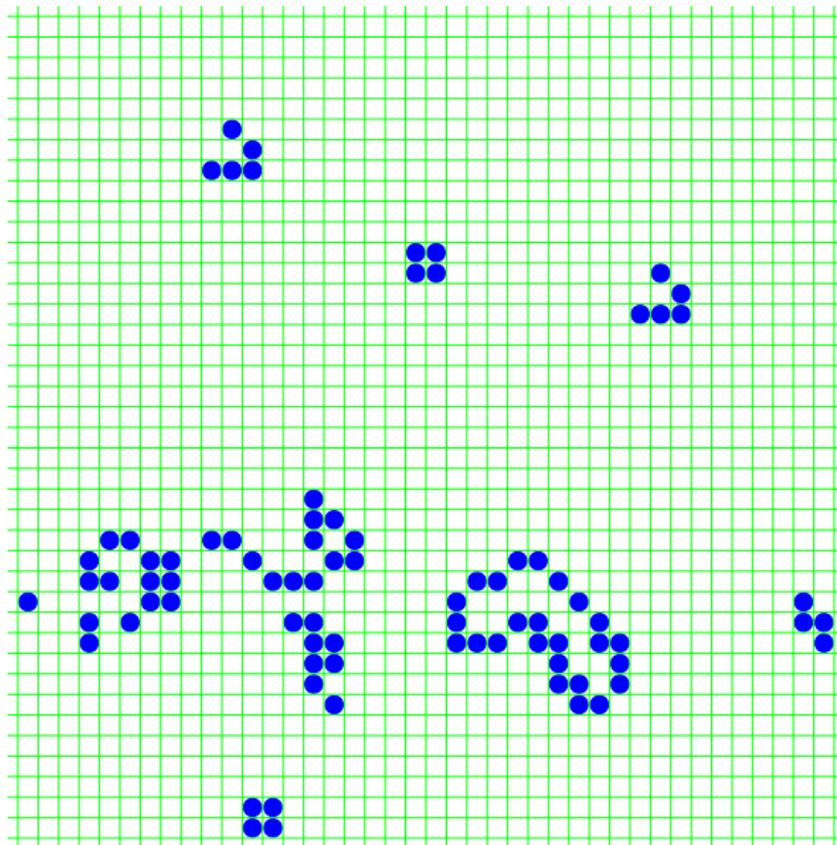
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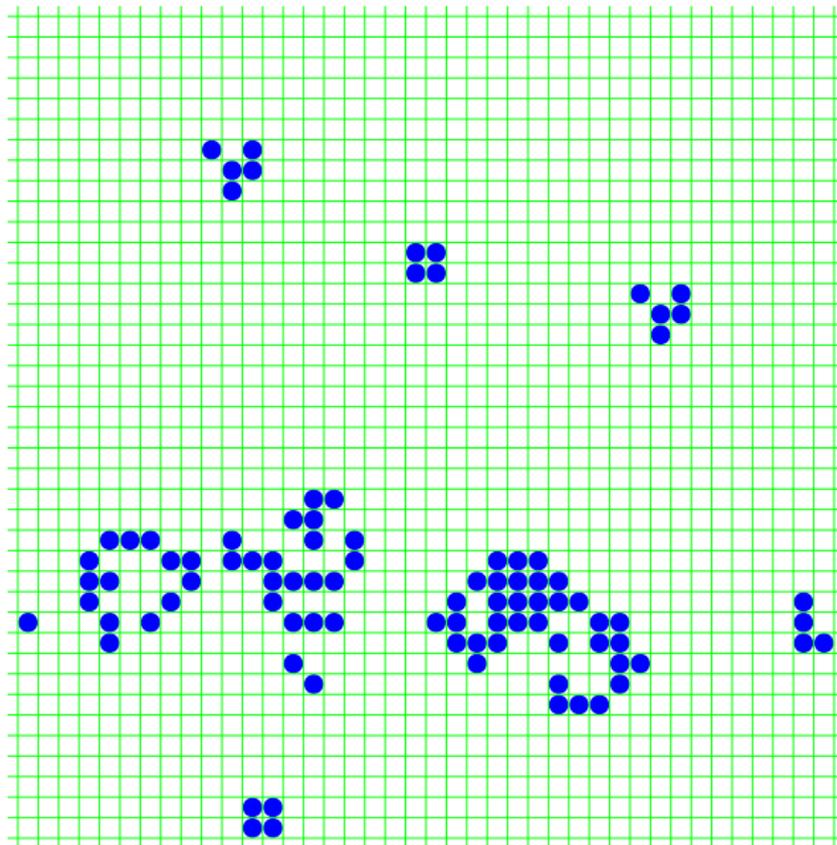
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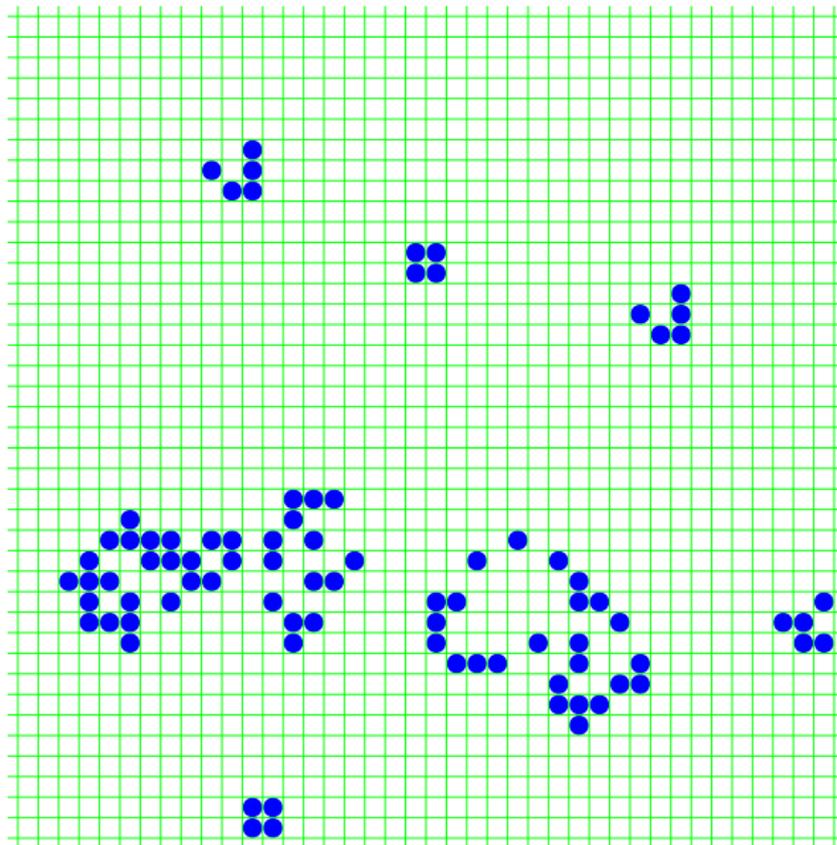
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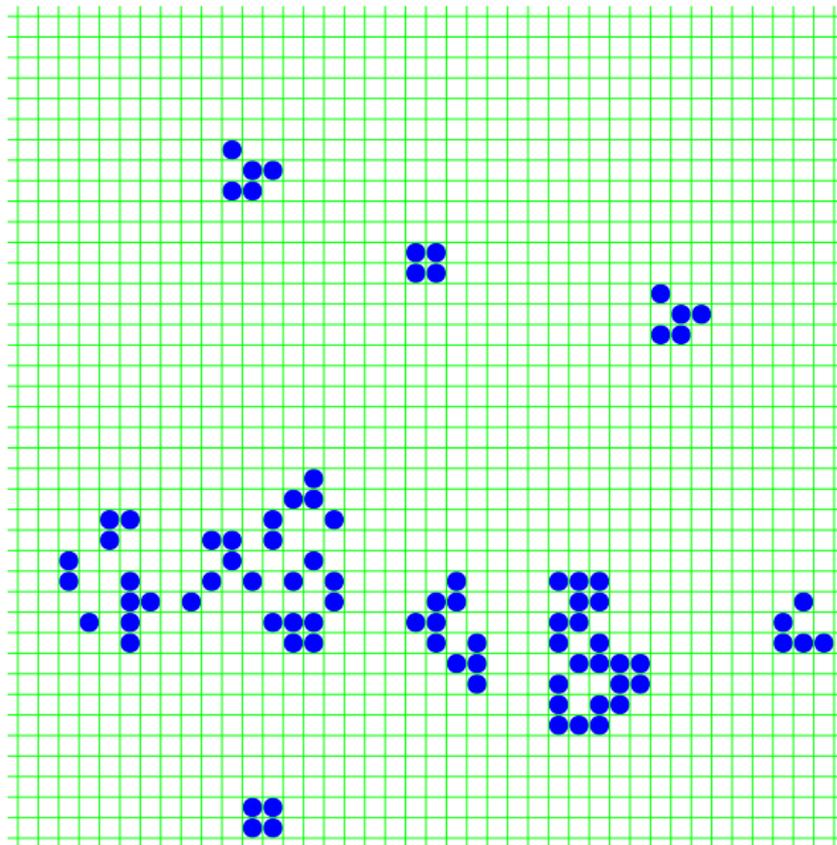
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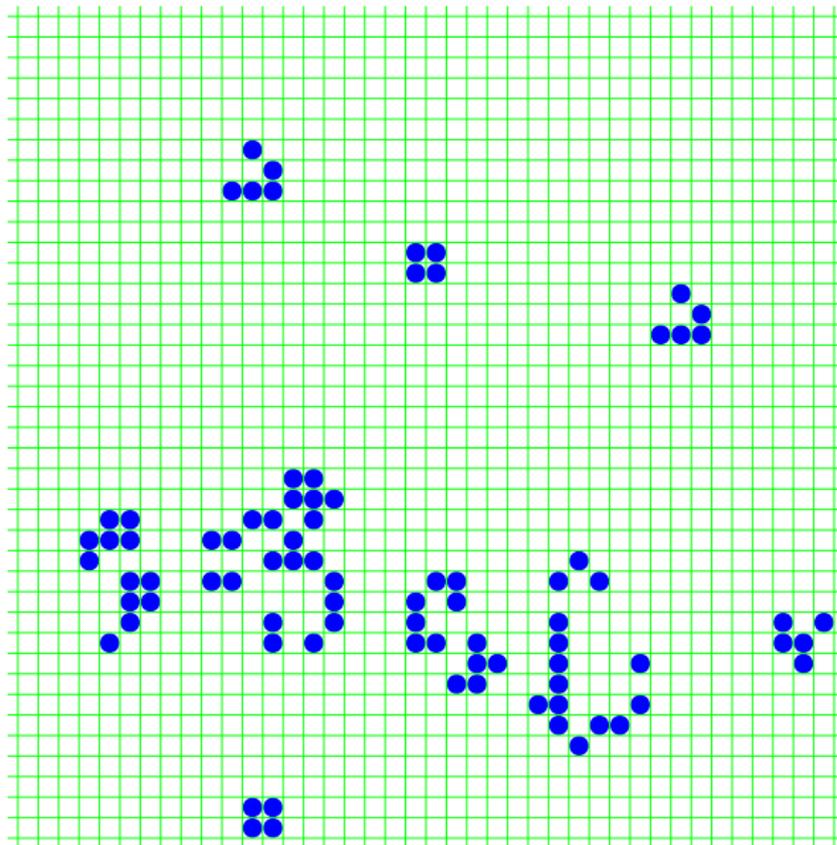
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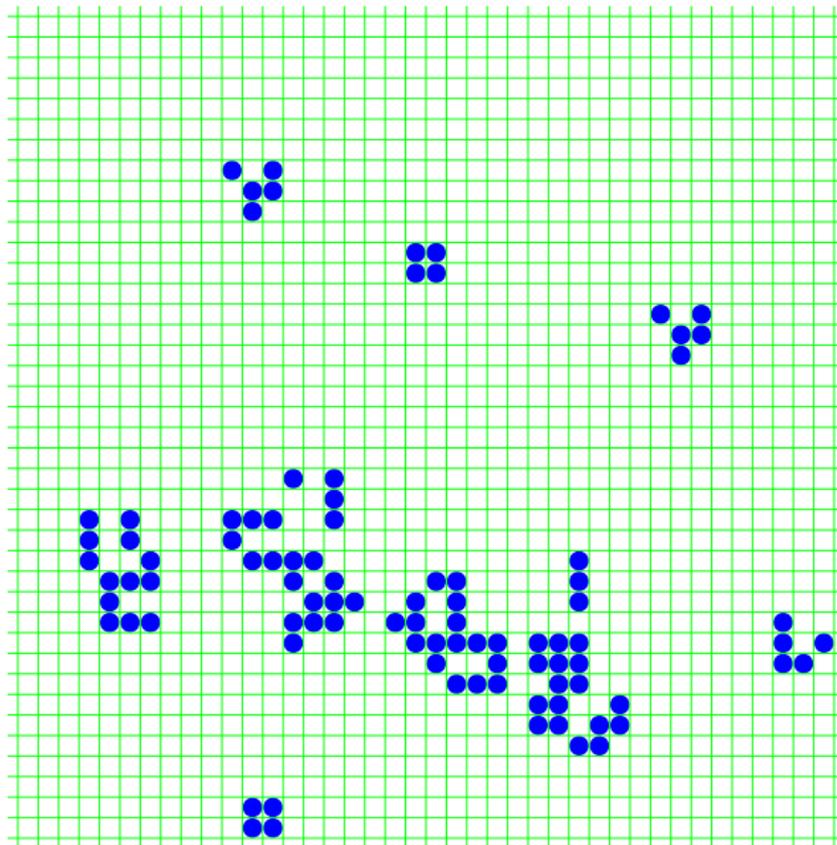
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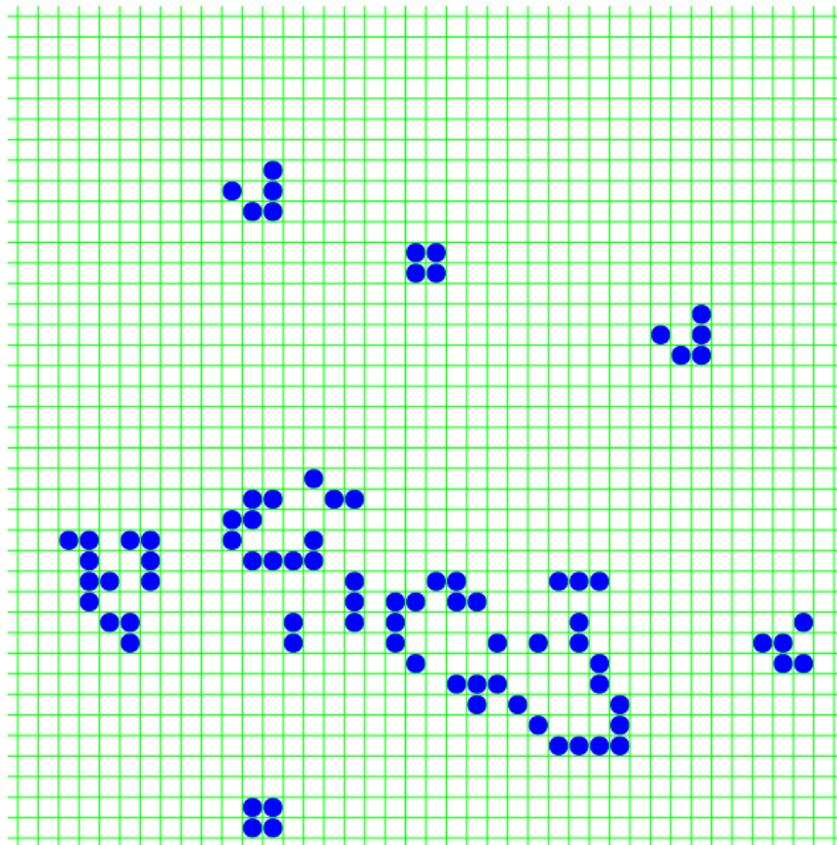
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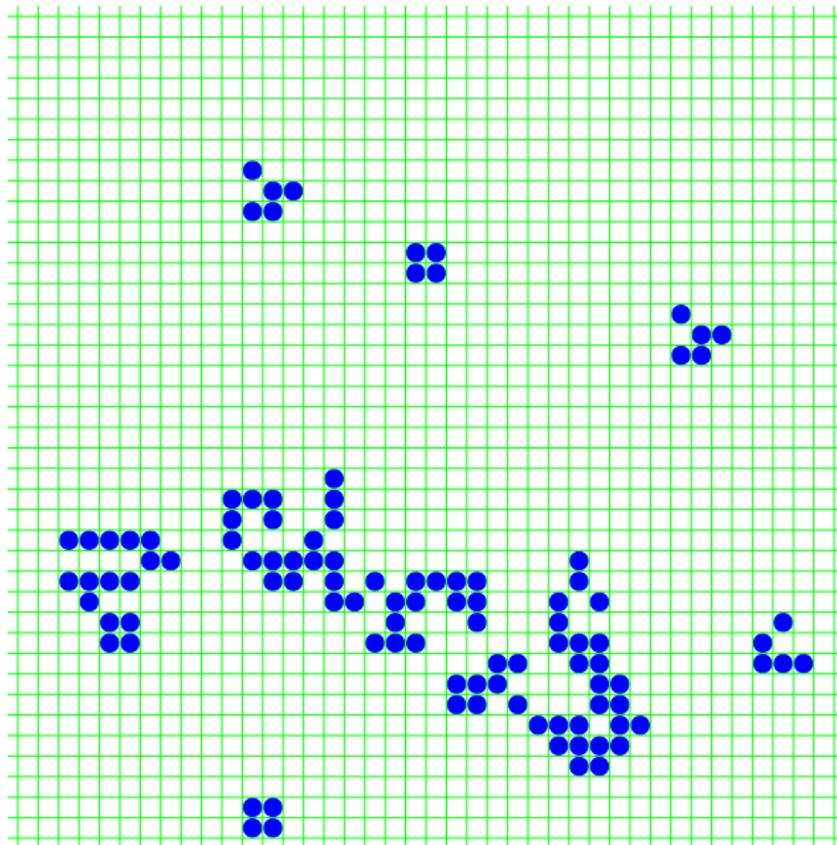
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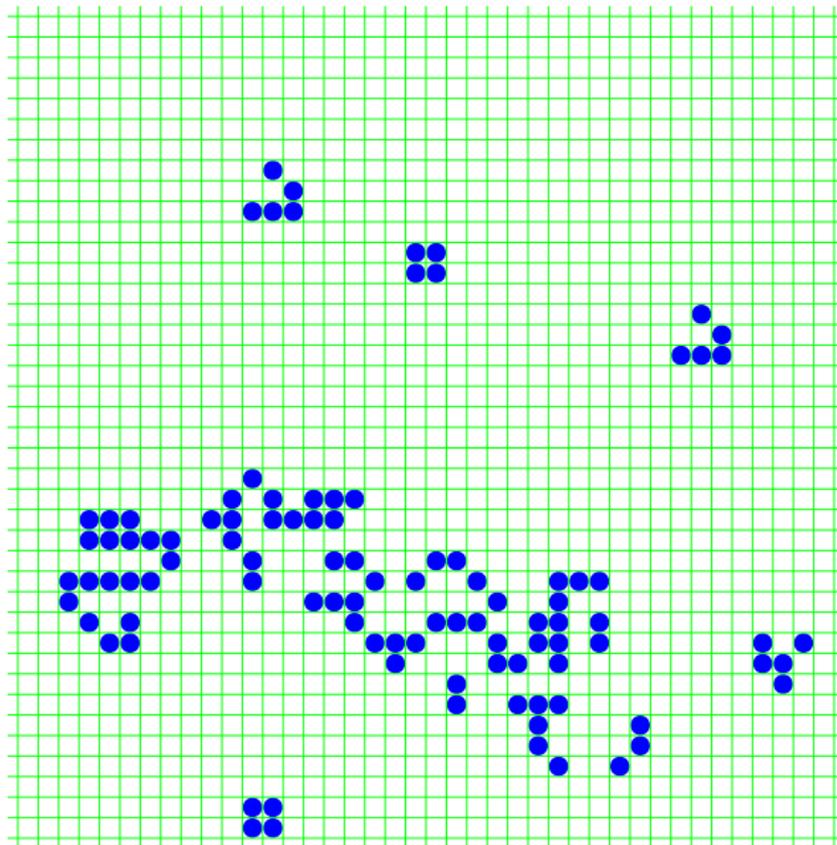
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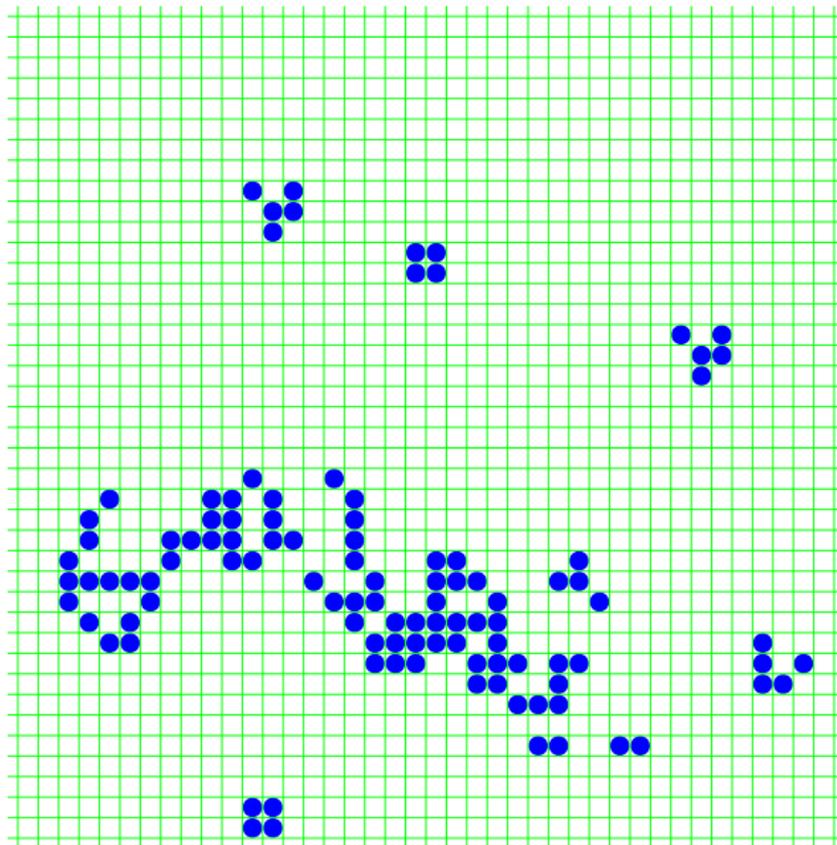
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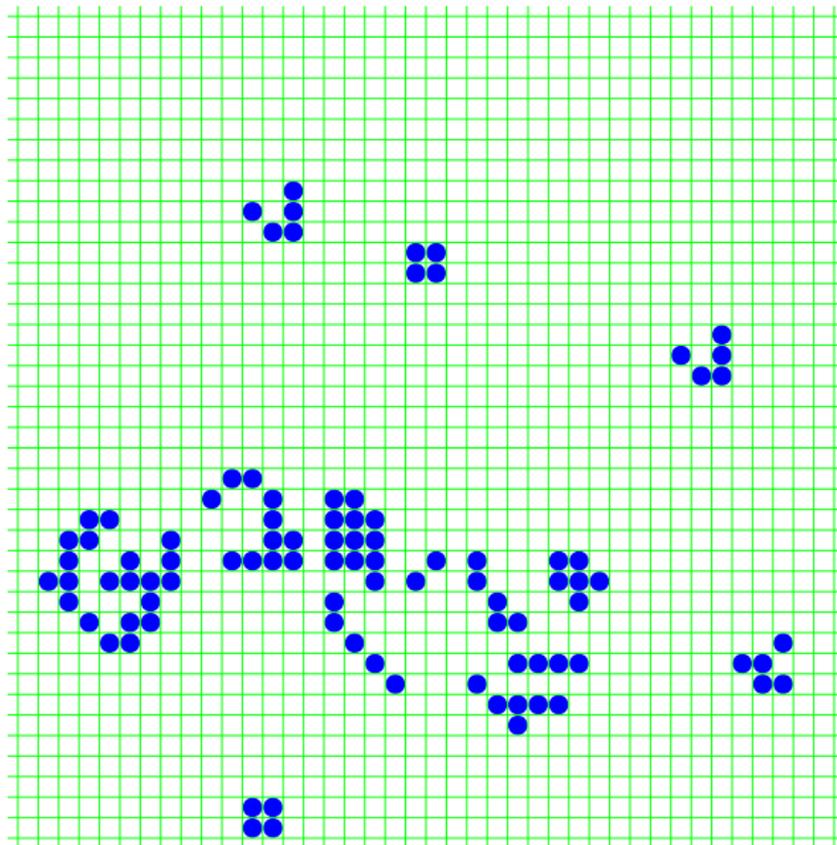
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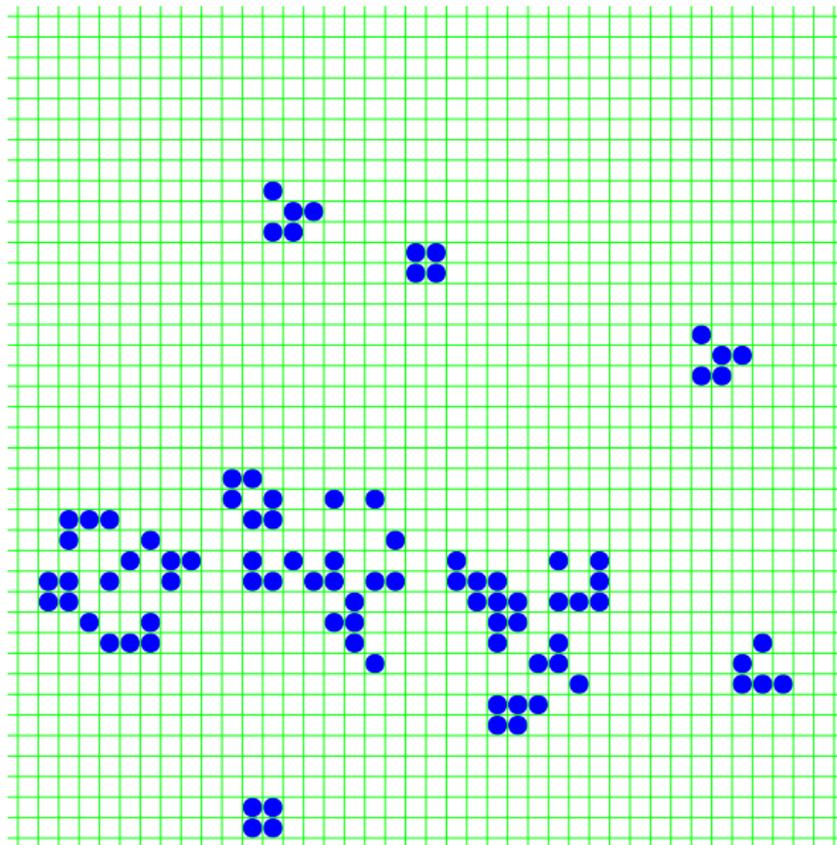
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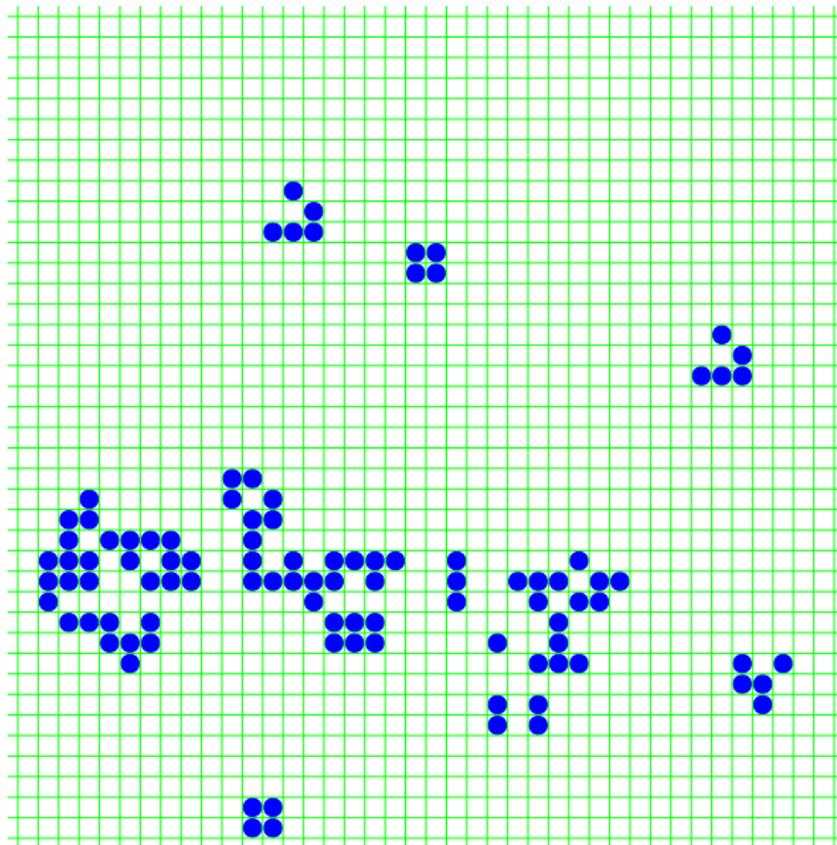
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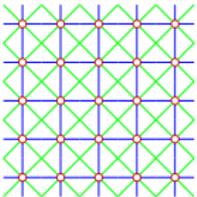
# Conway's Life. Typical Evolution Producing Gliders



# Conway's Life. Typical Evolution Producing Gliders



# Symmetries of Toric $N \times N$ Square Lattices $\Gamma_{N \times N}$

$\Gamma_{N \times N} =$ 

 has the **same** group  $G_{N \times N}$  in both **4-valent von Neumann**  and **8-valent Moore**  cases

**Principal case**  $N = 3, 5, 6, \dots, \infty$      $|G_{N \times N}| = 8N^2$      $\mathbf{T}^2$  is **normal**

$G_{N \times N} = \mathbf{T}^2 \rtimes \mathbf{D}_4$  — semidirect product of  $\mathbf{T}^2$  and  $\mathbf{D}_4$

$\mathbf{T}^2 = \mathbb{Z}_N \times \mathbb{Z}_N$  — translation group ( $\mathbb{Z}_\infty \equiv \mathbb{Z}$ )

$\mathbf{D}_4 = \mathbb{Z}_4 \rtimes \mathbb{Z}_2$  — dihedral group ( $\mathbb{Z}_4$  –  $90^\circ$  rotations,  $\mathbb{Z}_2$  – reflections)

Resembles Euclidean group  $\mathbf{E}_2 = (\mathbf{T}^2 = \mathbb{R} \times \mathbb{R}) \rtimes \mathbf{O}(2)$

**Exception:  $N = 4$**      $|G_{N \times N}| = 3 \times 8N^2$      $\mathbf{T}^2$  is **not normal**

normal closure of  $\mathbf{T}^2$

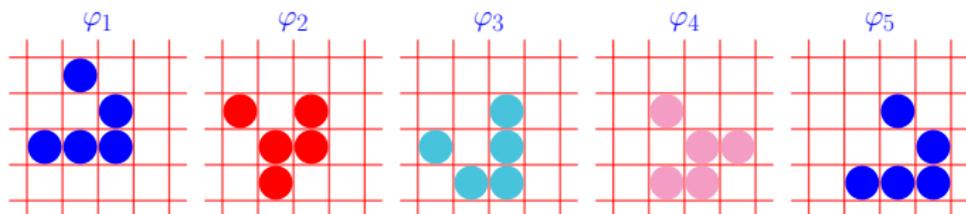
$G_{4 \times 4} = \overbrace{(((\mathbb{Z}_2 \times \mathbf{D}_4) \times \mathbb{Z}_2) \times \mathbb{Z}_3) \times \mathbb{Z}_2} \rtimes \mathbb{Z}_2$  (by GAP algorithm)

# Group Interpretation of “Glider”

Evolution operator = group action:  $\varphi_{t_b}(x) = A_{t_a t_b}(\varphi_{t_a}(x)) = \varphi_{t_a}(g_{t_a t_b}^{-1} x)$

One step diagonal shift

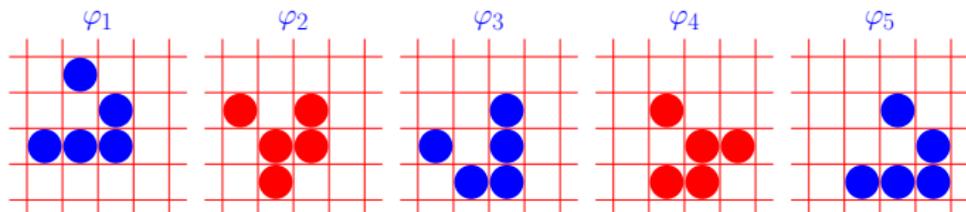
$$g_{15} \in \mathbf{T}^2$$



“Glider” over translation group  $\mathbf{T}^2$  is cycle in 4 orbits

One step downward shift  $\rightarrow$  90° clockwise rotation  $\rightarrow$  reflection in respect to vertical

$$g_{13} = g_{24} \in \mathbf{T}^2 \times \mathbf{D}_4$$



“Glider” over maximal symmetry group  $\mathbf{T}^2 \times \mathbf{D}_4$  is cycle in 2 orbits

# Two Examples of Trivalent Cellular Automata with Symmetric Local Rules

- **Rule 86** =  $\overbrace{01101010}^{\text{Bit string}} \sim \overbrace{B123/S0}^{\text{"Birth/Survival" lists}} \sim \overbrace{x'_4 = x_4 + \sigma_3 + \sigma_2 + \sigma_1}^{\text{Polynomial over } \mathbb{F}_2}$
- **Rule 23** =  $11101000 \sim B012/S0 \sim x'_4 = x_4(\sigma_2 + \sigma_1) + \sigma_3 + 1$

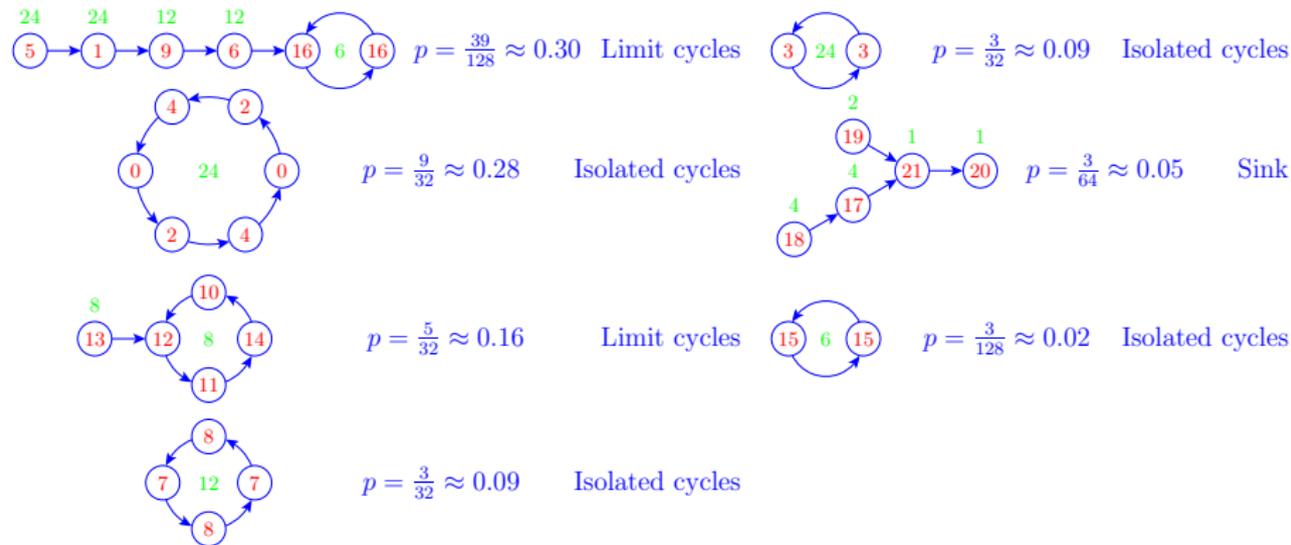
Rule 23 is BW symmetric

Notations:  $\sigma_1 = x_1 + x_2 + x_3$ ,  $\sigma_2 = x_1x_2 + x_1x_3 + x_2x_3$ ,  $\sigma_3 = x_1x_2x_3$

# Rule 86 $\sim$ B123/S0 $\sim x'_4 = x_4 + \sigma_3 + \sigma_2 + \sigma_1$

## Phase Portrait Modulo Aut ("Hexahedron")

Weight of structure  $p = \frac{\text{basin size}}{\text{number of states}}$

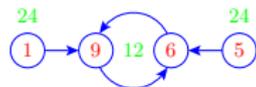


**Most cycles are spaceships — 36 of 45 or 80%**

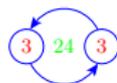
# BW Symmetric Rule 23 $\sim$ B012/S0

$$\sim X'_4 = X_4 (\sigma_2 + \sigma_1) + \sigma_3 + 1$$

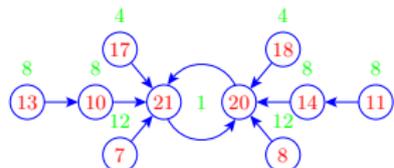
Phase Portrait Modulo Aut ("Hexahedron")



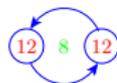
$$p = \frac{9}{32} \approx 0.28 \quad \text{Limit cycles}$$



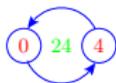
$$p = \frac{3}{32} \approx 0.09 \quad \text{Isolated cycles}$$



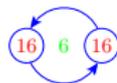
$$p = \frac{33}{128} \approx 0.26 \quad \text{Limit cycles}$$



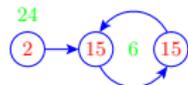
$$p = \frac{1}{32} \approx 0.03 \quad \text{Isolated cycles}$$



$$p = \frac{3}{16} \approx 0.19 \quad \text{Isolated cycles}$$



$$p = \frac{3}{128} \approx 0.02 \quad \text{Isolated cycles}$$



$$p = \frac{15}{128} \approx 0.12 \quad \text{Limit cycles}$$



$$p = \frac{3}{128} \approx 0.02 \quad \text{Gardens of Eden}$$

**22** spaceships of **61** cycles or about **36%**

# Quantum Gravity Difficulties:

- Irreversibility of Gravity: information loss (=dissipation) at horizon of black hole
- Reversibility and Unitarity of standard Quantum Mechanics

G. 't Hooft's approach to reconcile Gravity with Quantum Mechanics:

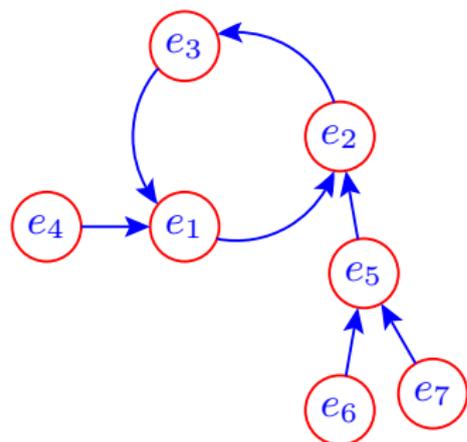
- 1 Discrete degrees of freedom at Planck distance scales
- 2 States of these degrees of freedom form primordial basis of Hilbert space with (nonunitary) evolution
- 3 Equivalence classes of states: two states are equivalent if they evolve into the same state after some lapse of time
- 4 Equivalence classes form basis of Hilbert space with unitary evolution governed by time-reversible Schrödinger equation

In our terminology this corresponds to transition to limit cycles: after short time of evolution limit cycles become physically indistinguishable from reversible isolated cycles

# Primordial and Unitary Hilbert Spaces

Primordial basis

$e_1, e_2, e_3, e_4, e_5, e_6, e_7$



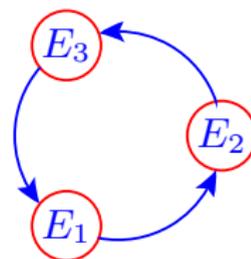
Equivalence classes

$$E_1 = \{e_1, e_5, e_6, e_7\}$$

$$E_2 = \{e_2\}$$

$$E_3 = \{e_3, e_4\}$$

form unitary basis



Why irreversibility is not visible: time **out of cycle**  $\approx 10^{-44}$  sec (Planck time),  
time **on cycle** potentially  $\infty$ , minimal time fixed in today's experiments  
 $\approx 10^{-18}$  sec  $\approx 10^{26}$  Planck units

# Search For Reversibility

Reversibility is **rare** property tending to **disappear** with growth of complexity of lattice

Two rules trivially reversible on **all lattices**

- **85**  $\sim$  B0123/S  $\sim x'_4 = x_4 + 1$
- **170**  $\sim$  B/S0123  $\sim x'_4 = x_4$

**Tetrahedron**, 6 additional reversible rules

- **43**  $\sim$  B0/S012  $\sim x'_4 = x_4 (\sigma_2 + \sigma_1) + \sigma_3 + \sigma_2 + \sigma_1 + 1$
- **51**  $\sim$  B02/S02  $\sim x'_4 = \sigma_1 + 1$
- **77**  $\sim$  B013/S1  $\sim x'_4 = x_4 (\sigma_2 + \sigma_1 + 1) + \sigma_3 + \sigma_2 + 1$
- **178**  $\sim$  B2/S023  $\sim x'_4 = x_4 (\sigma_2 + \sigma_1 + 1) + \sigma_3 + \sigma_2$
- **204**  $\sim$  B13/S13  $\sim x'_4 = \sigma_1$
- **212**  $\sim$  B123/S3  $\sim x'_4 = x_4 (\sigma_2 + \sigma_1) + \sigma_3 + \sigma_2 + \sigma_1$

**Cube**, 2 additional reversible rules

- **51**  $\sim$  B02/S02  $\sim x'_4 = \sigma_1 + 1$
- **204**  $\sim$  B13/S13  $\sim x'_4 = \sigma_1$

**Dodecahedron** and **Graphene 6 $\times$ 4**, **no** additional reversible rules

# Mesososcopic Lattice Models

- **Non-deterministic** dynamical system — transition from a state to any other state is possible with some probability
- **Markov chain** is typical example
- **Lattice models** are special instances of Markov chains
- **Stationary distributions** of these Markov chains is subject of statistical mechanics
- **Mesososcopic systems** — too large for detailed microscopic description but too small for classical thermodynamics
- **Mesoscop**y studies nuclei, atomic clusters, nanotechnological structures, multi-star systems etc.

# Canonical and Microcanonical Ensembles

Gibbs canonical ensemble with canonical partition function

$$Z = \sum_{\sigma \in \Sigma} e^{-E_{\sigma}/k_B T}$$

— main tool of conventional statistical mechanics — being essentially asymptotic concept based on “thermodynamic limit” approximation can not be applied to mesoscopic systems

Instead more fundamental microcanonical ensemble

with entropy formula

$$S_E = k_B \ln \Omega_E$$

or, equivalently, with microcanonical partition function

$$\Omega_E = e^{S_E/k_B}$$

# Symmetry Approach To Mesoscopic Lattice Models

is based on exact enumeration of group orbits of microstates

## Advantages

- Statistical studies are based on simplifying assumptions, it is important to control these assumptions by exact computation, wherever possible.
- Exact computation might reveal subtle details in behavior of systems.

## Example: Ising model

- Vertex values:  $s_i \in Q = \{-1, 1\}$
- Hamiltonian: 
$$H = -J \sum_{(i,j)} s_i s_j - B \sum_i s_i$$

# Microcanonical Partition Function

## Ising Model On Dodecahedron

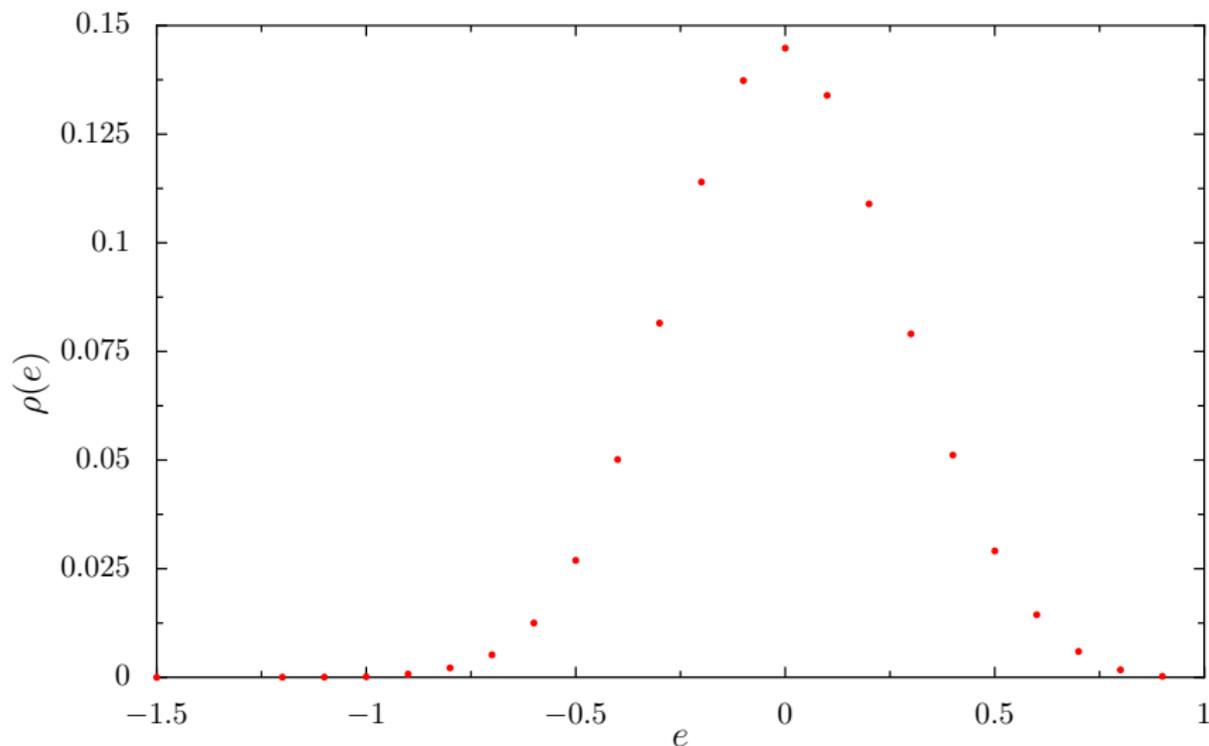


Figure: Density of states  $\rho(e) = \Omega_E/\Omega$  vs. energy per vertex  $e = E/|V(\Gamma)|$

# Magnetization

## Ising Model On Dodecahedron

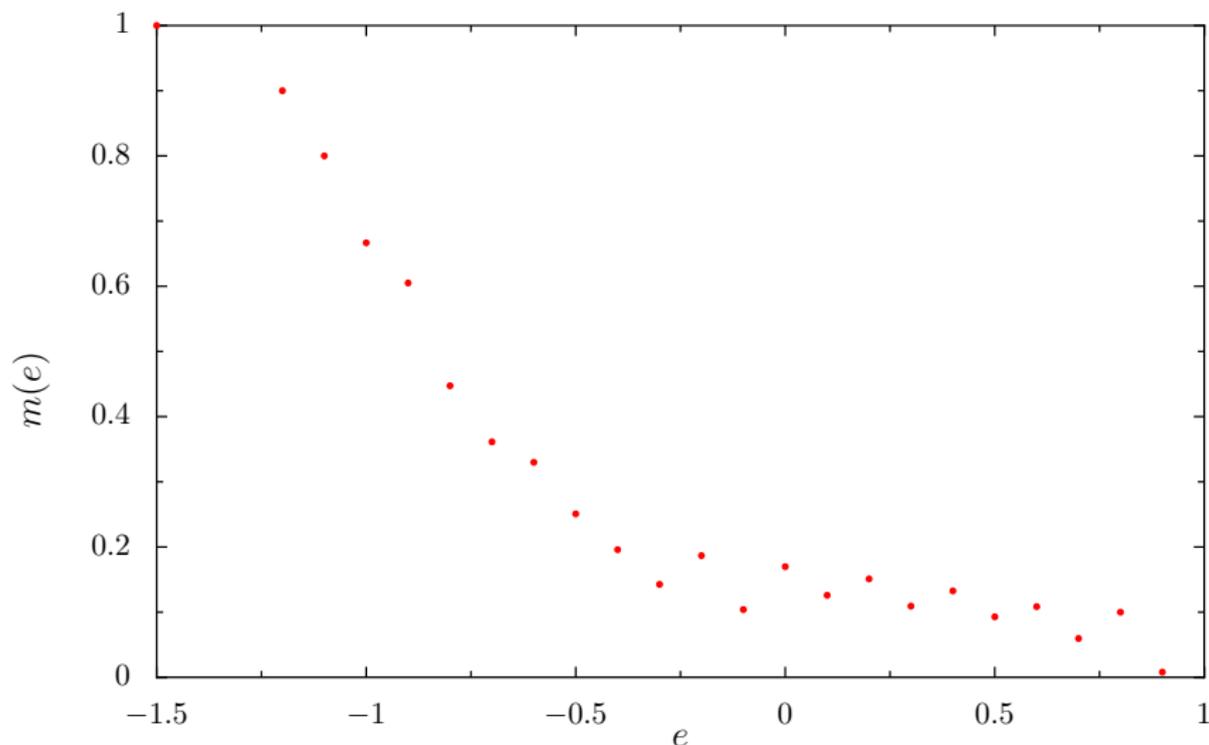


Figure: Specific magnetization  $m(e) = M(E)/|V(\Gamma)|$  vs. energy per vertex  $e$

# Phase Transitions In Mesoscopic Systems

## “Convex Intruders”

In standard thermodynamics

$\left. \frac{\partial^2 S}{\partial E^2} \right|_V = -\frac{1}{T^2} \frac{1}{C_V} \implies$  entropy vs. energy diagramm always concave  
 $C_V$  is specific heat

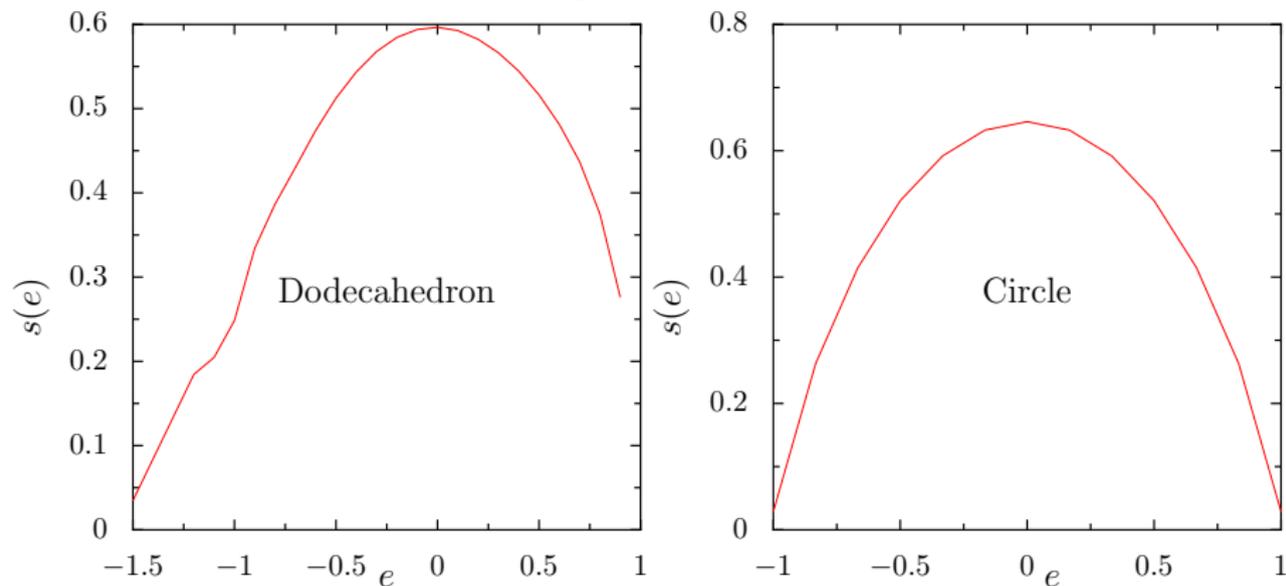
In microcanonical thermodynamics

(mesoscopic and nonextensive systems) there are energy intervals called “convex intruders” where  $\left. \frac{\partial^2 S}{\partial E^2} \right|_V > 0$   
Convex intruders are indicators of first-order phase transitions

Convex intruders in discrete case can be found

via easily computed inequality  $\Omega_{E_i}^{p+q} < \Omega_{E_{i-1}}^p \Omega_{E_{i+1}}^q$   
where  $p/q = (E_{i+1} - E_i) / (E_i - E_{i-1})$

# Convex Intruders In Ising Model On Dodecahedron



**Figure:** Microcanonical entropy  $s(e) = \ln(\Omega_E) / |V(\Gamma)|$  vs. energy  $e$ . Left diagram contains distinct convex intruder in interval  $-1.2 \leq e \leq -0.9$  and subtle one in interval  $-0.8 \leq e \leq -0.6$ . Right diagram is fully concave: 1D Ising model has no phase transitions.

# Convex Intruders. 3-, 4- and 6-valent Lattices

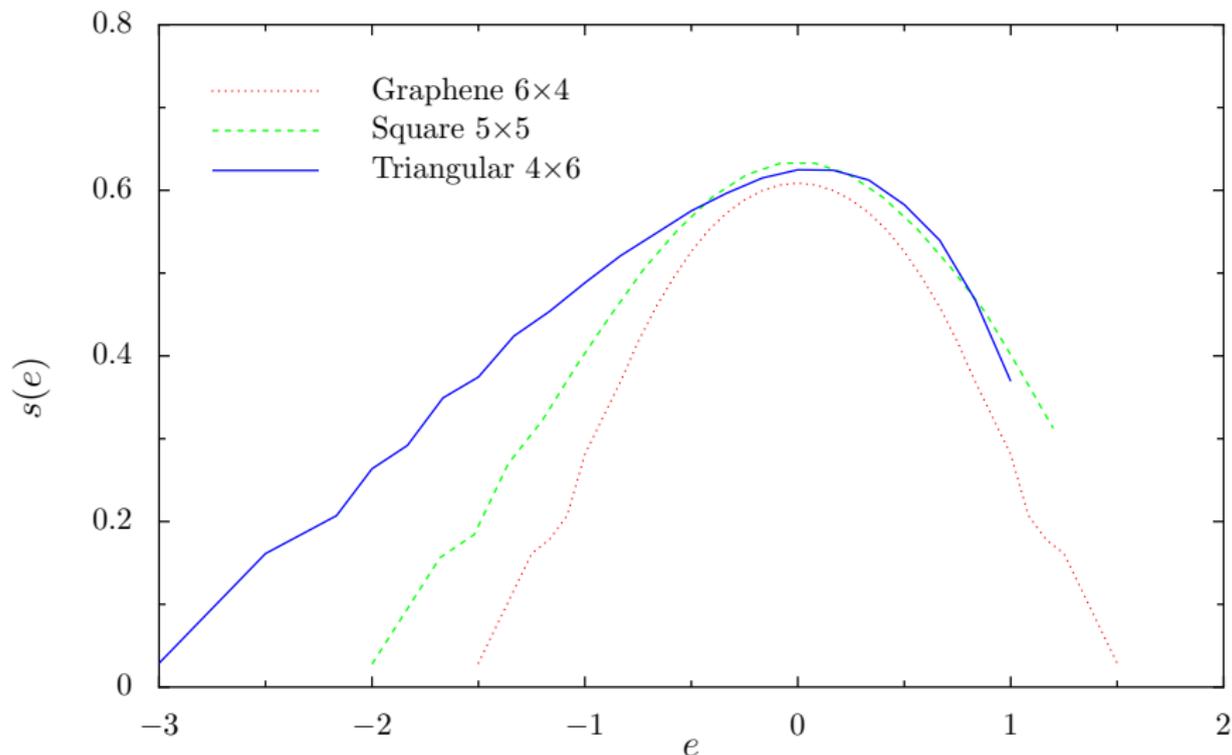


Figure: Entropy on 3-valent (dot), 4-valent (dash) and 6-valent (solid) tori

# Main Results

- **C program** for symmetry analysis of finite discrete dynamical systems has been created
- **Trajectories** of dynamical systems with non-trivial symmetry go always in the direction of **non-increasing** sizes of group **orbits**. **Cyclic trajectories** lie within orbits of the **same size**
- **Evolution operators** can be replaced by **group shifts** after some lapse of time. Initial data tend to form **soliton-like structures**
- **Reversibility** is **rare** property. Reversible systems are **trivial**
- **Lattice symmetries** facilitate study (in particular, search of **phase transitions**) of physical **lattice models**